Errata

Title & Document Type: 89441V VSB/QAM Signal Analyzer Operator's Guide

Manual Part Number: 89441-90061

Revision Date: September 1997

HP References in this Manual

This manual may contain references to HP or Hewlett-Packard. Please note that Hewlett-Packard's former test and measurement, semiconductor products and chemical analysis businesses are now part of Agilent Technologies. We have made no changes to this manual copy. The HP XXXX referred to in this document is now the Agilent XXXX. For example, model number HP8648A is now model number Agilent 8648A.

About this Manual

We've added this manual to the Agilent website in an effort to help you support your product. This manual provides the best information we could find. It may be incomplete or contain dated information, and the scan quality may not be ideal. If we find a better copy in the future, we will add it to the Agilent website.

Support for Your Product

Agilent no longer sells or supports this product. You will find any other available product information on the Agilent Test & Measurement website:

www.tm.agilent.com

Search for the model number of this product, and the resulting product page will guide you to any available information. Our service centers may be able to perform calibration if no repair parts are needed, but no other support from Agilent is available.



HP 89441V Operator's Guide

READ ME FIRST

The documentation for the HP 89441V VSB/QAM Signal Analyzer consists of the HP 89441V Operator's Guide, the analyzer's online help, and the following HP 89441A books:

- HP 89440A/HP 89441A Getting Started Guide
- HP 89441A Installation and Verification Guide
- HP 89400-Series HP-IB Command Reference
- HP-IB Programmer's Guide
- HP 89400-Series HP-IB Quick Reference

The analyzer's online help and the HP 89441A books contain a superset of information for the HP 89441V. Besides documenting the HP 89441V, the online help and HP 89441A books also document features and options not included in the HP 89441V. In particular, the HP 89441V does not have the source types used in chapters 3, 4, and 5 of the Getting Started Guide. However, the Getting Started Guide does contain tasks that show you how to use the analyzer's online help, make simple noise measurements, and perform general tasks. The HP 89441V Operator's Guide contains tasks that will help you get started making video demodulation measurements. Keep the following in mind when using the online help and HP 89441A books:



The HP 89441V does not include the following HP 89441A standard features:

- Analog Demodulation instrument mode
- Periodic chirp and arbitrary source types

The HP 89441V includes the following HP 89441A options:

- AYH—Digital Video Modulation Analysis (excluding selectable filtering)
- AYJ—Adaptive Equalization
- UFG—4 megabyte Extended RAM and Additional I/O

The HP 89441V can not be upgraded with the following HP 89441A options:

- AYA—Vector Modulation Analysis
- AYB-Waterfall and Spectrogram

HP Part No. 89441-90063

Printed in USA

Print Date: October 1997

Warranty

The information contained in this document is subject to change without notice.

Hewlett-Packard makes no warranty of any kind with regard to this material, including, but not limited to, the implied warranties or merchantability and fitness for a particular purpose.

Hewlett-Packard shall not be liable for errors contained herein or for incidental or consequential damages in connection with the furnishing, performance, or use of this material.

Safety Summary

The following general safety precautions must be observed during all phases of operation, service, and repair of this instrument. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Hewlett-Packard Company assumes no liability for the customer's failure to comply with these requirements. This is a Safety Class 1 instrument.

Ground the Instrument

To minimize shock hazard, the instrument chassis and cabinet must be connected to an electrical ground. The instrument is equipped with a three-conductor ac power cable. The power cable must either be plugged into an approved three-contact electrical outlet or used with a three-contact to two-contact adapter with the grounding wire (green) firmly connected to an electrical ground (safety ground) at the power outlet. The power jack and mating plug of the power cable meet International **Electrotechnical Commission** (IEC) safety standards.

Do Not Operate in an Explosive Atmosphere

Do not operate the instrument in the presence of flammable gases or fumes. Operation of any electrical instrument in such an environment constitutes a definite safety hazard.

Keep Away from Live Circuits

Operating personnel must not remove instrument covers. Component replacement and internal adjustments must be made by qualified maintenance personnel. Do not replace components with power cable connected. Under certain conditions, dangerous voltages may exist even with the power cable removed. To avoid injuries, always disconnect power and discharge circuits before touching them.

Do Not Service or Adjust Alone

Do not attempt internal service or adjustment unless another person, capable of rendering first aid and resuscitation, is present.

Do Not Substitute Parts or Modify Instrument

Because of the danger of introducing additional hazards, do not install substitute parts or perform any unauthorized modification to the instrument. Return the instrument to a Hewlett-Packard Sales and Service Office for service and repair to ensure the safety features are maintained.

Dangerous Procedure Warnings

Warnings accompany potentially dangerous procedures throughout this manual. Instructions contained in the warnings must be followed.

Cleaning

To prevent electricial shock, disconnect this product from mains before cleaning. Only use a dry cloth or one slightly dampened with water to clean external parts. DO NOT attempt to clean internally!

Safety Symbols

The following safety symbols are used throughout this manual and in the instrument. Familiarize yourself with each symbol and its meaning before operating this instrument.

General Definitions of Safety Symbols Used on Equipment or in Manuals



Instruction manual symbol. The product is marked with this symbol when it is necessary for the user to refer to the instruction manual to protect against damage to the instrument.



Indicates dangerous voltage (terminals fed from the interior by voltage exceeding 1000 volts must be so marked).



Protective ground (earth) terminal. Used to identify any terminal which is intended for connection to an external protective conductor for protection against electrical shock in case of a fault, or to the terminal of a protective ground (earth) electrode.



Low-noise or noiseless, clean ground (earth) terminal. Used for a signal common, as well as providing protection against electrical shock in case of a fault. A terminal marked with this symbol must be connected to ground in the manner described in the installation (operating) manual, and before operating the equipment.



OR



Frame or chassis terminal, A connection to the frame (chassis) of the equipment which normally includes all exposed metal structures.



Alternating current (power line).



Direct current (power line).



Alternating or direct current (power line).

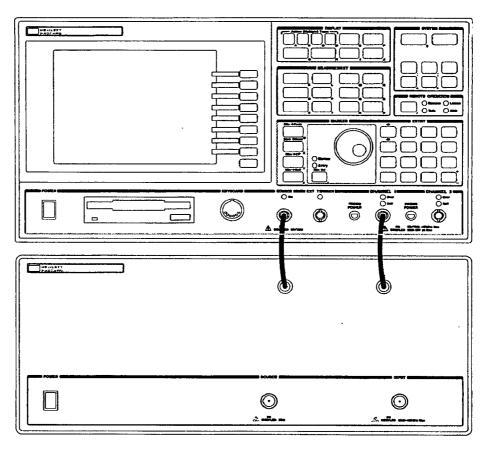
Warning

The warning sign denotes a hazard. It calls attention to a procedure, practice, condition or the like, which if not correctly performed or adhered to, could result in injury or death to personnel.

Caution

The caution sign denotes a hazard. It calls attention to an operating procedure, practice, condition or the like, which, if not correctly performed or adhered to, could result in damage to or destruction of part or all of the product or the user's data.

HP 89441V Operator's Guide



HEWLETT®

HP Part Number 89441-90061 For instruments with firmware version A.05.10 Printed in U.S.A.

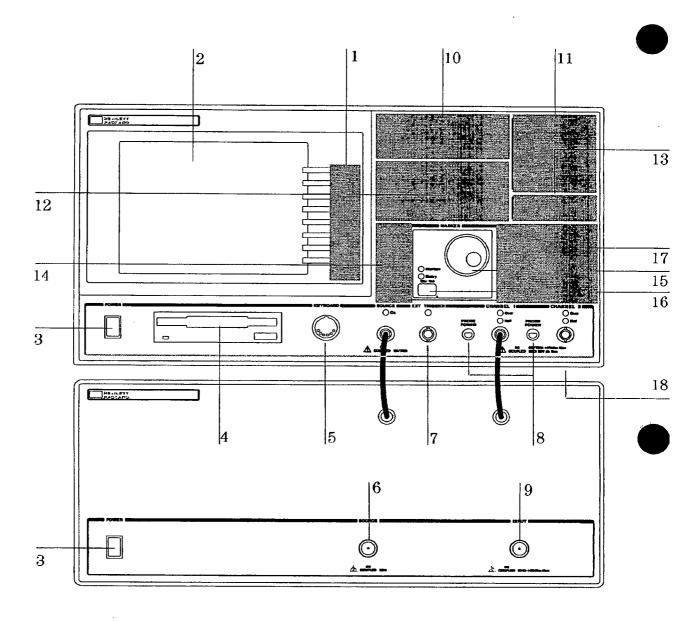
Print Date: October 1997

© Hewlett-Packard Company, 1993-1997. All rights reserved. 8600 Soper Hill Road Everett, Washington 98205-1298 U.S.A.

This software and documentation is based in part on the Fourth Berkeley Software Distribution under license from The Regents of the University of California. We acknowledge the following individuals and institutions for their role in the development: The Regents of the University of California.

Portions of the TCP/IP software are copyright Phil Karn, KA9Q.

The Analyzer at a Glance



Front Panel

1-A softkey's function changes as different menus are displayed. Its current function is determined by the video label to its left, on the analyzer's screen.

1 .

- 2-The analyzer's screen is divided into two main areas. The menu area, a narrow column at the screen's right edge, displays softkey labels. The data area, the remaining portion of the screen, displays traces and other data.
- **3**-The POWER switch turns the analyzer on and off.
- **4**-Use a 3.5 inch flexible disk (DS,HD) in this disk drive to save your work.
- **5**-The KEYBOARD connector allows you to attach an optional keyboard to the analyzer. The keyboard is most useful for writing and editing HP Instrument BASIC programs.
- **6** The SOURCE connector routes the analyzer's source output to your DUT. If option AY8 (internal RF source) is installed, the conector is a type-N. If option AY8 is not installed, the connector is a BNC. Output impedance is selectable: 50 ohms or 75 ohms with option 1D7 (minimum loss pads).
- **7**-The EXT TRIGGER connector lets you provide an external trigger for the analyzer.
- **8**-The PROBE POWER connectors provides power for various HP active probes.
- **9**-The INPUT connector routes your test signal or DUT output to the analyzer's receiver. Input impedance is selectable: 50 ohms or 75 ohms with option 1D7 (minimum loss pads).
- 10-Use the DISPLAY hardkeys and their menus to select and manipulate trace data and to select display options for that data.

- 11-Use the SYSTEM hardkeys and their menus to control various system functions (online help, plotting, presetting, and so on).
- 12-Use the MEASUREMENT hardkeys and their menus to control the analyzer's receiver and source, and to specify other measurement parameters.
- 13-The REMOTE OPERATION hardkey and LED indicators allow you to set up and monitor the activity of remote devices.
- 14-Use the MARKER hardkeys and their menus to control marker positioning and marker functions.
- 15-The knob's primary purpose is to move a marker along the trace. But you can also use it to change values during numeric entry, move a cursor during text entry, or select a hypertext link in help topics
- 16-Use the Marker/Entry key to determine the knob's function. With the Marker indicator illuminated the knob moves a marker along the trace. With the Entry indicator illuminated the knob changes numeric entry values.
- 17-Use the ENTRY hardkeys to change the value of numeric parameters or to enter numeric characters in text strings.
- 18-The optional CHANNEL 2 input connector routes your test signal or DUT output to the analyzer's receiver. Input impedance is selectable: 50 ohms, 75 ohms, or 1 megohm. For ease of upgrading, the CHANNEL 2 BNC connector is installed even if option AY7 (second input channel) is not installed.

For more details on the front panel, display the online help topic "Front Panel". See the chapter "Using Online Help" if you are not familiar with using the online help index.

This page left intentionally blank

Options and Accessories

To determine if an option is installed, press [System Utility] [option setup]. Installed options are also listed on the analyzer's rear panel.

To order an option to upgrade your HP $89441\,\mathrm{V}$, order HP $89441\,\mathrm{U}$ followed by the option number.

Option Description		HP 89441U Option	
Add Internal RF Source		AY8	
Add High Precision Frequency Referenc	e	AYC	
Add Digital Video Modulation Analysis and Adaptive Equalization		AYH (Standard for HP 89441V)	
Add Adaptive Equalization		AYJ (Standard for HP 89441V)	
Add Second 10 MHz Input Channel.		AY7	
Extend Time Capture to 1 megasample		AY9	
Add 4 megabyte Extended RAM and Additional I/O		UFG (Standard for HP 89441V)	
Add Advanced LAN Support (requires option UFG)		UG7	
Add HP Instrument BASIC		102	
Add 50 - 75 Ohm Minimum Loss Pads		107	
Add PC-Style Keyboard and Cable	U.S. version	1F0	
Add PC-Style Keyboard and Cable	German version	1F1	
Add PC-Style Keyboard and Cable	Spanish version	1F2	
Add PC-Style Keyboard and Cable	French version	1F3	
Add PC-Style Keyboard and Cable	U.K. version	1F4	
Add PC-Style Keyboard and Cable	Italian version	1F5	
Add PC-Style Keyboard and Cable	Swedish version	1F6	
Add Front Handle Kit		AX3	
Add Rack Flange Kit		AX4	
Add Flange and Handle Kit		AX5	
Add Extra Manual Set		OB1	
Add Extra Instrument BASIC Manuals		ОВИ	
Add Service Manual		0B3	

The accessories listed in the following table are supplied with the HP 89441V.

Supplied Accessories	Part Number	
Line Power Cable	See HP 89441A Installation and Verification Guide	
Rear Panel Lock Foot Kit	HP 5062-3999	
BNC Cable - 12 inch	HP 8120-1838	
2 BNC Cables - 8.5 inch	HP 8120-2682	
Coax BNC(m)-to-coax BNC(m) Connector (deleted with option AY4)	HP 1250-1499	
Type N-to-BNC Adapter (2 with option AY8)	HP 1250-0780	
Serial Interface Interconnect Cable	HP 8120-6230	
Interconnect Cable EMI Suppressor	HP 9170-1521	
Standard Data Format Utilities	HP 5061-8054	
HP 89441V Operator's Guide	(see title page in manual)	
HP 89440A/HP 89441A Getting Started Guide	(see title page in manual)	
HP 89441A Installation and Verification Guide	(see title page in manual)	
HP 89400-Series HP-IB Command Reference	(see title page in manual)	
HP-IB Programmer's Guide	(see title page in manual)	
HP 89400-Series HP-IB Quick Reference	(see title page in manual)	

The accessories listed in the following table are available for the HP 89441V.

Available Accessories	Part Number		
HP 89411A 21.4 MHz Down Converter	HP 89411A		
HP 89400-Series Using HP Instrument BASIC	HP 89441-90013		
HP Instrument BASIC User's Handbook	HP E2083-90005		
Spectrum and Network Measurements	HP 5960-5718		
Box of ten 3.5-inch double-sided, double-density disks	HP 92192U		
Active Probe	HP 41800A		
Active Probe	HP 54701A		
Resistor Divider Probe	HP 10020A		
Differential Probe (requires HP 1142A)	HP 1141A		
Probe Control and Power Module	HP 1142A		
50 Ohm RF Bridge	HP 86205A		
Switch/Control Unit	HP 3488A		
High-Performance Switch/Control Unit	HP 3235A		
HP-IB Cable - 1 meter	HP 10833A		
HP-IB Cable - 2 meter	HP 10833B		
HP-IB Cable - 4 meter	HP 10833C		
HP-IB Cable - 0.5 meter	HP 10833D		

This page left intentionally blank.

Notation Conventions

Before you use this book, it is important to understand the types of keys on the front panel of the analyzer and how they are denoted in this book.

Hardkeys Hardkeys are front-panel buttons whose functions are always the same. Hardkeys have a label printed directly on the key. In this book, they are printed like this: [Hardkey].

Softkeys Softkeys are keys whose functions change with the analyzer's current menu selection. A softkey's function is indicated by a video label to the left of the key (at the edge of the analyzer's screen). In this book, softkeys are printed like this: [softkey].

Toggle Softkeys Some softkeys toggle through multiple settings for a parameter. Toggle softkeys have a word highlighted (of a different color) in their label. Repeated presses of a toggle softkey changes which word is highlighted with each press of the softkey. In this book, toggle softkey presses are shown with the requested toggle state in bold type as follows:

"Press [key name on]" means "press the softkey [key name] until the selection on is active."

Shift Functions In addition to their normal labels, keys with blue lettering also have a shift function. This is similar to shift keys on an pocket calculator or the shift function on a typewriter or computer keyboard. Using a shift function is a two-step process. First, press the blue [**Shift**] key (at this point, the message "shift" appears on the display). Then press the key with the shift function you want to enable. Shift function are printed as two key presses, like this:

[**Shift**] [**Shift Function**]

Numeric Entries Numeric values may be entered by using the numeric keys in the lower right hand ENTRY area of the analyzer front panel. In this book values which are to be entered from these keys are indicted only as numerals in the text, like this: Press 50, [enter]

Ghosted Softkeys A softkey label may be shown in the menu when it is inactive. This occurs when a softkey function is not appropriate for a particular measurement or not available with the current analyzer configuration. To show that a softkey function is not available, the analyzer "ghosts" the inactive softkey label. A ghosted softkey appears less bright than a normal softkey. Settings/values may be changed while they are inactive. If this occurs, the new settings are effective when the configuration changes such that the softkey function becomes active.

This page left intentionally blank.

In This Book

This book, HP 89441V Operator's Guide, is designed to advance your knowledge of the HP 89441V VSB/QAM Signal Analyzer. You should already feel somewhat comfortable with this analyzer, either through previous use or through performing the tasks in chapters 1, 2, and 6 in the HP 89440A/HP 89441A Getting Started Guide. The HP 89441V does not have the source types used in chapters 3, 4, and 5 of the Getting Started Guide. This book consists of both measurement tasks and concepts.

Measurement tasks

Measurement tasks provide step-by-step examples of how to perform specific tasks with your HP 89441V VSB/QAM Signal Analyzer. These tasks may be similar to measurements you wish to make and you can modify them to meet your own needs. Even if these tasks are not specifically related to your measurement needs, you may find it helpful to perform the tasks anyway—they only take a few minutes each—since they will help you become familiar with many of your analyzer's features.

Concepts

The concepts section provides you with a conceptual overview of the HP 89441V and its essential features. This section assumes that you are already familiar with basic measurement concepts and is helpful in understanding the similarities and differences between the HP 89400 series analyzers and other analyzers you may have used. The concepts are also essential if you want to make the best use of the analyzer's features.

To Learn More About the HP 89441V

You may need to use other books in the HP 89400 series manual set. See the "Documentation Roadmap" at the end of this book to learn what each book contains.

This page left intentionally blank.

Table of Contents

1 Using Video Demodulation

To prepare a VSB measurement 1-2

To determine the center frequency for a VSB signal 1-4

To demodulate a VSB signal 1-6

To measure the peak-to-average power ratio 1-8

To prepare a QAM or DVB QAM measurement 1-10

To demodulate a QAM or DVB QAM signal 1-12

To select measurement and display features 1-14

To set up sync search (QAM only) 1-16

To select and create stored sync patterns (QAM only) 1-18

To demodulate a two-channel I/Q signal 1-19

2 Using Adaptive Equalization

To load the multi-path signal from the Signals Disk 2-2

To demodulate the multi-path signal 2-3

To apply adaptive equalization 2-5

To measure signal paths 2-8

To learn more about equalization 2-10

3 Using Band-Power Markers

To measure band power with improved dynamic range 3-2

4 Using the LAN

To determine if you have option UG7 4-2

To connect the analyzer to a network 4-3

To set the analyzer's network address 4-4

To activate the analyzer's network interface 4-5

To send HP-IB commands to the analyzer 4-6

To select the remote X-Windows server 4-7

To initiate remote X-Windows operation 4-8

To use the remote X-Windows display 4-9

To transfer files via the network 4-10

5 Using the HP 89411A Downconverter

Connection and setup details for the HP 89411A 5-4

6 Choosing an Instrument Mode

Why Use Scalar Mode? 6-2

Why Use Vector Mode? 6-4

Why Use Video Demodulation Mode? 6-6

The Advantage of Using Multiple Modes 6-7

Instrument Mode? Measurement Data? Data Format? 6-8

Unique Capabilities of the Instrument Modes 6-9

7 What Makes this Analyzer Different?

Time Domain and Frequency Domain Measurements 7-2

What are the Different Types of Spectrum Analyzers? 7-4

The Difference 7-8

8 Fundamental Measurement Interactions

Measurement Resolution and Measurement Speed 8-2

Windowing 8-6

Enhancing the Measurement Speed 8-8

Special Considerations in Scalar Mode 8-10

Special Considerations in Vector Mode 8-14

9 Gating Concepts

What is Time Gating? 9-2 How Does it Work? 9-4 Important Concepts 9-5 Parameter Interactions 9-6

10 Video Demodulation Concepts

Overview 10-2
Measurement Flow 10-3
Measurement management 10-7
Parameter interactions 10-11
Special considerations for sync search 10-15
Special considerations for pulsed signals 10-16
Filtering 10-17

Index
Declaration of Conformity
Need Assistance?
Documentation Roadmap
HP 89441V Technical Specifications

1

Using Video Demodulation

This chapter shows you how to use digital video demodulation to demodulate and view digitally-modulated video signals. You may perform the tasks in this chapter using signals from the Signals Disk, or you may use these tasks as a model for demodulating your own signals.

To prepare a VSB measurement

This task shows you how to load and view the 8 VSB signal located on the Signals Disk. If you have your own 8 VSB signal, use the steps below and enter the demodulation parameters for your signal.

1 Initialize the analyzer:

```
Press | Presst |.
Press | Instrument Mode |, [receiver], [RF section (0-10 MHz)].
Press | Instrument Mode |, [Vector].
Press | System Utility |, [memory usage], [configure meas memory].
Press | [max freq pts], 1601 [enter].
Press | [max time pts], 4096 [enter].
```

- 2 If your analyzer has the optional second input channel installed, turn it off: Press [Input], [channel 2], [ch2 state off].
- 3 Supply an 8 VSB signal to the INPUT or perform the following steps to load an 8 VSB signal from the Signals Disk into the analyzer's time-capture RAM:

Insert the Signals Disk into the internal disk drive.

Press [Save/Recall], [default disk], [internal disk].

Press [Return], [catalog on].

Rotate the knob to highlight 8VSB.CAP Press [recall more], [recall capture buffer], [enter].

4 Turn on averaging:

Press [Average], [average on].

5 Measure and scale the displayed trace:

Press [Meas Restart], [Auto Scale].

When you measure time-capture data, the analyzer automatically sets its frequency span and center frequency to that used to capture the data. Therefore, you did not need to set these parameters in the above steps.

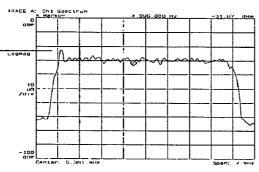
If you are not measuring time-capture data, you must set the center frequency, frequency span, and range. If these parameters are incorrect, the analyzer may not lock to your carrier, measurement speed may be reduced, or you may see excessive errors in the demodulated results. For details about setting these parameters, see "Carrier locking", "Input Range", and "Span considerations" in the *Video Demodulation Concepts* chapter. The next task, "To determine the center frequency for a VSB signal", shows you how to determine the correct center frequency.

VSB measurements typically require a large portion of measurement memory. Therefore, it is a good idea to choose the maximum value (4096) for [max time points] (see step 1). For details about [max time points], see online help (press [Help], then press [max time points]).

Note		

Before demodulating a VSB signal, view the signal in Vector mode to verify that the pilot is on the left (low) side of the spectrum. If it isn't, you must configure the analyzer to demodulate a high-side pilot. For further details, see "To demodulate a VSB signal."

To demodulate VSB signals, the pilot must be on the left (low) side of the spectrum. If it isn't, you must configure the analyzer to demodulate a high-side pilot, as shown in "To demodulate a VSB signal."



Spectrum of an 8 VSB signal

To determine the center frequency for a VSB signal

Choosing the correct center frequency is important for all digital video demodulation measurements. This task shows you how to determine the correct center frequency for VSB measurements. To learn how to determine the correct center frequency for QAM measurements, see the "Video Demodulation Concepts" chapter. Note that you must supply an 8 VSB signal to perform this task. You cannot use the time-capture signal from the signals disk because this task uses the analyzer's frequency counter, which cannot be used on time capture data.

1 Initialize the analyzer:

Press [Preset].

Press [Instrument Mode], [receiver], [RF section (0-10 MHzl].

Press [Instrument Mode], [Vector].

2 Increase the display resolution:

Press [ResBw/Window].

Press [num freq pts], 1601 [enter].

Press [rbw mode arb].

Press [rbw] and press the down-arrow key to select the smallest resolution bandwidth.

3 Position the marker on the pilot:

Press [Shift], [Marker].

4 Turn on the frequency counter:

Press [Marker Function], [freq counter on].

5 Compute the ideal center frequency:

Center Frequency (LOW SIDE PILOT) =
$$\frac{Symbol\ Rate}{4}$$
 + (Pilot Frequency)

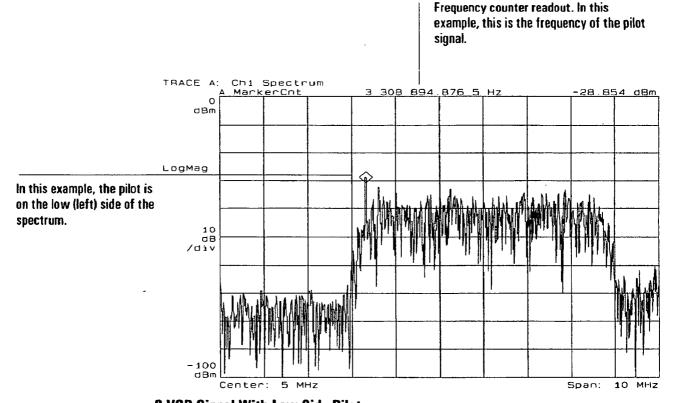
Center Frequency (HIGH SIDE PILOT) = (Pilot Frequency)
$$-\frac{Symbol\ Rate}{4}$$

In this example, the symbol rate is 10.762 MHz, the frequency counter shows the pilot frequency at 3.308894876 MHz, and the pilot is on the low side of the spectrum. Using the formula for low-side pilot, the ideal center frequency is 5.999394876 MHz. A center frequency of 6 MHz is close enough to ensure carrier lock.

6 Set the center frequency to the computed value: Press [Frequency], [center], 6 [MHz].

Note	

If your pilot is on the high (right) side of the spectrum, you must configure the analyzer to demodulate a high-side pilot. For further details, see the next task: "To demodulate a VSB signal."



To demodulate a VSB signal

This task shows you how to demodulate a VSB signal. The task uses the 8 VSB time-capture signal that you loaded into the analyzer in "To prepare a VSB measurement".

- 1 Prepare the analyzer for a VSB measurement as shown in "To prepare a VSB measurement".
- 2 Turn averaging off and restart the measurement:

Press [Average], [average off].

Press [Meas Restart].

3 Demodulate the signal:

Press [Instrument Mode], [Video Demodulation].

4 Select the correct demodulation parameters for the 8 VSB signal (if you are not using the signal provided on the Signals Disk, enter the parameters for your signal):

Press (demodulation setup).

Press [demod format], [VSB 8], [Return].

Press [symbol rate], 10.762 [MHz].

Press [result length], 800 [sym].

Press [filter alpha], .1152 [enter]

Press [Time], [points/symbol], 5 [enter].

Press [pulse search off], [sync search off].

5 If the pilot is on the left (low) side of the spectrum, configure the analyzer to demodulate a low-side pilot (if you are using the signal provided on the Signals Disk, the pilot is on the left side of the spectrum):

Press [Instrument Mode], [demodulation setup], [demod format], [freq spectrum normal].

6 If the pilot is on the right (high) side of the spectrum, configure the analyzer to demodulate a high-side pilot:

Press [Instrument Mode], [demodulation setup], [demod format], [freq spectrum mirror].

To learn what [freq spectrum mirror] does, see online help (press [Help], then press [freq spectrum]).

7 View the constellation and eye diagram:

Press [Display], [2 grids].

Press [A], [Measurement Data], [10 measured time].

Press [Data Format], [polar (10) constellation].

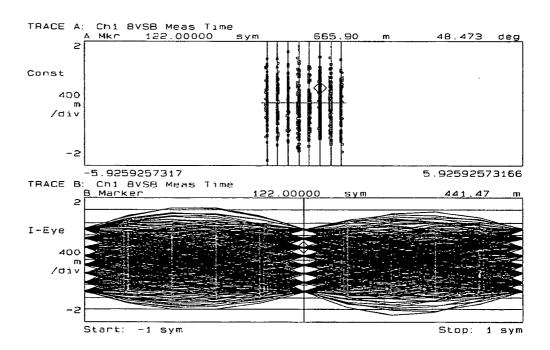
Press [B], [Measurement Data], [10 measured time].

Press [Data Format], [eye diagram I].

With VSB signals, symbol locations (detection decision points) are derived from the real portion (I) of the demodulated data. This is evident in the constellation diagram where you see symbols aligned vertically in 8 locations (16 locations for 16 VSB) along the I-axis. The vertical lines in the constellation diagram indicate ideal symbol locations.

Hint

Displayed data must contain real data to see symbol locations for VSB signals. For example, if you press | Data Format| and select the imaginary part of the data or the Q eye-diagram, you won't see symbol information.



Constellation and eye diagram for 8 VSB signal

To measure the peak-to-average power ratio

This task shows you how to measure the peak-to-average power ratio of a digitally modulated signal. The task uses the 8 VSB time-capture signal that you loaded into the analyzer in "To prepare a VSB measurement".

- 1 Prepare the analyzer for a VSB measurement as shown in "To prepare a VSB Measurement".
- **2** View the time waveform:

Press [A], [Measurement Data], [main time] or [main time ch1]. Press [Data Format], [magnitude log(dB)].

3 Enable time domain calibrations:

Press [System Utility], [time domain cal on].

In vector mode, calibrations are normally applied only to the spectrum data. The peak-to-average power measurements are performed on the time data, so the data must be calibrated for greatest accuracy.

4 If you are measuring the 8 VSB time-capture signal, disable averaging and overlap processing of the time capture buffer:

Press [Average], [average off].
Press [Time], [overlap], [ovlp: avq off], 0 [%].

- 5 Enable peak-to-average measurements on Trace A Press [Marker Function], [peak/average statistics], [statistics on].
- 6 Measure the peak-to-average power ratio:

Press [Meas Restart], [Auto Scale].

The ratio of the peak-to-average power is displayed near the bottom of the trace. The value is related to the peak percent specified in the peak/average statistics menu. The peak percent value may be adjusted after the measurement has been completed.

7 Adjust [peak percent] to set the probability that the instantaneous power will be below a level that is 6 dB above the signal's average power:

Press [Marker Function], [peak/average statistics].

Press [peak percent], [Return].

Press [Marker/Entry] to illuminate the Entry LED.

While observing the Peak/Avg ratio on the trace, adjust the Marker knob until the ratio is near 6 dB.

The peak percent key should read near 99.78%. This implies that 99.78% of the time, the signal power is below 6 dB above average, or 0.22% of the time, the signal power exceeds a level that is 6 dB above the average power.

8 Determine the average signal power in dB:

Press [average power].

Press [Ref Lvl/Scale], [X&Y units setup], [Y units], [dBm].

The result should be near -11.7 dBm.

9 Determine the average signal power in Watts:

Press [Data format], [magnitude linear].

Press [Ref Lvi/Scale], [X&Y units setup], [Y units], [W].

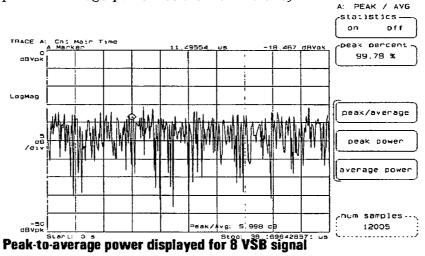
Press [Auto Scale].

The result should be near 66.8 uW.

10 View the peak-to-average ratio in linear units:

Press [Marker Function], [peak/average statistics], [peak/average].

The power ratio was expressed in dB. When the display data format was changed to linear magnitude, the ratio also changed from a log to linear format. So, instead of 6 dB, the ratio is now reported as 4 (i.e., a peak-to-average power ratio of four-to-one).



To prepare a QAM or DVB QAM measurement

This task shows you one way to set up a QAM or DVB QAM measurement. The task uses the RF section (0-10 MHz) receiver and a 32 QAM signal from the signals disk. Several other tasks in this chapter use this setup to teach you how to use video demodulation.

1 Initialize the analyzer:

Press [Preset].

Press [Instrument Mode], [receiver], [RF section (0-10 MHz)].

Press [Instrument Mode], [Vector].

Press [System Utility], [memory usage], [configure meas memory].

Press [max time pts], 4096 [enter].

- 2 If your analyzer has the optional second input channel installed, turn it off: Press [Input], [channel 2], [ch2 state off].
- 3 Supply a 32 QAM signal to the INPUT or perform the following steps to load a 32 QAM signal from the Signals Disk into the analyzer's time-capture RAM:

Insert the Signals Disk into the internal disk drive.

Press [Save/Recall], [default disk], [internal disk].

Press [Return], [catalog on].

Rotate the knob to highlight 32QAM.CAP

Press [recall more], [recall capture buffer], [enter].

Press [catalog off].

When you measure time-capture data, the analyzer automatically sets its frequency span and center frequency to that used to capture the data. Therefore, you did not need to set these parameters in the above steps.

If you are not measuring time-capture data, you must set the center frequency and frequency span. The center frequency tunes the analyzer to the carrier frequency. To obtain reliable carrier lock, the center frequency must be close to the carrier frequency. For details, see "Carrier Locking" in the *Video Demodulation Concepts* chapter.

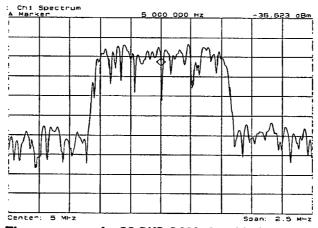
Selecting the correct frequency span is also important when using video demodulation. The span must be wide enough to include all signal components, and yet not too wide, or the measurement may be affected by excessive noise and slower speed. For details, see "Parameter Interactions" in the *Video Demodulation Concepts* chapter.

4 Measure and scale the displayed trace:

Press [Meas Restart], [Auto Scale].

This task sets [max time pts] to its maximum value (4096), which allocates the maximum amount of measurement memory for digital video demodulation. This lets you choose larger result lengths, search lengths, and points-per-symbol. For additional details about allocating memory for digital video demodulation, see "Parameter Interactions" in the *Video Demodulation Concepts* chapter and see online help for [max time points], (press [Help], then press [max time points]).

QAM and DVB QAM measurements treat I/Q origin offset differently. QAM measurements remove I/Q origin offset, DVB QAM measurements *do not* remove I/Q origin offset. Both demodulation formats report I/Q origin offset (in the symbol table).



The spectrum of a 32 DVB QAM signal before demodulation.

To demodulate a QAM or DVB QAM signal

This task shows you how to demodulate the 32 DVB QAM signal generated in "To prepare a QAM or DVB QAM measurement". Prior to demodulating your own video signal, you must select the correct center frequency, frequency span, and range as shown in that task. You use the same procedure to demodulate both QAM and DVB QAM signals.

- 1 Prepare the analyzer for a DVB QAM measurement as shown in the previous task.
- 2 Demodulate the signal:

Press [Instrument Mode], [Video Demodulation].

3 Select the correct demodulation parameters for the 32 DVB QAM signal (if you are not using the signal provided on the Signals Disk, enter the parameters for your signal):

```
Press [demodulation setup].
```

Press [demod format], [DVB QAM 32], [Return].

Press [symbol rate], 1 [MHz].

Press [result length], 400 [sym].

Press [filter alpha], .15 [enter].

Press [Time], [points/symbol], 5 [enter].

Press [pulse search off], [sync search off].

4 View the created signal versus the reference:

Press [Display], [2 grids].

Press [A], [Measurement Data], [10 measured time].

Press [B], [Measurement Data], [10 reference time].

Press [Shift], [A] to activate both traces.

Press [Data Format], [polar (IQ) vector].

Press [more format setup], [symbol dots] (if [symbol dots] is already selected, you still must press this key to force both traces to display symbols as dots).

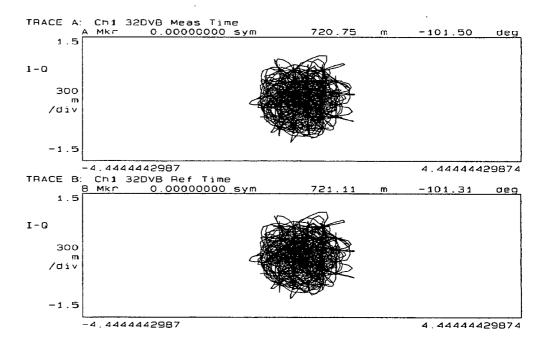
5 Scale both traces:

Press [Auto Scale].

Press [Meas Restart].

Hint

You use [demodulation setup] to set demodulation parameters, you use [Measurement Data] to select the measurement calculation used on demodulated data, and you use [Data Format] to select a display format (trace coordinates). To learn more about these keys and the choices under them, see online help. Online help contains detailed descriptions for all keys (press [Help], then press the desired key). The next task uses [Measurement Data] and [Data Format] to display a constellation diagram and the error-vector trace.



Two time displays of a demodulated signal: IQ measured versus IQ Reference

To select measurement and display features

You can display demodulated data in many different formats. This task uses the demodulated 32 DVB QAM signal from the previous task to show you just a few ways of viewing demodulated data.

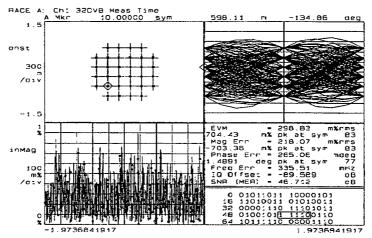
- 1 Select multiple display grids: Press [Display], [4 grids quad].
- 2 Change the data format for trace A:
 Press [A], [Data Format], [polar [0] constellation].
- 3 Change the measurement data for trace B: Press [B], [Measurement Data], [error vector time].
- 4 Scale traces A, B, and C:

 Press [Shift], [A], [Shift], [C] to activate traces A, B, and C.

 Press [Auto Scale].

By default, selecting 4 grids displays the current trace in trace A, the error-vector trace in trace B, the eye diagram in trace C, and the symbol table in trace D. Thus you can view demodulated data in four different ways at the same time.

You can change the [Measurement Data] and [Data Format] for any trace. Simply activate the trace (for example, press [A] to activate trace A), then select the desired measurement data and data format.



Each grid shows a different measurement type with an appropriate data format.

To set up sync search (QAM only)

In this task you learn how to synchronize your measurement by using a specific bit pattern within the chain of bits. This task uses the demodulated 32 DVB QAM signal from the previous task to show you how to define sync words and set an offset. Note that you cannot use sync search with VSB measurements.

1 Select two displays and format them:

Press [A], [Data Format], [magnitude log(dB)].
Press [Display], [2 grids]

Press [D].

2 Select the search length for this particular signal:

Press [Time], [search length], 1000 [sym].

3 Enter a sync bit pattern:

Press [sync setup], [pattern], [clear entry], 0000011111 [enter].

4 Select an offset:

Press [offset], 6 [sym].

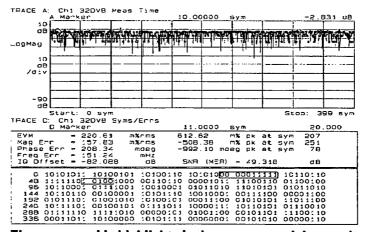
5 Turn on sync search:

Press [Return], [sync search on].

6 Disable averaging and overlap processing of the time capture buffer:

Press (Average), [average off].
Press [Time], [overlap], [ovlp: avg off], 0 [%].

The search length must be longer than the combination of result length, sync pattern, and offset. The sync pattern may include up to 32 symbols. The offset may be positive or negative. See the online help topics for more information on these keys.



The sync word is highlighted when sync search is completed successfully

To select and create stored sync patterns (QAM only)

When using sync search you can enter a sync bit pattern as in the previous task, or you can load up to six of your own sync patterns into softkeys F3 through F8, and then use the softkeys to select a sync bit pattern. This task uses the results of the previous task.

1 Insert the Signals Disk into the analyzer's disk drive.

2 Load an example of user-defined sync patterns:

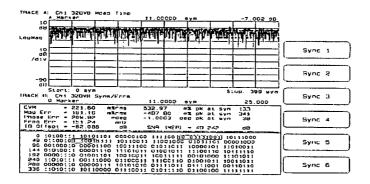
Press [Save/Recall], [catalog on].
Scroll to highlight SYNC_KEY.TXT
Press [recall more], [recall sync/state defs], [enter].

3 Choose one of the user-defined sync patterns:

Press [Time], [sync setup], [offset], 15 [sym], [user sync patterns]. Press one of the six user-defined softkeys to change sync patterns.

If you select Sync 3 or Sync 4, you see what happens if the analyzer cannot find the sync pattern. The analyzer demodulates the signal but displays the message "SYNC NOT FOUND." When this happens, the result is positioned at the start of data collection. In this case, the sync is not found because the combination of offset and sync word place the result length beyond the pulse. The other four sync words show the result length on the leading edge, trailing edge, or center of the pulse.

You may create your own sync bit pattern definitions for the softkeys. See the file "STAT_DEF" on the Signals Disk. The file may be viewed and edited with any ASCII editor and the results may be saved on a disk. If you have IBASIC installed, you may use it as an editor. You may view the files "SYNC_KEY.TXT" and "STATES.TXT" to see a sync pattern and a state definition which were created by using IBASIC to modify portions of the "STAT_DEF" file.



Up to 6 sync patterns may be loaded into softkeys

To demodulate a two-channel I/Q signal

Note

This measurement can only be performed with a 2-channel analyzer—you must have option AY7 (option AY7 adds a second input channel).

If you have separate baseband I and Q signals available for your measurement, you may demodulate them directly if you have a two-channel analyzer. This type of demodulation preserves the original transmitted relationship between the I and Q signals.

- 1 Apply real I and Q signals to Channel 1 and Channel 2 respectively. Be sure to use the inputs on the upper (IF) section of the analyzer.
- 2 Select the special baseband receiver mode: Press [Instrument Mode], [receiver], [IF section (ch1 + j*ch2)].
- 3 Adjust the frequency span to encompass the signal with a span of at least 78 kHz.
- 4 Make sure that time domain calibration is on under the [System Utility] key.
- 5 Select identical parameters for both channels under the [Range] key.
- 6 Select identical parameters for both channels under the [Input] key.
- 7 Select identical parameters for both channels under the [Trigger] key.
- 8 Proceed with digital demodulation as shown previously.

For more information on this type of measurement see online help for the [IF section (ch1 + j*ch2)] key.

2

Using Adaptive Equalization

This chapter shows you how to use Adaptive Equalization. Adaptive equalization removes linear errors from modulated signals by dynamically creating and applying a compensating filter.

To load the multi-path signal from the Signals Disk

This task shows you how to load a 16-QAM, multi-path, time-capture signal from the Signals Disk. Other tasks in this section use this signal to teach you how to use adaptive equalization.

1 Initialize the analyzer and select the Video Demodulation instrument mode:

Press [Instrument Mode], [receiver], [IF section 10-10 MHz1].

Press [Preset].

Press [Instrument Mode], [Video Demodulation].

2 If your analyzer has the optional, second input-channel installed, turn it off:

Press [Input], [channel 2], [ch2 state off].

3 Load the time-capture data into the capture buffer:

Insert the Signals Disk in the analyzer's disk drive.

Press [Save/Recall], [default disk], [internal disk].

Press [Return], [catalog on].

Rotate the knob until the file EQSIGNAL.DAT is highlighted.

Press [recall more], [recall capture buffer], [enter].

Using time-captured data causes the analyzer to automatically measure from the capture-buffer instead of the input channel and sets the center frequency, span, and resolution bandwidth to those used when the data was captured. In a typical equalization measurement you would set these parameters instead of loading captured data.

To demodulate the multi-path signal

This task shows you how to demodulate the multi-path signal that you loaded in the previous task.

1 Load the multi-path signal as instructed in the previous task.

2 Set demodulation parameters for this signal:

```
Press [Instrument Mode], [demodulation setup].
Press [symbol rate], 5 [MHz].
Press [filter alpha], 0.15 [enter].
Press [result length], 500 [sym].
Press [demod format], [QAM 16], [Return].
Press [Time], [points/symbol], 1 [enter].
```

3 Configure different displays for the demodulated data:

```
Press [Display], [4 grids quad].

Press [A], [Measurement Data], [more choices], [channel frequency resp].

Press [B], [equalizer impulse resp], [Data Format], [magnitude log(dB)].

Press [C], [Measurement Data], [symbol table/error summary]

Press [D], [Measurement Data], [IQ measured time],

Press [Data Format], [polar (IQ) constellation], [more format setup], [symbol dots].
```

4 Start the measurement:

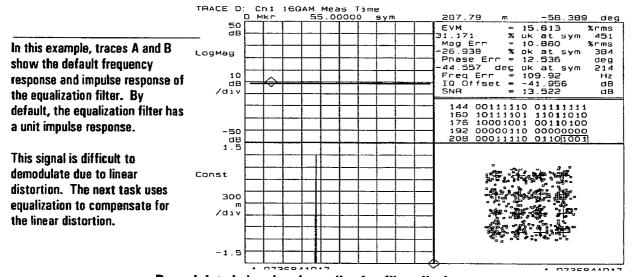
Press [Meas Restart].

Using Adaptive Equalization

Traces A and B display the frequency response and the impulse response of the equalization filter. You can view these displays even when you are not using the equalization filter. In this example equalization is turned off, therefore the equalization filter does not change and these displays remain constant.

Traces C and D display the symbol table and constellation diagram for the multi-path signal. The signal contains a significant amount of distortion which makes it difficult to demodulate. The next task uses equalization to compensate for distortion in the signal which significantly improves these displays.

By default, the equalization filter is defined to have a unit impulse response which yields a flat frequency response.



To apply adaptive equalization

This task shows you how to apply adaptive equalization to the multi-path signal that you demodulated in the previous task.

- 1 Perform the previous task.
- 2 Display the equalization-filter menu:

Press [Instrument Mode], [demodulation setup], [equalizer].

3 Set equalization parameters for this measurement:

Press [eq filter len], 41 [sym].

Press [convergence], then press the up or down arrow key until convergence is 2e-06.

4 Configure the equalization filter to update with each measurement:

Press [eq adapt run].

5 Reset the equalization filter:

Press [eq reset].

6 Enable the equalization filter:

Press [eq filter on].

7 Restart the measurement:

Press [Meas Restart].

8 Autoscale traces A and B (the frequency response and impulse response of the equalization filter) as the analyzer shapes the equalization-filter.

Press [A]

Press [Shift], [B].

Press [Auto Scale].

Using Adaptive Equalization

This example lets you watch as the analyzer shapes the equalization filter. The analyzer estimates new filter coefficients with each measurement, and then uses the new coefficients to adapt the filter for the next measurement.

By default, the equalization filter has a unit impulse response when the analyzer is first turned on, if you press [Preset] or [eq reset], or if you change instrument modes or [points/symbol]. Aside from these conditions, the analyzer uses the last computed coefficients when you enable equalization. For example, if you used equalization in a previous measurement, the analyzer uses the coefficients from the previous measurement unless you press [Preset] or [eq reset], or change instrument modes or [points/symbol]. Therefore, it is good practice to press [eq reset] to reset the filter coefficients before you start a measurement.

The [convergence] determines how quickly the old and new filter-coefficients converge. Larger values converge faster. Values that are too large can cause the adaptation algorithm to become unstable or fluctuate from stable to unstable. Filter length, points-per-symbol, modulation format, and result length interact to determine the best value for convergence. Good results are normally achieved using values between 10^{-7} and 10^{-6} .

HINT

At the start of your measurement, set the convergence high to quickly shape the filter. Then decrease the convergence to fine-tune the filter to the optimum shape.

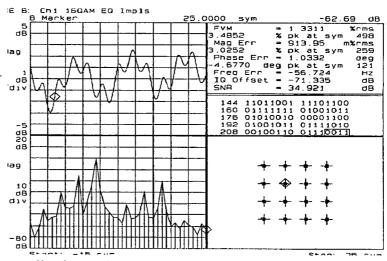
The equalization filter length ([eq filter len]) affects the number of taps in the equalization filter. For multi-path environments, longer filter lengths are needed to estimate good filter coefficients.

The following parameters affect measurement speed when using adaptive equalization.

- [result length]
- [eq filter len]
- [points/symbol]

For additional details, see online help for the [eq filter on/off] softkey.

In this example, trace A shows the frequency response and trace B shows the impulse response of the equalization filter. With [eq adapt run] selected, the traces change with each measurement as the analyzer updates the filter coefficients.



Applying equalization to the measurement

To measure signal paths

This task shows you how to use the equalization filter's impulse response to identify and measure paths in a multi-path signal. This task uses the multi-path signal on the Signals Disk and is a continuation of the previous task.

- 1 Perform the previous task.
- 2 Configure the display to show the impulse response of the equalization filter in a single grid:

Press [B], [Display], [single grid].

- 3 Change the x-axis units to seconds from the default unit of symbols: Press [Ref Lvl/Scale], [X & Y units setup], [X units], [s].
- 4 Display bars at the symbol locations: Press [Data Format], [more format setup], [symbol bars].
- 5 Move the marker to the peak impulse (this is the main signal path): Press [Shift], [Marker].

The marker readout shows the main impulse at 0 seconds with approximately 0 dB of loss.

6 Move the marker to the next peak (this is the second signal path): Press [Marker Search], [next peak].

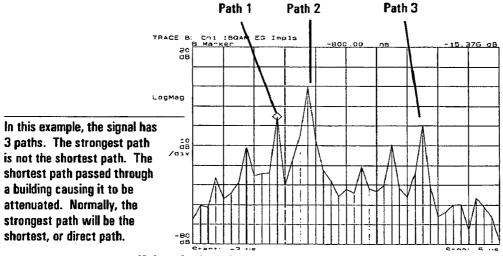
The marker readout shows the second signal path at -800 ns with approximately 15 dB of loss relative to the main impulse (the strongest path).

7 Move the marker to the next peak (this is the third signal path): Press [next peak] again.

The marker readout shows the third signal path at $3 \mu s$ with approximately 20 dB of loss.

The impulse response in this example shows several peaks. The three highest peaks correspond to the main signal path plus two multi-path signals. The remaining peaks correspond to the two multi-path signals, as described in the next paragraph.

Each point in the impulse-response display corresponds to a tap in the feed-forward equalizer (FFE). In a FFE, large coefficients that are separate from the main tap correspond directly to alternate signal paths. The smaller peaks are a result of the same alternate signal paths that created the large peaks. In other words, a signal with one strong alternate path will have more than two impulses on the display (the main impulse and the impulses due to the alternate path). The additional impulses will be lower than the two main impulses.



Using the impulse-response display to measure multi-path signals.

To learn more about equalization

Adaptive equalization is a powerful feature that you can use in many applications. The following paragraphs include additional information that may help you use adaptive equalization for your application.

- The primary application of the equalizer's *impulse-response* display is for evaluating multi-path environments. Multi-path environments usually require longer filter lengths.
- The primary application of the equalizer's *frequency-response* display is for evaluating the transmitter or receiver signal-path for errors such as passband ripple and group-delay distortion. Short filter lengths usually work well for these types of measurements.
- By default, the equalization filter has a unit impulse response (only one tap in the
 filter has a non-zero value and data simply passes through the filter). The
 position of the unit impulse is a function of the filter length and is positioned to
 provide the most optimum efficiency for most situations. The position cannot be
 adjusted.
- The filter length and points/symbol determine the number of taps in the equalization filter, as follows:

```
\# Taps = ((filter\_length - 1) times points\_per\_symbol)) + 1
```

Press [Instrument Mode], [demodulation setup], [equalizer], [eq filter len] to set the filter length. Press [Time], [points/symbol] to set the points/symbol.

- Generally, there is no advantage to using more than 2 points/symbol when using
 equalization. You may want to use more than 2 points/symbol for better
 resolution of such displays as eye diagrams, but the tradeoff is slower
 measurement speed.
- To see the channel frequency-response over the entire bandwidth of your signal, use 2 points/symbol or greater. You cannot see the channel frequency-response over the entire bandwidth of your signal if you use 1 point/symbol.
- Online help for the equalization-filter softkeys includes additional information.
 Select Digital or Video demodulation, then press [Help], [Instrument Mode], [demodulation setup], [more] and any equalization softkey.

3

Using Band-Power Markers

This chapter shows you how to use band-power markers.

To measure band power with improved dynamic range

1 Initialize the analyzer:

Press [Preset].

Press [Instrument Mode], [receiver], [RF section 10-10 MHz]].

Press [Instrument mode], [Vector].

Press [System Utility], [memory usage], [configure meas memory], [num math temp], 5.

2 If your analyzer has the optional second input channel installed, turn it off:

Press [input], [channel 2], [ch2 state off].

3 Supply a signal from the internal source:

Connect the SOURCE output to the INPUT with a cable.

Press [Source], [source on], [sine treq], 5 [MHz].

4 Select video averaging:

Press [Average], [average on].

5 Display the same spectrum measurement in two grids:

Press [Display], [2 grids].

Press [B].

Press [Measurement Data], [spectrum] or [spectrum ch1] (for a two channel analyzer).

6 Measure the power in the source signal with a single marker:

Press [A], [Shift], [Marker] to put the marker on the peak.

7 Measure the power in the source signal with band power markers:

Press [Marker Function], [band power markers], [band pwr mkr on].

Press [band center], 5 [MHz].

Press [band width], 2 [MHz].

For a sinusoid in vector mode, the peak marker and the band power marker will report nearly identical results.

8 Measure the noise power in an adjacent band:

Press [B], [Marker Function], [band power markers], [band pwr mkr on]. Press [band center], 7 [MHz].

Press [band width], 2 [MHz].

In this measurement, the analyzer's receiver is contributing much of the noise. Using waveform math and data registers, it is possible to calibrate out much of the noise and improve the dynamic range of this measurement by as much as 10 dB.

9 Measure the input noise with the source disabled:

Press [Source], [source off].

Press [Average], [num averages], 100 [enter].

Press [Meas Restart].

10 When the average count reaches 100, save the spectrum measurement of the noise floor into a data register:

Press [A], [Save[Recall], [save trace], [into D1]

11 Create a math function to subtract the instrument noise from the spectrum measurement:

Press [Math], [define F1].

Press [operation], [SQRTI].

Press [meas data], [spectrum ch1], [*], [meas data], [spectrum ch1].

Press [-], [data reg], [D1], [*], [data reg], [D1].

Press []], [enter].

The math function should read F1 = SQRT(SPEC1*SPEC1-D1*D1).

Note

The math function takes this form because the spectrum results have units of volts. To convert the units from voltage to power, the spectrum data should be multiplied by its conjugate. The conjugate operation has been left out of this particular equation because the imaginary component is zero when averaging is enabled. A conjugate operation would not change the result—only the speed at which is is calculated. The SQRT() operation forces the math result to have units of volts. The selection of [magnitude log(dB)] in the [Data Format] menu causes the displayed result to be displayed in power units

12 Select the math function as the new result in both traces:

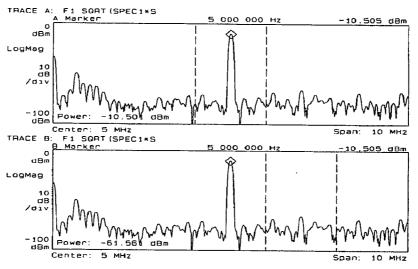
Press [A], [Shift], [B] to select both traces.

Press [Measurement Data], [math func], [F1].

13 Turn the source on and restart the measurement:

Press [Source], [source on].
Press [Meas Restart].

The signal power should be the same as before. The noise power displayed in trace B should be eight to ten dB lower than before.



Band power measurement

4

Using the LAN

This chapter shows you how to configure and use the analyzer's LAN interface. X-Windows operation and FTP (File Transfer Protocol) are available only in analyzers that have option UG7 (Advance LAN).

To determine if you have option UG7

- 1 Turn on the analyzer.
- 2 Press [LAN setup]. If softkey F4 is [X11 display on/off], you have option UG7. If the [X11 display on/off] softkey does not exist, you do not have option UG7.

Option UFG, the LAN interface, is standard in all HP 89441V analyzers. This option lets you use telnet or C-programs to send HP-IB commands to the analyzer via the LAN.

Option UFG consists of a single printed circuit board (card) that contains 4 MegaBytes of memory, a LAN interface, and an additional HP-IB port. The LAN interface provides Ethernet (IEEE 802.3) LAN compatibility and has two LAN ports: a ThinLAN BNC and a 15-pin AUI (MAU) connector. The additional HP-IB port is a controller-only port that communicates with external HP-IB devices, and provides a simple way to program external receivers (such as downconverters) without tying up the primary HP-IB port or system controller. For details on using external receivers, see "Using the HP 89411A Downconverter."

Option UG7 enhances option UFG. This option provides remote X-Windows capabilities, which lets you view the analyzer's display and control the analyzer from across the building or across the world. Option UG7 also includes FTP (File Transfer Protocol) software. You can use FTP to transfer data to and from the analyzer.

To order option UG7 (Advanced LAN Support), contact your local Hewlett-Packard Sales and Service Office.

To connect the analyzer to a network

- 1 Turn off the analyzer.
- 2 If your network uses ThinLAN BNC cables, connect one of them to the ThinLAN connector on the analyzer's rear panel. or If your network uses MAUs, connect one of them to the AUI Port connector on the analyzer's rear panel.
- 3 Turn on the analyzer.
- 4 Press [Local/Setup], [LAN setup], [LAN port setup].
- 5 Press [port select] to display the option corresponding to the connector you used in step 2: either "ThinLAN (BNC)" or "AUI (MAU)."

The ThinLAN connector only allows you to connect the analyzer to a ThinLAN network. However, the AUI Port lets you to connect the analyzer to ThinLan, ThickLAN, or StarLAN 10 networks via the appropriate off-board MAU. (These networks are Hewlett-Packard's implementation of IEEE 802.3 types 10BASE2, 10BASE5, and 10BASE-T.)

The analyzer should be connected to a network by only one of its LAN connectors. Check with your network administrator if you have any other questions about the LAN connections.

To set the analyzer's network address

- 1 Ask your network administrator to assign an Internet Protocol (IP) address to your analyzer. Write down the address for use in step 4.
- 2 If your analyzer must communicate with computers outside of the local subnet, ask your network administrator for the IP address and subnet mask required to route data through the local gateway. Write down these values for use in steps 5 and 6.
- 3 On the analyzer, press [Local/Setup], [LAN setup], [LAN port setup].
- 4 Press [IP address], type the address obtained in step 1, then press [enter].
- 5 If you obtained a gateway address in step 2, press [gateway IP], type the address, then press [enter].
- 6 If you obtained a mask value in step 2, press [subnet mask], type the value, then press [enter].
- 7 Turn off the analyzer, then turn it back on to make the new settings permanent.

You must enter the addresses and the subnet mask using dotted decimal notation (for example, 13.1.212.66). You can disable gateway routing by setting [gateway IP] or [subnet mask] to 0.0.0.0.

To activate the analyzer's network interface

- 1 Press [Local/Setup], [LAN setup], then press [LAN power-on] to display "active."
- 2 Turn off the analyzer, then turn it back on to make the new setting permanent.

When you are not using the network interface, you should press [LAN power-on] to display "inactive." This will free additional memory for other uses.

To send HP-IB commands to the analyzer

- 1 Confirm that the first four tasks in this chapter have been completed.
- 2 If you do not know the network address of your analyzer, press [Local/Setup], [LAN setup], [LAN port setup], then write down the value displayed under [IP address].
- 3 On the computer, type: telnet <IP_address> (where <IP_address> is the network address of your analyzer).
- 4 On the computer, type the HP-IB command that you want to send to the analyzer. For example, to query the analyzer for its center frequency, type: FREQ: CENTER?
- 5 To end your telnet session, type <Ctrl><D>.

The computer you use to send HP-IB commands to the analyzer must be attached to the network and configured with software that supports the TELNET protocol. For additional information about using telnet, refer to the documentation that came with your TELNET software.

To select the remote X-Windows server

- 1 Determine the IP address of the computer you will use for remote X-Windows operation. (Ask your network administrator for help if you don't know how to do this.) Write down the address for use in step 3.
- 2 Press [Local/Setup], [LAN setup].
- 3 Press [X11 IP address], type the address obtained in step 1, then press [enter].

After you have attached the analyzer to the network and configured it as described in the previous two tasks, you can operate it remotely from any computer that is attached to the network and running X-Windows. This task shows you how to select the computer you want to use for remote operation. The next task shows you how to initiate remote operation.

Remote X-Windows is available only in analyzers that have option UG7. To determine if your analyzer has option UG7, see the task: "To determine if you have option UG7."

To initiate remote X-Windows operation

- 1 Confirm that the previous six tasks have been completed.
- 2 On the remote computer (selected in the previous task), position the mouse pointer in one of the windows, then enter the following command: xhost +
- 3 On the analyzer, press [Local/Setup], [LAN setup].
- 4 Press [X11 display] to display "on."
- 5 On the remote computer, use the mouse to position the outline of the remote X11 display, then click the left mouse button to continue.

When you complete this task, the outline of the remote X11 display is filled in with a replica of the analyzer's front panel. The computer maintains this replica by using its LAN connection to get the latest trace, and state information, from the analyzer.

You may find that the computer responds more slowly to other processes (for example, key presses and mouse movements) while it is maintaining the X11 display. If it responds too slowly, you can decrease the value of [rate limit], which is located under [Local/Setup], [LAN setup]. This allows the analyzer to respond more quickly to other processes by reducing the amount of time it spends maintaining the X11 display.

Remote X-Windows is available only in analyzers that have option UG7. To determine if your analyzer has option UG7, see the task: "To determine if you have option UG7."

To use the remote X-Windows display

- 1 Confirm that the previous task has been completed.
- 2 Use the instructions in the following paragraphs to control the analyzer from the remote X-Windows display.
 - To press a key. Place the cursor on the key, then click the left mouse button.
 - To activate shifted key functions. Place the cursor on the [Shift] key, then click the left mouse button. (Text is now displayed in blue on keys with shifted functions.)
 - To modify parameters. Click on the key that activates the parameter you want to modify, use the computer's keyboard to type the new text or number, then click on [enter] (or the appropriate units key.)
 - To turn the knob. Place the cursor on the knob, then click the right or left mouse button to turn it; right turns it clockwise, left turns it counter-clockwise.
 - To position the marker. Place the cursor on or near the trace at the desired x-axis location, then click the left mouse button.

You may want to pause the analyzer before changing its configuration via the X-Windows display. The analyzer can respond more quickly to these changes when it is paused. Click on [Pause|Single] to pause the analyzer.

Remote X-Windows is available only in analyzers that have option UG7. To determine if your analyzer has option UG7, see the task: "To determine if you have option UG7."

To transfer files via the network

- 1 Confirm that the first four tasks in this chapter have been completed.
- 2 If you do not know the network address of your analyzer, press [Local/Setup], [LAN setup], [LAN port setup], then write down the value displayed under [IP address].
- 3 On the computer, type: ftp <IP_address> (where <IP_address> is the network address of your analyzer).
- 4 On the computer, just press <Enter> (or <Return>) when you are prompted for a name and password.
- 5 If you want to list the files in the root directory, type: 1s
- 6 Change to the directory where you want the file transfer to occur by typing: cd <directory>
- 7 If the file is an ASCII file, set FTP to ASCII by typing: ascii. If the file is a binary file, set FTP to binary by typing: binary.
- 8 If you want to transfer a file from the analyzer to the computer, type: get <filename>
- 9 If you want to transfer a file from the computer to the analyzer, type: put <filename>

10 To exit FTP, type quit

The computer you use to transfer files must be attached to the network and configured with software that implements the following networking application: TCP/IP's File Transfer Protocol (FTP). Refer to the documentation supplied with that software for additional information about using FTP to transfer files.

You cannot transfer LIF files from the computer to the analyzer. LIF files can only be transferred from the analyzer to the computer. If you transfer a LIF file from the computer to the analyzer, the LIF file will be corrupted.

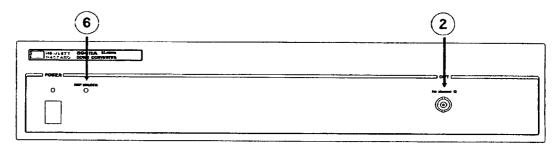
For information about the analyzer's directory structure, see the "FTP (File Transfer Protocol)" topic in online help. (Press [Help] [1] to select the online help index, use the knob or the arrow keys to highlight "FTP (File Transfer Protocol)," and press [4]). FTP is available only in analyzers that have option UG7. To determine if your analyzer has option UG7, see the task: "To determine if you have option UG7."

5

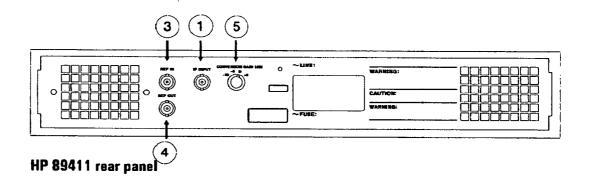
Using the HP 89411A Downconverter

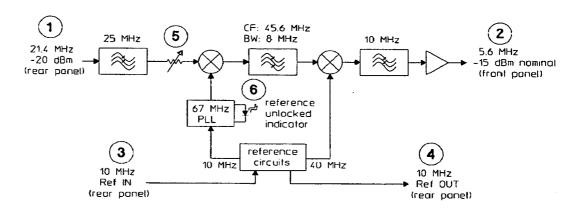
The HP 89411A allows the use of the advanced analysis features of the HP 89410A (the IF Section) to be applied to signals above the frequency limit of the HP 89441V.

The HP 89411A at a Glance



HP 89411A front panel





HP 89411A block diagram

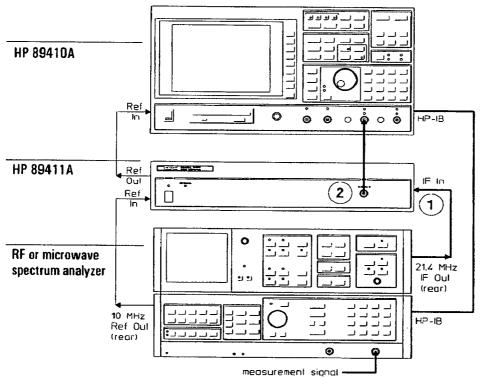
Descriptions

The HP 89411A is a fixed downconverter used to translate the 21.4 MHz IF output on several Hewlett-Packard RF/microwave spectrum analyzers to a baseband frequency within the range of the HP 89410A. It translates the entire IF bandwidth to a baseband frequency centered at 5.6 MHz, The conversion gain of the HP 89411A can be varied to be compatible with several different spectrum analyzers.

The following describes elements appearing in the front and rear panel illustrations, the block diagram, and the setup diagram (on the next page).

- 1 (rear) The IF Input connector. This is a 21.4 MHz signal from the rear panel of an RF or microwave spectrum analyzer. The input signal level should be approximately -20 dBm to achieve optimum performance from the HP 89411A.
- 2 (front) The Output connector provides a 5.6 MHz signal that goes to the Channel 1 input connector on the HP 89410A Vector Signal Analyzer. This signal should be approximately -15 dBm. The downconversion gain step attenuator 5 may be adjusted to change the gain.
- **3** (rear) The Reference Input connector accepts a 10 MHz reference signal from the RF or microwave spectrum analyzer.
- **4** (rear) The Reference Output connector provides a 10 MHz reference signal that goes to the HP 89410A Vector Signal Analyzer.
- **5** (rear) The downconversion gain switch controls a step attenuator that allows you to adjust the total gain of the downconverter from +5 dBm to -15 dBm in 5 dB steps, the goal being an output of approximately -15 dBm. When the IF Input level is -20 dBm, an attenuator setting of 0 dB yields an output level of -15 dBm.
- **6** (front) The Reference Unlocked indicator. This indicator lights when the 10 MHz reference input signal at **3** is <0 dBm, or when there is a malfunction in the HP 89411A local oscillator.

Connection and setup details for the HP 89411A



HP 89411 setup diagram

- ☐ If the RF/microwave analyzer is the HP 8566A/B:
- 1 The frequency reference output of the HP 8566 is connected to the reference input in the HP 89411A. The reference output of the HP 89411A connects to the external reference input of the HP 89410A (both signals ≥ 0 dBm).
- 2 21.4 MHz IF output of the HP 8566 connects to the IF input of the HP 89411A. This signal level is nominally -20 dBm when the signal level on the HP 8566 is at its reference level (top of screen).
- 3 The (front panel) baseband output of the HP 89411A is connected to the channel 1 input on the HP 89410A. Its level is nominally -15 dBm when the step attenuator in the HP 89411A is set to the rightmost position (labeled +5 dB). For optimum results the input range of the HP 89410A should be set to -14 dBm.

Note

The SYSTEM INTERCONNECT port is provided only for connection to the spectrum analyzer used with the HP 89411A 21.4 MHz Down Converter.

The HP-IB address for the port is one higher than the analyzer address. For example if [Local/Setup], [analyze addrs] is 19, the address of the SYSTEM INTERCONNECT port is 20. The port is also available via IBASIC at select code 10.

The HP 8566A/B should be set up as follows:

Set the center frequency to the frequency of your signal. Set the frequency span to 0 Hz, and the resolution bandwidth to 3 MHz. The reference level should be adjusted so that the signal lies within 1 division of the top of the screen. The vertical scaling should be set to linear rather than log. You should also set the sweep time to a large value (e.g., 100 seconds) to prevent the sweep retrace from causing unwanted transients in your measurement.

☐ If the RF/microwave analyzer is an MMS system:

Several possibilities exist here, depending on the combination of RF and IF modules present. In addition, the frequency reference connections are more involved. The conversion gain of the system depends on which IF module supplies the 21.4 MHz IF signal, and the attenuator setting of the RF section. The nominal conversion gains in the section that follows do not include effects of frequency response of the RF section. The conversion gain is generally smaller at higher frequencies, especially for the RF sections with preselectors (e.g., 70905, 70906, and 70908). For simplicity, the stated conversion gains assume the attenuation of the RF section is set to 0 dB. However, to prevent damage to the mixer in the RF section, it is recommended that the attenuation be set to at least 10 dB. You should make sure the reference level and attenuator settings are appropriate for your measurement. The reference level should be set to a level equal to or larger than the largest signal you expect to measure.

At this time you should also set the following parameters: Set the center frequency to the frequency of your signal and the frequency span to 0 Hz. The reference level should be adjusted so that the signal lies within 1 division of the top of the screen. You should also set the sweep time to a large value (e.g., 100 seconds) to prevent the sweep retrace from causing unwanted transients in your measurement.

The frequency reference module (70310A) should be ordered with the standard configuration (i.e., do not order opt, 002 which deletes the ovenized oscillator), unless there will always be a good externally supplied reference signal present.

- 1 If the system contains a 70902A and a 70903A IF section, the signal flow is normally from the RF section to the 70903A, then to the 70902A. The 21.4 MHz OUT port on the 70903A drives the 70902A, and the AUX 21.4 MHz OUT port on the 70902A drives the HP 89411A IF input. The conversion gain of the system is nominally -5 dB in this case.
- 2 If the system contains only the 70902A IF section, the RF section is connected to the 70902A, and the AUX 21.4 MHz OUT port of the 70902A drives the IF input of the HP 84911A. The conversion gain is nominally -5 dB.
- 3 If the system contains only the 70903A, the RF section drives 21.4 MHz input, and its 21.4 MHz OUT port drives the HP 84911A input. The conversion gain is nominally +5 dB.
- 4 If the system contains only an RF section (such as the 70904A) then the output can be taken from it directly to the HP 89411A input. The conversion gain of the RF section is nominally 5 dB.

In some of the situations previously listed, the combination of input signal level, attenuation, and IF section employed may result in a IF level at the HP 89411A input that is too large. The conversion gain switch on the rear of the HP 89411A should be set to provide a lower amount of conversion gain in this case. To obtain optimum performance from the HP 89411A, its conversion gain should be set, if possible, to give –15 dBm at the HP 89411A front panel output for the largest measured signal. In some cases, the amplitude may be too small and you should lower the range setting of the HP 89411A to obtain the best dynamic range.

Example

If you have an RF signal level of +10 dBm into the MMS spectrum analyzer configured as previously described, you would probably want to use the following setup. The MMS spectrum analyzer's reference level is set to +10 dBm resulting in 20 dB of RF attenuation and the signal at the 70902A AUX 21.4 MHz OUT port is -15 dBm. The conversion gain of the HP 89411A should be set to 0 dB and the signal provided to the HP 89411A is -15 dBm, as desired.

For more complete information on MMS system components, refer to the operation manual supplied with your system, and to the *Modular Measurement System* catalog.

Using the HP 89411A Downconverter

6

Choosing an Instrument Mode

The analyzer provides three measurement modes—Scalar, Vector, and Video Demodulation. This chapter provides a brief overview of the instrument modes and guidelines for choosing which type you need for various measurement situations.

Why Use Scalar Mode?

If you've used a spectrum analyzer before, you should have no trouble making scalar measurements with this analyzer. And even if you haven't used a spectrum analyzer before, you'll find this analyzer quite easy to learn.

Scalar measurements are implemented differently than measurements in the traditional swept-tuned spectrum analyzer, but the results will appear familiar to you. For more details on the implementation of scalar measurements see "What Makes this Analyzer Different" and "Fundamental Measurement Interactions".

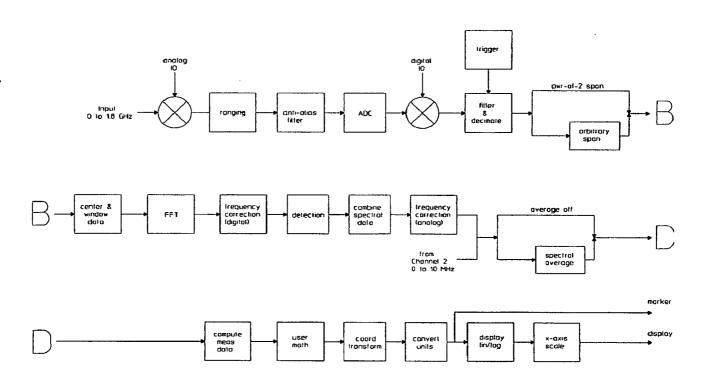
Scalar Measurements provide displays of amplitude versus frequency for both narrow and wide spans. Use Scalar Mode when you need:

- Very narrow resolution bandwidth with high speed
- Very low noise floor with wide spans
- High signal-to-noise dynamic range
- Maximum flexibility of span, resolution bandwidth, and speed
- Spans greater then 8 MHz

Specific examples of applications for which you would use Scalar Mode include:

- Looking at spurious signals or noise
- Looking for low level distortion products

Measurement data flow diagram for Scalar Mode



Why Use Vector Mode?

The Vector Mode provides extremely fast measurements of magnitude and phase. It can also easily change between the frequency and time domains. These capabilities are especially useful in characterizing transient or non-stationary signals.

If you've used a swept-tuned spectrum analyzer before, you already know that narrow resolution bandwidth measurements of small frequency spans are very time-consuming. Traditionally, swept-tuned analyzers have required very long sweep times for narrow resolution bandwidths due to the sweep rate of the narrow filters. The narrower the resolution bandwidth, the more time it takes for the resolution bandwidth filters to settle. In fact, a swept-tuned analyzer's sweep time is inversely proportional to the square of the resolution bandwidth. As you choose increasingly narrower resolution bandwidths (for example, when trying to resolve close-in sidebands) the time it takes to make a measurement *increases* exponentially. This characteristic is common to all conventional swept-tuned analyzers.

However, this analyzer can make narrow band measurements very quickly in Vector Mode. This lets you make measurements for spans from 1 Hz to 10 MHz (with resolution bandwidths from 9.6 mHz to 3 MHz) much faster than you can with a swept spectrum measurement. For vector measurements, the analyzer uses the FFT (Fast Fourier Transform) to convert the input signal from the time domain to the frequency domain. The result is measurement capability up to 1000 times faster than conventional swept spectrum analyzers.

If you have previously used FFT or dynamic signal analyzers, Vector measurements will seem familiar to you. However, with most FFT analyzers you are restricted to low frequency measurements, often to less than 100 kHz. But in this analyzer, Vector Mode lets you perform FFT measurements that extend beyond 1 GHz.

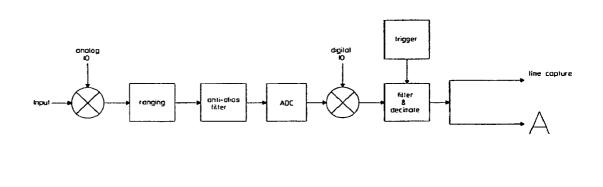
Use Vector Mode when you need:

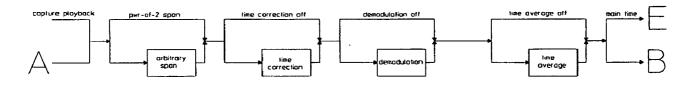
- Time selective (gated) frequency domain measurements
- Time data display
- Phase information
- Time capture/playback
- Narrow span with high speed

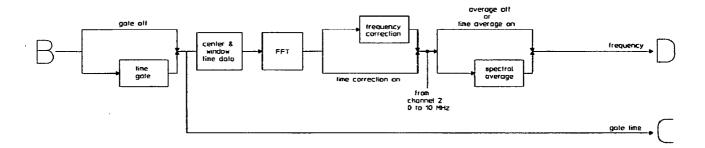
Specific examples of applications for which you would use Vector Mode include:

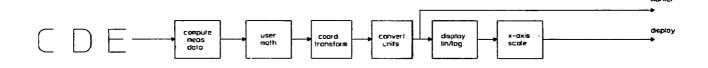
- Characterizing spurious response of an oscillator
- Characterizing a burst signal in both the time and frequency domain

Measurement data flow diagram for Vector Mode









Why Use Video Demodulation Mode?

The video demodulation mode acts as a *reference receiver*. It demodulates the signal with a high degree of accuracy, enabling information to be extracted from it. This information includes a portion of the binary data stream, as well as metrics that indicate modulation (signal) quality.

With the video demodulator you may choose to:

- View eye and constellation diagrams to identify sources of modulation error such as IQ gain and phase imbalance.
- Look at phase error as a function of time or symbol to look for oscillator instability.
- Look at amplitude error as a function of time to look for distortions associated with signal amplitude.
- Use the equalizer to characterize linear distortion. For example, you can observe group delay distortion over the bandwidth of the signal.
- Measure carrier frequency while the signal is modulated.
- Use the error vector spectrum to identify spurious interference that would otherwise be invisible in the signal spectrum.
- Use quality metrics such as EVM and MER for go/no-go testing.

The Advantage of Using Multiple Modes

You can often take advantage of the analyzer's flexibility by using more than one instrument mode in a measurement scenario.

Scalar—the big picture

Use Scalar Mode to identify signals present in a wide span and to evaluate small signals very close to the noise floor. For example, in evaluating an oscillator you can use Scalar Mode to identify spurs and harmonic distortion products and evaluate them with very narrow resolution bandwidths.

Vector—the important details

After you have identified signals in a wide-span Scalar measurement, use Vector Mode to quantify and analyze the important signals with phase and time data capabilities. In the oscillator example above, you could use Vector Mode to measure oscillator sidebands.

Video Demodulation—another view of the details

After you have identified the video signal's carrier frequency in a Vector measurement, use Video Demodulation to determine the modulation (signal) quality of the video signal.

Instrument Mode? Measurement Data? Data Format?

Instrument modes

When you specify an instrument mode, you are asking the analyzer to acquire input data and process it in a certain way. For example, with the Vector Mode, the analyzer uses an FFT algorithm to convert a single time record into the most basic frequency domain measurement available—the spectrum. For Video Demodulation Mode, the signal is filtered by a matched filter and demodulation for signal quality analysis.

Look at the front panel. Notice how the [Instrument Mode] key is in the MEASUREMENT group. This is because anything you change from this group of keys affects the way the analyzer collects input data. In general, if you change something with these keys (such as the instrument mode, or a different start or stop frequency), the analyzer must make a new measurement.

If you look at the analyzer's front panel, you can see that both the [Measurement Data] and [Data Format] hardkeys are in the DISPLAY group. If you press a key in this group, all you are doing is selecting which type of data you want to display and how you want to display it—you aren't changing the way the analyzer makes measurements or the data that was measured.

Softkeys in the MEASUREMENT group, however do affect the way the analyzer takes input data. For example, [Instrument Mode] is in this group. So is [Frequency], which you use to change the start and stop frequencies. So if you need to change a parameter under any of these menus (or select a different instrument mode), you will need to take new data.

Measurement data

Suppose you've selected the Vector Mode. Now you can select different types of measurement data, for example, the linear spectrum, frequency response, or main time data. No matter which measurement data selection you make, the analyzer does not have to acquire new data. When you select a type of measurement data, you are simply asking the analyzer to display a particular piece of the measurement data that's already been acquired.

Data format

Once you select both an instrument mode and appropriate measurement data, choosing a data format simply tells the analyzer how you want to look at the selected measurement data. For example, if you are in the Vector Mode and you are viewing power spectrum data, you could change the Y-axis scaling by selecting linear magnitude or logarithmic magnitude.

Unique Capabilities of the Instrument Modes

Many features and capabilities are available in all three measurement modes but others are available in selected modes. The following table shows, at a very general level, those features and capabilities which are not universal. The ensuing tables show in more details the features available in each instrument mode.

General Capabilities Unique to Specific Measurement Modes				
,	Scalar	Vector	Video Demodulation	
Phase information	no	yes	yes	
Time data	no	yes	yes	
Gating	no	yes	no	
Time capture	no	yes	yes	
Network Measurements	no	yes	yes *	
Selectable detectors	yes	no	no	
Manual Sweep	yes	no	no	
Very narrow resolution bandwidths	yes	no	no	
Very low rbw/span ratios	yes	no	no	
Spans greater than 10 MHz	yes	no	no	

^{*} with adaptive equalization

Display Features Available by Instrument Mode				
		Scalar	Vector	Video Demodulation
Measurement data	spectrum	yes	yes	yes
	PSD	yes	yes	no
	time	no	yes	yes
	frequency response*	no	yes	yes **
	math functions	yes	yes	yes
	data registers	yes	yes	yes
	coherence*	no	yes	no
	cross Spectrum*	no	yes	no
	correlation	no	yes	no
	capture buffer	no	yes	yes

with optional second channelwith adaptive equalization

	Measurement Features Av	ailable by Instrun	rent Mode	
		Scalar	Vector	Video Demodulation
Trigger types	Free run	yes	yes	yes
	channel1 *	yes	yes	yes
	channel2	yes	yes	yes
	IF channel	no	yes	yes
	HP-IB	yes	yes	yes
	external	yes	yes	yes
Source types _{CW}	CW	yes**	yes	yes
	random noise	yes	yes	yes
	rms (and rms exponential)	yes	yes	yes***
	time (and time exponential)	no	yes	no
	peak hold	yes	yes	yes

available only in receiver modes of 0-10 MHz
 available only when optional RF source is disabled
 available for scalar results, such as EVM; not available for 10 measured reference time and 10 measured spectrum results.

7

What Makes this Analyzer Different?

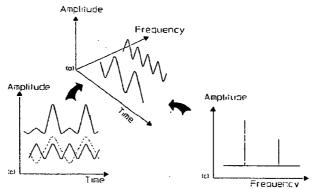
As you become familiar with your new analyzer, you will find that most measurements look like those made with other types of analyzers with which you are probably familiar. This chapter introduces you to the reasons for the similarities, differences, and increased capabilites of this analyzer as compared to other types of analyzers.

Time Domain and Frequency Domain Measurements

Measurements made in the time domain are the basis of all measurements in this analyzer. The time domain display shows a parameter (usually amplitude) versus time. You are probably familiar with time domain measurements as they appear in an oscilloscope. Similar measurements may be viewed with the time measurement data capability.

Frequency-domain displays show a parameter (again, usually amplitude) versus frequency. A spectrum analyzer takes an analog input signal—a time-domain signal—and converts it to the frequency domain (this conversion can be done in several ways; we'll talk about that a little later). The resulting spectrum measurement shows the energy of each frequency component at each point along the frequency spectrum.

Many signals not visible in the time domain (such as noise and distortion products) are clearly visible in the frequency domain. Because spectrum displays show frequency components distributed along the frequency axis, it's possible to view many different signals at the same time. This is why the spectrum analyzer is such a useful tool for looking at complex signals—it lets you easily measure (and compare) the frequency and amplitude of individual components.



Notice the difference between the time-domain and frequency-domain displays of the same input signal.

The Y-axis (amplitude)

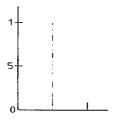
Time-domain measurements are usually viewed with a linear X-axis and a linear Y-axis (think of an oscilloscope). Frequency-domain measurements are sometimes viewed with a linear Y-axis and a linear X-axis, but usually must be viewed with a logarithmic Y-axis, since this is the only way to view very small signals and much larger signals simultaneously.

Let's look at the spectrum of a sine wave. Because the amplitude of any harmonic is small relative to the fundamental frequency, it's nearly impossible to view a harmonic on the same display as the fundamental unless the Y-axis scale is logarithmic. That's why most measurements made with spectrum analyzers use a logarithmic amplitude scale—a scale based on decibels. And since the dB scale is by definition logarithmic, there's no need to use logarithmically-spaced graticule lines.

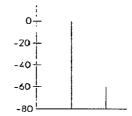
The X-axis (frequency)

Sometimes it's convenient to use a logarithmic X-axis. Perhaps most familiar to you is the frequency response measurement. This is traditionally displayed with a log X-axis (frequency) versus a log Y-axis (relative magnitude).

But most measurements do not require a logarithmic frequency scale. In fact, when making spectrum measurements it's easier to characterize harmonics with a linear X-axis scale since harmonics that are multiples of the same fundamental will appear at evenly-spaced intervals.



(a) Linear Amplitude Scale



(b) Logarithmic Amplitude Scale

What are the Different Types of Spectrum Analyzers?

There are two broad categories of spectrum analyzers: *swept-tuned analyzers* and *real-time analyzers*. Both swept-tuned analyzers and real-time analyzers have been around for many years. However, within the past decade or so, spectrum analyzers have become much more sophisticated. These newer spectrum analyzers use digital signal processing to provide additional measurement capablity—and let you interpret measurement results much more easily.

Both swept-tuned and real-time spectrum analyzers display amplitude versus frequency. How they process and display this information, however, varies with the specific type of analyzer. A real-time spectrum analyzer displays the energy at all frequency components simultaneously. A swept-tuned spectrum analyzer displays measurement results sequentially—in other words, not in "real time." This is because a swept-tuned analyzer, in effect, uses a single narrow filter that is tuned across a range of frequencies to produce a spectrum display.

Swept-tuned analyzers have been the traditional choice for higher frequency applications—for example, 100 kHz and above. Real-time analyzers are generally used for lower frequencies—for example, audio-frequency and vibration measurements.

For an additional overview of spectrum/network measurements, see *Spectrum and Network Measurements* by Robert A. Witte (Prentice Hall, Englewood Cliffs, New Jersey, 1993).

Swept-tuned spectrum analyzers

Swept-tuned spectrum analyzers are descended from radio receivers. So it should come as no surprise that swept-tuned analyzers are either *tuned-filter* analyzers (analogous to a TRF radio) or *superheterodyne* analyzers. In fact, in their simplest form, you could think of a swept-tuned spectrum analyzer as nothing more than a frequency-selective voltmeter with a frequency range that's tuned (swept) automatically.

Modern swept-tuned analyzers (superheterodyne analyzers, in particular) are precision devices that can make a wide variety of measurements. However, they are primarily used to measure steady-state signals since they can't evaluate all frequencies in a given span simultaneously. The ability to evaluate all frequencies simultaneously belongs exclusively to the *real-time* analyzer.

Real-time spectrum analyzers

Despite the high performance of modern superheterodyne analyzers, they still can't evaluate frequencies simultaneously and display an entire frequency spectrum simultaneously. Thus, they are not *real-time* analyzers. And the sweep speed of a swept-tuned analyzer is always limited by the time required for its internal filters to settle.

Parallel-filter analyzers

Another way to build a spectrum analyzer is to combine several bandpass filters, each with a different passband frequency. Each filter remains connected to the input at all times. This type of analyzer is called a *parallel-filter* analyzer. After an initial settling time, the parallel-filter analyzer can instantaneously detect and display all signals within the analyzer's measurement range.

The particular strength of such an analyzer is its measurement speed—this allows it to measure transient and time-variant signals. However, the frequency resolution of a parallel-filter analyzer is much coarser than a typical swept-tuned analyzer. This is because the resolution is determined by the width of the decimating filters. To get fine resolution over a large frequency range, you would need many, many individual filters—thus increasing the cost and complexity of such an analyzer. This is why all but the simplest parallel-filter analyzers are expensive.

Typically, parallel-filter analyzers have been used in audio-frequency applications.

FFT analyzers

FFT spectrum analyzers (also referred to as *dynamic signal analyzers*) use digital signal processing to sample the input signal and convert it to the frequency domain. This conversion is done using the *Fast Fourier Transform* (FFT). The FFT is an implementation of the Discrete Fourier Transform, the math algorithm used for transforming data from the time domain to the frequency domain. This analyzer is an example of an FFT analyzer that can make real-time measurements.

FFT spectrum analyzers are powerful instruments, since their processing power can extract more information from an input signal than just the amplitude of individual frequency components. For example, FFT analyzers can measure both magnitude and phase, and can also switch easily between the time and frequency domains. This makes them ideal instruments for the analysis of communication, ultrasonic, and modulated signals.

If an FFT analyzer samples fast enough, all input data is evaluated and the analyzer makes a *real-time* measurement. When operating in real time, FFT analyzers can make the same measurements traditionally done with parallel-filter analyzers—and make these measurements, if desired, with far greater frequency resolution.

In the past FFT analyzers have had the disadvantage of their restricted frequency range—most FFT analyzers could not make measurements above 100 kHz. The limiting factor has been the speed of the analog-to-digital converter used to sample the analyzer's input signal. This is why swept-tuned superheterodyne analyzers are still used for RF and microwave measurements, though some newer-generation swept-tuned analyzers, such as the HP 3588A and the HP 8560 family of analyzers can also make FFT measurements. As you will see, this trend toward hybrid technology has gone one step further with the HP 89400 Series Vector Signal Analyzers.

See the related sidebar for FFT background information.

FFT Background

FFT Basics

The Fourier transform integral converts data from the time domain into the frequency domain. However, this integral assumes the possibility of deriving a mathematical description of the waveform to be transformed—but real-world signals are complex and defy description by a simple equation. The Fast Fourier Transform (FFT) algorithm operates on sampled data, and provides time-to-frequency domain transformations without the need to derive the waveform equation.

The Fast Fourier Transform (FFT) is an implementation of the Discrete Fourier Transform, the math algorithm used for transforming data from the time domain to the frequency domain. Before an analyzer uses the FFT algorithm, it samples the input signal with an analog-to-digital converter (the Nyquist sampling theorem states that if samples are taken twice as fast as the highest frequency component in the signal, the signal can be reconstructed exactly). This transforms the continuous (analog) signal into a discrete (digital) signal.

Because the input signal is sampled, an *exact* representation of this signal is not available in either the time domain or the frequency domain. However, by spacing the samples closely, the analyzer provides an excellent approximation of the input signal.

FFT Properties

As with the swept-tuned analyzer, the input to the analyzer is a continuous analog voltage. The voltage might come directly from an electronic circuit (for example, a local oscillator) or through a transducer (for example, when measuring vibration). Whatever the source of the input signal, the FFT algorithm requires digital data. Therefore, the analyzer must convert the analog voltage in to a digital representation. So the first steps in building an FFT analyzer are to build a sampler and an analog-to-digital converter (ADC) in order to create the digitized stream of samples that feeds the FFT processor.

The FFT algorithm works on sampled data in a special way. Rather than acting on each data sample as it is converted by the ADC, the FFT waits until a number of samples (N) have been taken and transforms the complete block of data. The sampled data representing the time-domain waveform is typically called a time record of size-N samples.

But the FFT analyzer cannot compute a valid frequency-domain result until at least one time record is acquired—this is analogous to the initial settling time in a parallel-filter analyzer. After this initial time record is filled, the FFT analyzer is able to determine very rapid changes in the frequency domain. A typical size for N might be 1024 samples in one time record.

During the FFT process, the FFT algorithm transforms the N time domain samples into N/2 equally-spaced lines in the frequency domain. Each line contains both amplitude and phase information—this is why half as many lines are available in the frequency domain (actually, slightly less than half the number of lines are used, since some data is corrupted by anti-aliasing filters).

The Difference

The ideal analyzer would combine the advantages of both swept-tuned and FFT analyzers while minimizing the disadvantages. To provide these advantages the HP 89400 series analyzers use FFT technology to provide wideband and high frequency measurements as well as narrowband and low frequency measurements. The nearby figure shows the difference between the modern microprocessor-controlled swept-tuned analyzer and the HP 89400 series analyzers. The analog IF section is replaced by a digital IF section which incorporates FFT technology and digital signal processing to make very fast measurements.

Vector mode and zoom measurements

The HP 89400 series analyzers expand FFT technology to perform measurements on narrow as well as relatively wide spans from baseband to the analyzer's upper frequency limits. Earlier FFT analyzers have been limited to narrow spans and low frequencies. These limitations restricted the ability to measure phase and to analyze time-variant, transient, and modulated signals. These measurements often require real-time analysis with a non-zero start frequency and wide frequency spans. Vector mode provides a single FFT measurement as wide as 8 MHz (or 10 MHz in 0-10 MHz receiver mode). The zoom capability of Vector mode allows you to analyze spans away from DC. You may place a selected narrower span at any frequency within the analyzer's frequency range.

Stepped FFT measurements in Scalar mode

The HP 89400 series analyzers use FFT technology to provide enhanced wideband measurements. Technological advances in designing analog-to-digital converters and digital signal processors have been combined with FFT technology to provide the same results as a swept-tuned analyzer but with additional capability. The nearby diagrams reflect the differences between swept-tuned technology and stepped FFT technology.

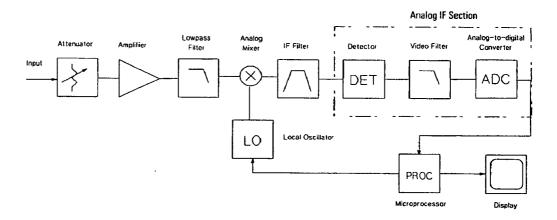
If you are familiar with swept-tuned analyzers for making high frequency measurements you will find that the technology used in the HP 89400 series analyzers has expanded the capability to make FFT measurements with excellent resolution at higher frequency ranges. This has been accomplished by translating the highest frequencies to a lower band, then performing FFTs on separate segments of the spectrum. These segments are displayed contiguously so that the result appears as it would with a swept-tuned spectrum analyzer.

If you have previously used FFT Dynamic Signal Analyzers, you will discover that with the HP 89400 series analyzers you can select spans and resolution bandwidths which have previously been unavailable in FFT analyzers.

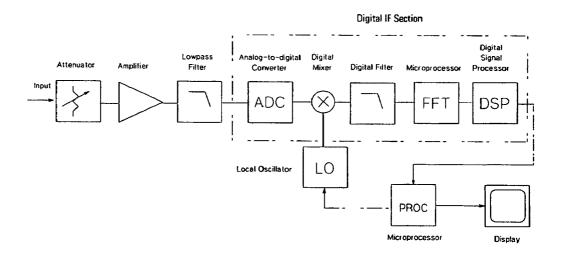
For low resolution bandwidths, the stepped technology in the HP 89400 series analyzers is much faster than swept-tuned analyzers. For each local oscillator step in a swept-tuned analyzer, time is required for the IF filters to settle on each input signal. With stepped technology, the largest time constraint is the time required to collect the data and perform the FFT. This results in speeds up to 1000 times faster with the new stepped technology.

Differences between swept-tuned and stepped analyzer technologies in IF function

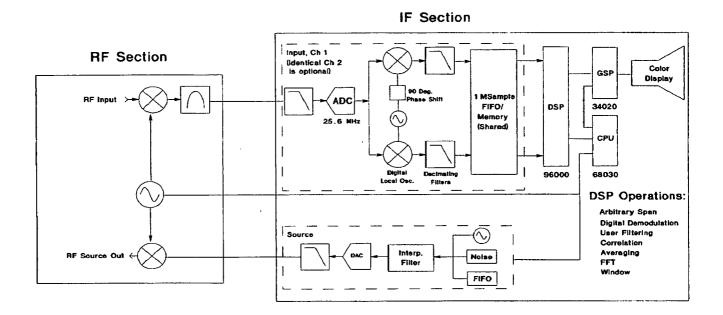
Simplified block diagram of a modern swept-tuned analyzer



Simplified block diagram of the HP 89400 series analyzer



Signal flow diagram

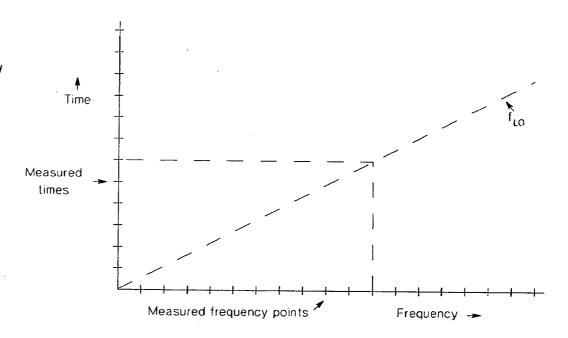


A more complete block diagram shows the complex local oscillator which allows the analyzer to use complex time analysis for phase, demodulation, and other time-related measurements.

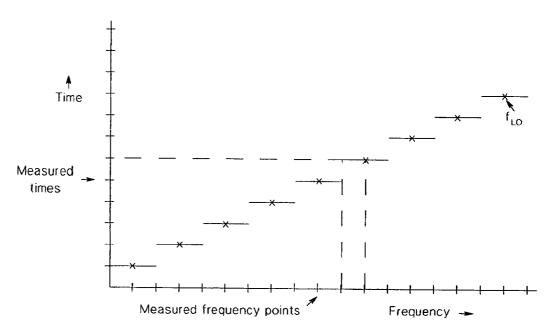
What Makes this Analyzer Different?

The difference between swept-tuned and stepped analyzer technology in local oscillator function

A swept-tuned analyzer changes the local oscillator frequency linearly over time and measures one frequency point at a time



A stepped analyzer like the HP 89400 series changes the local oscillator frequency in sequential steps over time and measures multiple frequency points at one time



8

Fundamental Measurement Interactions

Measurement Resolution and Measurement Speed

You should understand the interactions and limits related to measurement fundamentals in order to optimize your measurements. These fundamentals affect measurement speed, measurement resolution, and display resolution. If you are familiar with either swept-tuned or FFT spectrum analyzers, you will find both similarities and differences in the HP 89400 series analyzers. In any case, you should become acquainted with the material in this section in order to be comfortable with measurements in the HP 89400 series analyzers.

Resolution bandwidth, frequency span, main length, and window selection are closely related in determining measurement resolution and measurement speed. The flexible display resolution also affects your perception of measurement results.

Resolution bandwidth

Resolution bandwidth—often called RBW—determines the analyzer's frequency resolution. It may also affect how fast the analyzer makes a measurement. Normally, resolution bandwidth is adjusted automatically as you select different frequency spans. Resolution bandwidth is one of the most important parameter settings in a spectrum analyzer.

Because resolution bandwidth may also affect measurement time, manually selecting a narrower resolution bandwidth can slow down a measurement more than necessary. Selecting a resolution bandwidth that is too wide, on the other hand, may not provide adequate frequency resolution and can obscure spectral components that are close together.

Narrowing the resolution bandwidth lowers the noise floor because there is less noise power within the bandwidth of a narrower filter. This occurs because noise is equally distributed across the frequency spectrum, so the noise floor is lowered as you progressively restrict the range of frequencies fed to the detector algorithm.

In most analyzers, the final IF filters determine the resolution bandwidth, but in the HP 89400 series analyzers the time record length and window shape determine the resolution bandwidth—resolution bandwidth is largely independent of the span. Resolution bandwidth is related to the number of frequency points and span only when it approaches minimum and maximum limits. You will learn more about this later in this chapter.

Video filtering

In some analyzers, a low-pass filter is included between the detector and the display to smooth the noise level—in some cases revealing low-level signals that might otherwise be obscured. Other analyzers are equipped with a "video averaging" feature. This lets you average successive traces. Because video filtering and video averaging both smooth the noise floor, the results of video averaging are often similar to a single trace with video filtering.

Video averaging with the HP 89400 series Vector Signal Analyzers is actually a better approximation of noise than a video filtered-trace, since a series of averaged measurements will reveal a complete frequency span much faster than the slower progression of a single, video-filtered trace. However averaging, like video filtering, does slow down a measurement.

Frequency span

Full-span measurements let you view the entire available frequency spectrum on one display. With the HP 89410A, for example, full-span measurements extend from 0 Hz to 10 MHz. Measurements with spans that start at 0 Hz are often called baseband measurements.

Alternatively, you may wish to view smaller slices of the frequency spectrum. You can select any number of different spans and position these spans where you want by specifying their start or center frequencies. This process of viewing smaller spans is sometimes called *zooming* or *band-selectable* analysis. You can control the frequency span examined by specifying a center frequency and a span size. Alternatively, you can specify a start and a stop frequency to define a particular frequency span.

In the HP 89400 series analyzers, the sample rate is adjusted, based on the span, to achieve the desired information bandwidth.

Bandwidth coupling

Bandwidth coupling may be used to link resolution bandwidth and frequency span in ways which are important to understand when setting up your measurement.

The automatic adjustment of resolution bandwidth to frequency span is called "bandwidth coupling." It is an important feature and one common to most spectrum analyzers.

For most measurement situations, the default bandwidth coupling type (auto) provides the best compromise between frequency resolution and speed. And for most measurements, bandwidth coupling is generally preferable since it simplifies your measurement setup.

Changing bandwidth coupling

You can easily override the current resolution bandwidth selection by manually entering a setting of your own. For example, you can specify a different resolution bandwidth setting.

If you override a current resolution bandwidth setting, the analyzer remembers the adjustment you made in terms of a resolution bandwidth to span ratio. It attempts to maintain this ratio when calculating appropriate resolution bandwidth for different spans. This is called *offset coupling*. For example, if you changed to a narrower resolution bandwidth than the default (the resolution bandwidth selected automatically), the analyzer maintains a narrower-than-normal resolution bandwidth for subsequent spans. You can also specify this type of coupling by selecting [offset coupled]. This type of coupling allows the response to appear the same as the span is changed.

The other available coupling type is *fixed* coupling which maintains a resolution bandwidth setting independent of other parameter changes. For example, this allows you to change span without changing resolution bandwidth. Fixed coupling is automatically selected if you explicitly alter the analyzer's time record length.

Flexible bandwidth mode

The HP 89400 series analyzers offers two levels of flexibility in selecting a resolution bandwidth setting: 1-3-10 and arb. The first, 1-3-10, is the more restrictive. In this mode the analyzer always sets the resolution bandwidth at a 1 X 10^{x} or 3 X 10^{x} value. In this mode the analyzer emulates many existing spectrum analyzers. The arb mode allows arbitrary setting of resolution bandwidth. Your choice of bandwidth mode in conjunction with your choice of rbw coupling mode affects both resolution and speed. To get the best resolution to speed tradoff, choose *auto* rbw coupling and arb rbw mode.

Display resolution and frequency span

FFT analyzers have a finite record length, usually stated in number of "points," "lines," or "bins." We will use the term "frequency points." Most FFT analyzers use the same number of frequency points regardless of frequency span. However, with the HP 89400 series analyzers you may select a variable number of frequency points. The HP 89400 series analyzers have a default resolution of 401 frequency points but you may select from 51 to 3201 points of display resolution. However, for a given number of frequency points, narrower spans have finer frequency resolution. This is because the same number of frequency points represents a smaller range of frequencies.

For each frequency span, the analyzer assigns a discrete frequency value to each frequency point:

Display resolution =
$$\frac{\text{Frequency span}}{\text{Number of frequency points-1}}$$

The analyzer then uses the specified start frequency to calculate nominal frequency values for each of the remaining points.

To better understand the concept of display resolution, move the main marker from display point to display point. Notice how the marker jumps to each point—you cannot put the marker between points. As you move the marker, also notice how the marker readout steps through a series of discrete frequencies that corresponds to each display point.

Display resolution is different from frequency resolution. See "The relationship between Frequency Resolution and Display Resolution" later in this chapter.

For a given display resolution and window selection, the best measurement resolution is achieved with the bandwidth mode set to <i>arb</i> and bandwidth coupling set to <i>auto</i> .
Set to thing.

Windowing

General

A window is a time-domain weighting function applied to the input signal. A window is a filter used to compensate for the fact that most signals are not periodic within the input time record. Depending on the window, the analyzer attenuates the ends of the input time record, to prevent *leakage*—a smearing of energy across the frequency spectrum—caused by transforming signals that are not periodic within the time record.

FFT analyzers usually have several window types available. Each window offers particular advantages. Because each window type produces different measurement results (just *how* different depends on the characteristics of the input signal and how you trigger on it), you should carefully select a window type appropriate for the measurement you're trying to make.

Windowing is a concept basic to understanding FFT spectrum analyzers. To learn more, see *Spectrum and Network Measurements* by Robert A. Witte. Refer also to online help for a description of each window type and guidelines on choosing a window type.

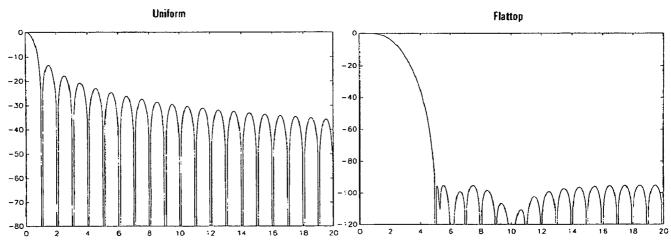
Windows used with this analyzer

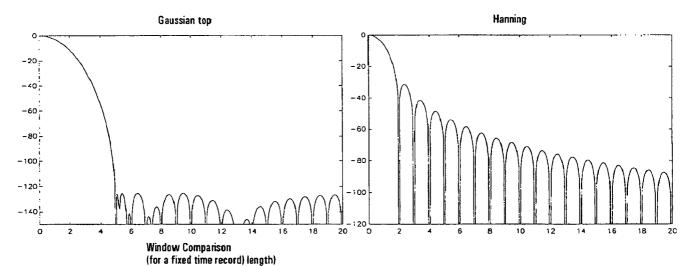
This analyzer functions as if the input signal were applied to a parallel bank of narrow-band filters (the number corresponding to the number of frequency points). The illustrations on the next page show the frequency-domain response of a single filter when using uniform, Hanning, gaussian top, or flattop windows.

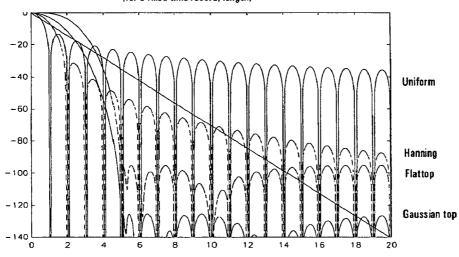
The left side of each illustration represents the center of each filter. Since the filters are symmetrical, we've shown only one side of each filter response (the other side is a mirror image). The horizontal axis is normalized to 1/T.

Think of each drawing as a template. If you position a sine frequency at the exact center of the filter, more of a sine wave's energy appears in the center bin. Some of its energy also appears in other bins. The amount of energy that spills into adjacent bins depends on the type of window you use. Frequency resolution is determined by the width of the main lobe. The Hanning window provides better frequency resolution for a fixed time record length while the Flattop window has good frequency resolution for a fixed resolution bandwidth.

Frequency response of window filters







Enhancing the Measurement Speed

You can make several choices in order to maximize measurement speed:

- Turn calculation off for unused traces under [Measurement Data] [more choices].
- Reduce the number of frequency points to the minimum required for your
 measurement in order to reduce internal vector sizes. This applies to the number
 of frequency points selected in [Res BW/Window] as well as the maximum number
 of frequency points in memory configuration under [System Utilities].
- Choose a cardinal span: $\frac{10^7}{2^n}$.
- Turn the marker off.
- If averaging is used, select fast averaging.
- If you have a two channel analyzer turn off any unused channel under the [input] key.
- If time calibrations are enabled, disable them.

To enhance real-time bandwidth as well as measurement speed, the following suggestions apply:

- Follow the speed enhancing suggestions above.
- Set [rbw mode] to arb
- Select 1601 frequency points for a single channel measurement, or 801 frequency points for a two channel measurement.
- Set [rbw coupling] to auto.

Digital storage

All spectrum analyzers require some form of display storage to retain, on a CRT screen, the relatively slow-moving results of a swept spectrum measurement. Early spectrum analyzers used CRTs with long-persistence phosphors (or storage meshes behind the CRT face) to maintain a visible trace throughout an entire frequency sweep. Modern spectrum analyzers use digital technology to convert the analog output from an analyzer's video detector to binary numbers in an internal memory. These values are then displayed on the analyzer's CRT screen.

Although digital storage requires a display with a finite number of frequency points, there are tremendous advantages to digitizing measurement results. Many functions, such as trace math, were unobtainable with older spectrum analyzers. Digitizing measurement results also makes it easy to save and recall traces and to transfer measurement data to other instruments (for example, over the HP-IB).

Zero response and DC measurements

What is zero response?

When viewing frequency spans that start at 0 Hz (or very close to 0 Hz), a spectral line is usually visible at the extreme left of a spectrum analyzer's display. This is called zero response or LO feedthrough. In an FFT spectrum analyzer, zero response is caused by residual dc that originates in the analyzer's own input amplifiers. Zero response gives the illusion of a dc offset, even if the input signal has no dc component—and this occurs even if the analyzer has an ac-coupled input.

In the HP 89400 Series Vector Signal Analyzers, some degree of zero response is always present in the 0 Hz bin (sometimes called the dc bin). The residual dc that causes this offset may also leak into the first several bins as well. If you don't want to see any zero response on the analyzer's display, simply start the frequency span several bins above 0 Hz.

Can spectrum analyzers measure DC?

Most spectrum analyzers are not intended to measure dc. However, analyzers such as the HP 89400 series analyzers can measure very low frequencies. This analyzer can, in fact, measure dc, but not without including a dc offset of its own that can contribute to (or obscure) a dc offset in the input signal. As we mentioned, this internal offset is caused by residual dc that originates in the analyzer's input amplifiers. Thus, measurement performance at dc is not specified.

Special Considerations in Scalar Mode

Sweep time limitations

Sweep time is the time required for the analyzer to complete one full sweep on the display. With the standard swept-tuned analyzer, sweep time is limited by analog IF filter dynamics because the filter must have time to respond to the input signal before accurately measuring a frequency.

In the HP 89400 series analyzers the digital IF and FFT act like a parallel filter bank so the sweep speed is limited by data collection and digital processing time rather than filters. For this reason, the HP 89400 series analyzers allow measurements for low resolution bandwidths to run much faster than would be case with a swept analyzer. The sweep time is adjusted automatically—the analyzer selects the optimum sweep time, based on the frequency span, the resolution bandwidth, and the maximum number of frequency points.

Stepped measurements

Traditional swept-tuned analyzers are subject to speed and frequency limits imposed by the resolution bandwidth filters which determine the information bandwidth. Traditional FFT analyzers have been subject to fixed resolution bandwidth-to-span limitations. However, the information bandwidth of the HP 89400 series analyzers is determined by the span rather than the resolution bandwidth. Therefore, the resolution bandwidth can be changed without affecting the span.

As discussed previously in the chapter "What Makes this Analyzer Different?", the scalar measurement mode uses a stepped local oscillator to perform multiple FFTs which are then combined into a single trace. This technique, combined with digital signal processing, allows the analyzer to maximize the sweep time and overcome the fixed relationship between resolution bandwidth and span. In effect the minimum resolution bandwidth is limited only by the maximum number of frequency points and the minimum span.

The relationship between frequency resolution and display resolution

For spectrum measurements, your ability to resolve two closely-spaced components—that is, the analyzer's ability to display each component as a separate frequency point—may be limited by the display resolution. However, the maximum frequency resolution obtainable is actually determined by the resolution bandwidth you've selected. As you select increasingly narrower spans, the display resolution improves until the point where you reach the maximum resolution available with the current resolution bandwidth setting.

Resolution limited by current resolution bandwidth setting:

If the resolution bandwidth is insufficient to reveal two closely-spaced components, the detector simply sees these two components as a single frequency and displays them on as a single frequency point. The amplitude of the two components is combined, though it varies from sweep to sweep as the phase relationship between the two components changes.

Resolution limited by current display resolution:

If the display resolution is insufficient to reveal two closely-spaced components—but the current resolution bandwidth setting does provide enough resolution to distinguish two separate components—the detector uses an algorithm (peak, normal, or sample) to select a frequency component and displays it as a single frequency point. However, were you to narrow the span enough or increase the number of frequency points—keeping the resolution bandwidth constant—you would be able to view two discrete frequency components as the display resolution improved.

Resolution bandwidth limitations

The standard swept analyzer uses the last in a series of analog IF filters to determine resolution bandwidth. In contrast, the HP 89400 series analyzers use digital IF and and DSP algorithm to determine resolution bandwidth. For this reason, the narrowest practical resolution bandwidth in Scalar mode is constrained by the length of time you are willing to wait for a measurement to be performed.

The widest resolution bandwidth in Scalar mode is 300 kHz for combinations of span, resolution bandwidth, and maximum number of frequency points which require that the local oscillator be stepped to more than one frequency. But for measurements which do not require that the oscillator be stepped the widest resolution bandwidth is determined by the resolution bandwidth to span ratio:

 $RBW_{max} = .3 \times span$

What is a detector and why is one needed

The measurement results that you view on the CRT screen are actually made up of 51 to 3201 evenly-spaced discrete frequency points. For spectrum measurements, these points represent the range of frequencies that the analyzer evaluates during each frequency sweep—extending from the currently-selected start frequency to the currently-selected stop frequency. The analyzer always uses the number of points you have selected to represent measurement data, regardless of selected frequency span or measurement type.

During spectrum measurements, the analyzer evaluates all frequencies within its displayed frequency span but it determines the number of points to display depending on the number of frequency points you have selected. The interval between frequency points represents one displayed point. Between two frequency points the signal may rise and fall a number of times. A detector determines what signal level to display for each interval.

For example, with narrow resolution bandwidths the stepped FFT measurements can result in more measurement points than were requested. When this occurs a data reduction must occur. The process of reducing the data is called detection. Detection works by combining the results of several FFT bins into a single display point. In the process of detection some information is lost. For this reason several detectors are provided, each optimized for a different purpose.

The peak, normal, or sample detector uses its own algorithm to find a suitable spectral point between the nominal frequencies that define a pair of frequency points. It transfers the amplitude of this spectral point to a nearby display point. The analyzer moves the detected point between two frequency points to the leftmost point for each pair of frequency points. For more information on how each detector type functions, display the relevant online help topics.

Manual sweep

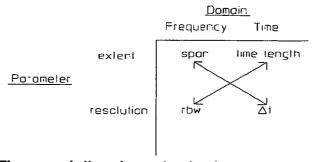
For swept spectrum measurements, sweep times can be very long for low resolution bandwidth to span ratios. You can use *manual sweep* to disable the analyzer's automatic sweep. Manual sweep lets you tune the analyzer to a discrete frequency. This lets you measure the amplitude of discrete frequencies without waiting for the analyzer to sweep through an entire span—a considerable advantage when using a narrow resolution bandwidth.

Manual sweep is also useful when making automated measurements. Using manual sweep dramatically reduces measurement time since it's much faster to transfer amplitude data for a single frequency over the HP-IB rather than sending data for the entire display.

Special Considerations in Vector Mode

Related parameters

The characteristic time/resolution bandwidth relationship for the HP 89400 series analyzers is a natural part of the FFT process and is common to all FFT analyzers, not just this one. However, the HP 89400 series analyzer is unique in allowing you to change span and resolution bandwidth independently.



The arrows indicate inversely related parameters.

Topics later in this chapter discuss these relationships in more detail but the most important implictions are:

- Resolution bandwidth changes always affect time length for a given window.
- Time length changes always affect resolution bandwidth.
- Span changes always affect Δt.
- At is related to sample rate and is not user-accessible—it is only affected by changing span.
- Span and resolution bandwidth may be adjusted independently.

Time data

The HP 89400 series analyzers provide the ability to view and analyze the time domain data. Time measurement data provides a time domain view of the input data before FFT processing. The following points will help you interpret time data:

- Time data is available in Vector and Demodulation modes but not in Scalar mode.
- Time data may look similar to an oscilloscope display in some cases but you will see distortion, particularly at high frequencies. The distortion occurs because the waveform is made up of the discrete samples from a time record which is optimized for FFT measurements. FFT measurements require a lower sample rate than would be required for an optimum time domain display.
- The analyzer must be in baseband mode to display data similar to an oscilloscope. In other words the measurement must start at 0 Hz and the center frequency must not be set explicitly. If you enter zoom mode either by setting the center frequency explicitly or by pressing the zoom/baseband key, a notice will flash on the screen which indicates that time data is in zoom mode. In zoom (band-selectable) measurements the time data is displayed relative to the center (local oscillator) frequency rather than relative to DC. Therefore, zoom time data has a different appearance because baseband data is real while zoom data is complex. Because the local oscillator is tuned to the center frequency for zoom measurements, the time data is represented as the difference frequency between the local oscillator and the input signal frequencies.
- Time and time exponential averaging are the only types of averaging which affect time data displays. Other average types only display the most recent time record.
- In baseband mode with maximum span, some signals, particularly square waves and transients, may appear to have excess distortion or ringing because of the abrupt frequency cut-off of the anti-alias filters. In this case the time data display can be improved by turning off the anti-alias filter under the [Input] menu. Make sure you turn the filter back on before viewing frequency domain data.

The time record

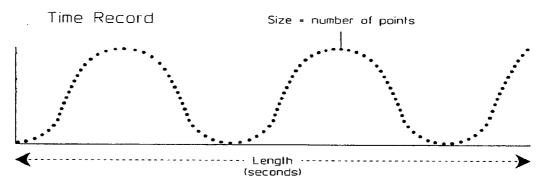
A time record is the amount of time-domain data the analyzer needs to perform one FFT operation. The time record and its FFT are the building blocks the analyzer needs for all subsequent measurements.

Why is a time record needed?

Essentially, the time record is a block of time-domain sample points. Since the actual Fourier Transform does not have explicit time or frequency references (it simply operates on a sequential collection of points), FFT analyzers must assign arbitrary start and finish times for data to be transformed. These blocks of input data are called time records.

For example, with the default display resolution of 401 frequency points, the HP 89400 Series Vector Signal Analyzer takes up to 1024 samples of time data to produce 512 points of frequency domain data. The analyzer usually displays the first 401 points of this data and discards the rest (this accommodates the anti-aliasing filters, but that's beyond the scope of our current discussion).

The time record can be described by both a *length* and a *size*. The time record length is the amount of time required to acquire a time record and is altered by changing resolution bandwidth, window, main length, or gate length. The time record size is the number of time points in the time record and is dictated by the time record length in combination with the sample rate (and sample rate, in turn, is directly related to span). More detail on these interactions can be found later in this chapter.



Time record size refers to the number of time points (samples) in a time record. Time record length refers to the amount of time needed to acquire a time record.

Time record, span and resolution bandwidth

The HP 89400 series analyzers eliminate a restriction inherent in previous FFT analyzers by allowing you to choose span and resolution bandwidth independent of one another. This implies a different method of handling the time record before the FFT.

The HP 89400 series analyzers take a number of samples (time points) directly related to span. These samples are acquired in a time length inversely related to the resolution bandwidth. The FFT converts this time record to the frequency domain and displays the result across the number of frequency points (display points) selected by the user.

Measurement speed and time record length

The length of a time record is inversely proportional to the resolution bandwidth. For smaller resolution bandwidths, an FFT analyzer needs a longer time record and therefore takes longer to make a measurement. For larger resolution bandwidths, an FFT analyzer needs a shorter time record and can therefore make a measurement much faster. The different time length required will become noticeable as you start making measurements. Refer to the earlier discussion: "Enhancing the Measurement Speed."

How do the parameters interact?

Window bandwidth

In most analyzers the final IF filter determines the resolution bandwidth. In the HP 89400 series analyzers the window type you select shapes the resolution bandwidth filter shape. And the window type, along with the time record length, determines the width of the resolution bandwidth filter. Therefore, for a given window type, a change in resolution bandwidth will directly affect the time record length. Conversely, any change to time record length will cause a change in resolution bandwidth.

Window Bandwidth

Flattop	3.8193596
Gaussian top	2.21234968
Hanning	1.5
Uniform	1.0

Important relationships

Window bandwidth represents the noise equivalent bandwidth of a window's filter shape and affects the resolution bandwidth and time record length:

$$T = \frac{WBW}{RBW}$$

Some useful equations help explain the relationship between time record length and time record size:

 $SR = 2.56 \times span$ (in baseband mode)

 $SR = 1.28 \times span$ (in zoom mode)

$$TP = SR \times T$$

$$\Delta T = \frac{1}{SR}$$

where:

RBW = resolution bandwidth (Hz)

WBW = window bandwidth

T = time record length (seconds)—refers to main length or gate length

TP = time record size (number of time points)

SR = sample rate (frequency)

Time record length limitations

The maximum time record size (the number of points of time data) is limited by the number of frequency points. As noted earlier, the sample rate (the rate at which data is digitized and entered into the time record) is determined by span. Therefore, the maximum time record length for a given span is determined by the number of frequency points. Because of this we can see that for a given window type, the minimum resolution bandwidth, while not directly affected by span and number of frequency points, may be limited by these parameters.

Time record size (also called block size or number of time points) is determined by window, span, and resolution bandwidth. But maximum and minimum time record sizes are determined by memory and FFT constraints:

Maximum time record length

The time record length is limited by the number of frequency points.

$$T_{\text{max}=} \frac{\text{(FP-1)}}{\text{span}}$$

Where:

FP = number of frequency points

Maximum time record size

The time record size is also limited by the number of frequency points.

$$TP_{max} = 2.56 \times (FP-1)$$
 (In baseband mode, real data)

$$TP_{max} = 1.28 \times (FP-1)$$
 (In zoom mode, complex data)

Therefore:

$$T_{max} = TP_{max} \times \Delta T$$

Minimum time record length

Minimum time record length is dependant on the resolution bandwidth to span ratio:

$$T_{min} = \frac{WBW}{RBW_{max}}$$

$$RBW_{max} = .3 \times span$$

Time record length and memory

To increase the time record length you can increase the number of frequency points until you reach the maximum number of frequency points allocated in memory (up to a maximum of 3201). To increase time record length you may have to reallocate memory space under the [System Utility] key.

Time record processing

The relationship between a time record and the frequency data is relatively straight forward if the minimum resolution bandwidth (and therefore the maximum time record length) is used. In this case the time record size is equal to the time record size required by the FFT (which is dictated by the number of frequency points and must be a power of 2"). Therefore, the FFT converts the samples in the time record directly to display points.

If a higher resolution bandwidth is selected, the time length necessary to acquire the time samples is shorter and fewer samples are required. However, the FFT must still operate on the same time record length for display purposes, so the extra time record length is set to zero (zero padded) before the FFT process. This enables the FFT to properly convert the time record to the required number of display points without adversely affecting the frequency data.

The time record calculations

The length of the time record determines how long a given measurement will take and the maximum frequency resolution you can measure. As described above the FFT time record size may differ from the size dictated by the resolution bandwidth. The FFT record size must be a power of 2 equal to or greater than the number of frequency points.

$$TP = INTEGER\left(\frac{T}{\Delta T}\right)$$

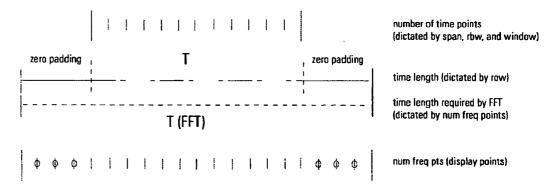
 $TP(FFT) = 2^n \ge FP$ for zoom mode

TP (FFT) = $2^n \ge (FP \times 2)$ for baseband mode

The time record and zero padding

l	I	ł	1	l	ı	I	I	ı		1	I	1	1		J	I	i	1		number of time points (dictated by span, rbw, and window)			
	_	_		<u> </u>	_	_			T	-	_								_	time length (dictated by row)			
-		_	_					- T (FFT	- [}		-							_	time length required by FFT (dictated by num freq points)			
j	į	I	ŀ	1	ı	l	ł	İ	ı	l	١	ı	1	ı	ı	ŀ	ı	i		num freq pts (display points)			

At the minimum resolution bandwidth in zoom mode, the time length necessary to collect the time samples is equal to the time record length required by the FFT.



At any other resolution bandwidth, the number of frequency points remains the same, but the time required to collect the time samples is shorter than the time record required by the FFT. Therefore, the time record is extended by the addition of zeros.

9

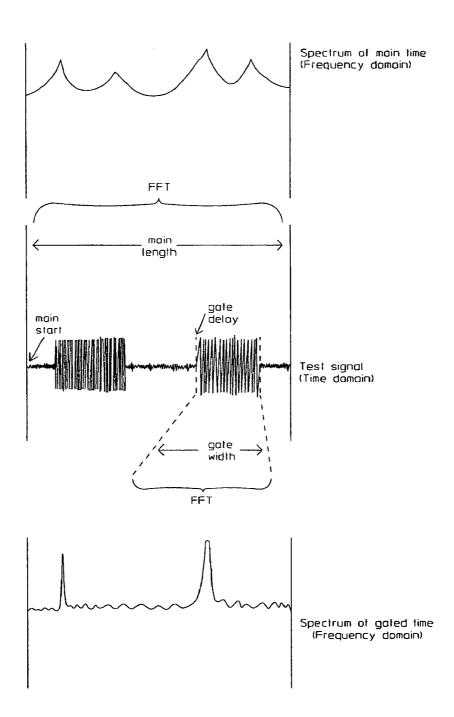
Gating Concepts

What is Time Gating?

Time gating is only available in Vector Mode. Gating allows the instrument to isolate a portion of a time record for further viewing and analysis. Time gating is often used to analyze non-stationary signals or portions of stationary signals such as burst signals from devices such as videotape recorders, computer disk drives, TDMA communication bursts, or ultrasonic tranducers.

Time gating lets you see a large time domain signal, only part of which you want to analyze. From the larger displayed signal, you can easily isolate a portion for further analysis.

For details on the use of the various keys related to time gating, display Online Help for the specific keys.



Time gating isolates a portion of a time domain signal. In this example the gated portion contains two of the four spectral components included within the total (main) test signal. Note that gating has minimized leakage, resulting in more distinct signals in the frequency domain.

How Does it Work?

The analyzer collects a record of data the duration of which is defined by main length, and the position of which is defined by trigger delay. After the main time data has been acquired, the analyzer isolates a portion of the main data as the gate record. The duration and position (relative to the start of the main record) of the gate are determined by [gate length] and [gate dly] respectively.

The gate record is then processed as the analyzer's time record. That is, spectrum, frequency response, coherence, and correlation displays are based on the gate record.

To control time gating, you define the following parameters:

- Trigger setup (if any)
- [main length]
- [ch1 gate dly]
- [gate length]

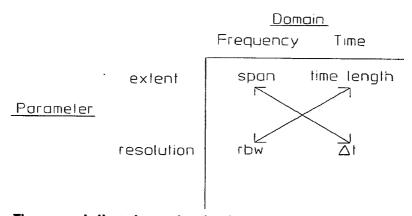
After you have acquired main time data, you may reposition or resize the gate without obtaining new main time data. The analyzer will automatically recompute and redisplay the data contained in the modified gate record.

Important Concepts

- Trigger delay and gate delays are independent for each channel—you can select different delay times for both trigger and gate regions for each channel—though lengths must be the same for both channels.
- You can smoothly scroll with the knob to change data position and length.
- You can use averaging on gated measurements. Rms and peak averaging are applied to the spectrum display of the gate, while time averaging is applied to the main time record.
- You can step the gate delay through the main time data in predetermined increments by setting [gate dly step] to the desired increment, then selecting [gate dly] and using the up and down arrow keys.
- In some applications, the overhead required to acquire a new main record may be undesirable. In this case, you may expand the gate region to cover the entire display with the [gate->main] key. You may then continue to analyze the previous gate region without collecting a large main record.
- The maximum length of the main record is determined by the span and the number of frequency points. When working in the time domain, you may not want to be limited by the selected span. In this case, you would like the span to be adjusted to meet your main record length needs. To do this, you can set [time resltn] to [auto] then you may adjust main length while span is automatically adjusted to keep the number of points in the main record within the limits of the maximum number of frequency points in memory.
- You can increase the main record length by increasing the number of frequency points. You will then be able to select a narrower resolution bandwidth, longer time length, or wider frequency span.
- Resolution bandwidth cannot be independently adjusted in time gating because the resolution bandwidth is determined by the length of the time record. Since you set the length of the time record in gated measurements, you cannot set resolution bandwidth.
- If you are using gating to estimate the frequency or phase of a signal at a specific point in time, you may want to consider using demodulation instead. With demodulation you can measure the instantaneous frequency or phase at a point in time, rather than the estimate over the gate interval.

Parameter Interactions

There are some inherent parameter interactions:



The arrows indicate inversely related parameters.

- When the gate is off, rbw and time length refer to main length. When the gate is on, these parameters refer to gate length—when you change gate length you change the resolution bandwidth. This also implies that you cannot explicitly set resolution bandwidth without changing the gate length.
- When the gate or main length are explicitly set, rbw coupling is set to fixed and rbw mode is set to arbitrary. This allows time length to be unrestricted and can therefore be set to whatever you enter.
- When rms or peak averaging is on, changing trigger delay, gate delay, main length, or gate length aborts any averaging in progress and restarts a new one. Changing the gate when time average is on does not abort the average.

10

Video Demodulation Concepts

Overview

This chapter presents an overview of video demodulation and includes concepts to help you understand how the analyzer demodulates video signals. For examples on setting up a video demodulation measurement, see the chapter titled "Using Video Demodulation." For key-specific information, refer to online Help, which is accessed by pressing the [Help] key on the analyzer.

Video Modulation Analysis provides the following capabilities:

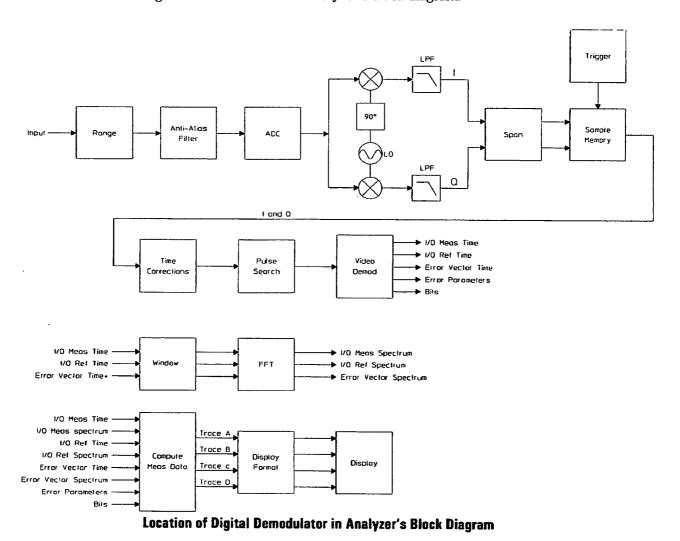
- 8 and 16 VSB (Vestigual Side Band) Demodulation
- 16, 32, and 64 DVB QAM (Digital Video Broadcast QAM) Demodulation
- 16, 32, 64 and 256 QAM Demodulation
- Mirrored (flipped) frequency spectrums so you can remove the effects of hi-side mixing.
- A maximum frequency span of 7 MHz or 8 MHz for RF measurements.

Video demodulation does not require external filters, coherent carriers, or symbol clock timing signals. Instead, the analyzer locks to the carrier and to the symbol-clock phase. The analyzer uses the demodulated signal to generate an ideal reference signal. The ideal reference signal is compared to the demodulated signal to provide a quantitative measure of system errors. The analyzer has built-in filters that may be applied to the measured signal as well as to the reference signal. This allows you maximum flexibility in comparing your signal to an ideal signal. Additionally, this allows complete flexibility to probe any analog point in your communication system. An optional second baseband channel allows IQ baseband measurement capability.

Measurement Flow

General block diagram

The Video Demodulation instrument mode uses the analyzers digital demodulator to demodulate video signals. The following block diagram shows the location of the digital demodulator in the analyzer's block diagram.

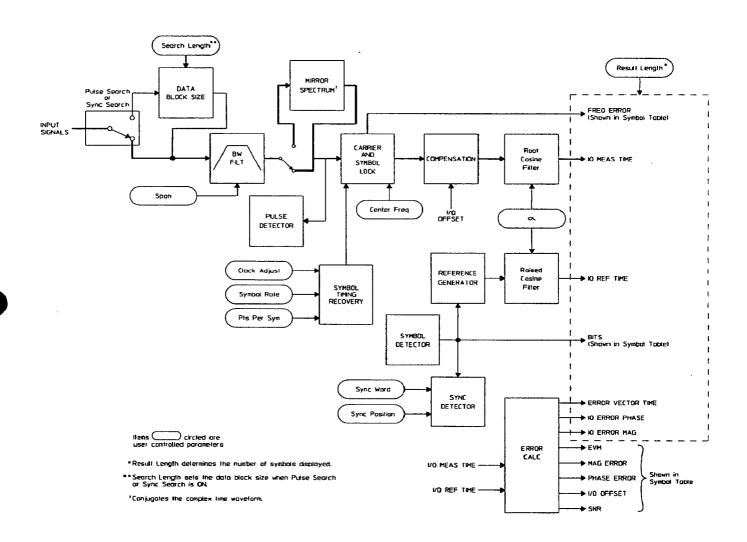


Digital demodulator block diagram: QAM and DVB QAM

Selecting Video Demodulation reconfigures the analyzer's digital demodulator to demodulate video signals.

The following illustration shows the digital-demodulator block diagram when QAM or DVB QAM is selected. The block diagram is identical for both demodulation formats, with the following exceptions:

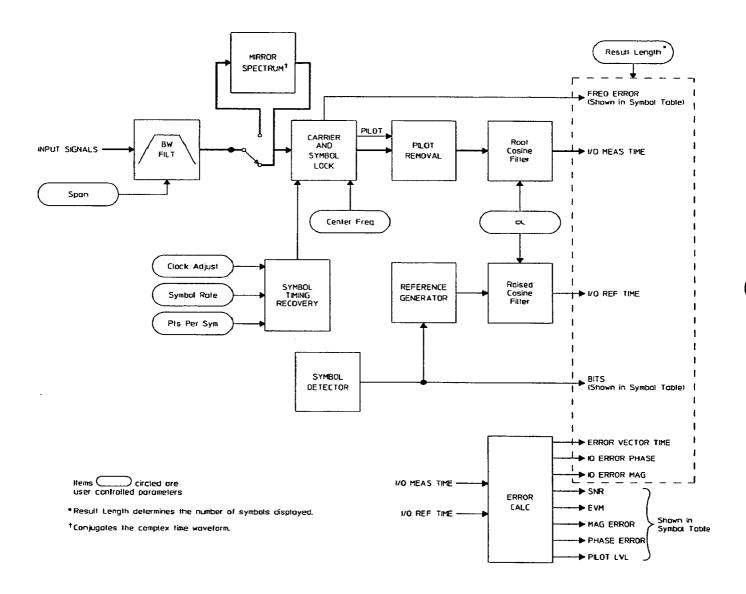
- Bits are decoded differently.
- I/Q origin offset is removed from QAM measurements. I/Q origin offset is not removed from DVB QAM measurements (but it is reported in the symbol table).



Digital Demodulator Block Diagram: QAM and DVB QAM

Digital demodulator block diagram: VSB

The following shows the digital-demodulator block diagram when 8 VSB or 16 VSB is selected.

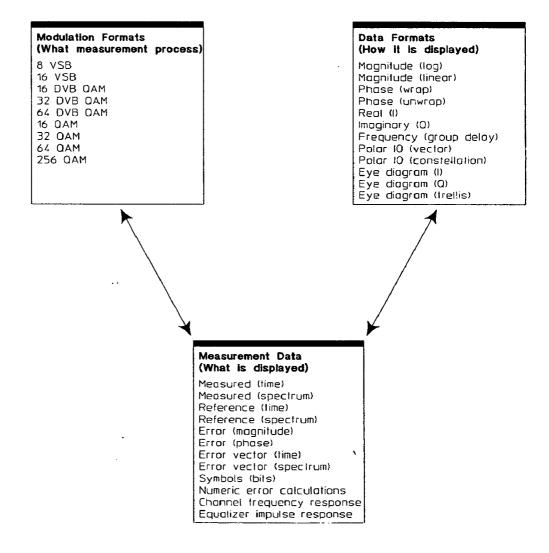


Digital Demodulator Block Diagram: VSB

Measurement management

Measurement and display choices

The flexibility of this analyzer provides numerous possible ways of viewing digitally demodulated signals. You may demodulate signals of various types then view aspects of those signals in several ways. Modulation format, measurement data, and data format may be combined in different ways for specific measurement needs.



Carrier locking (all except VSB)

For QAM signals, the analyzer's center frequency must be close to the transmitted carrier frequency to achieve carrier lock. The required proximity of the center frequency to the carrier frequency varies depending on the signal type, symbol rate, and system noise. If symbol locking appears poor, you may achieve better carrier locking by observing the "Freq Err" value in the symbol table of any successfully locked measurement and adding that amount to the center frequency.

To obtain reliable carrier locking, the difference between the analyzer's center frequency and carrier frequency should be within 3% of the symbol rate for 16 and 32 QAM. For 64 and 256 QAM, the difference should be within 1% and 0.2%:

```
16 or 32 QAM/DVB QAM: (center frequency) — (carrier frequency) ≤ ± .03 (symbol rate)
64 QAM/DVB QAM: (center frequency) — (carrier frequency) ≤ ± .01 (symbol rate)
256 QAM/DVB QAM: (center frequency) — (carrier frequency) ≤ ± .002 (symbol rate)
```

For QAM signals, the result length also affects the analyzer's ability to achieve reliable carrier lock, as shown in the following table. Result lengths less than those shown may result in unreliable carrier lock. Optimal carrier locking occurs when the result length is 1000 or greater.

If the modulation type is:	The minimum result length for reliable carrier lock is:					
16 QAM or 16 DVB QAM	50 symbols					
32 QAM or 32 DVB QAM	75 symbols					
64 QAM or 64 DVB QAM	150 symbols					
256 QAM	400 symbols					

The following may also affect carrier locking:

- A frequency span that is too narrow.
- An incorrect range setting.
- Using the wrong measured or reference filter.

Carrier locking and pilot search: VSB

The same parameters that affect carrier locking for QAM signals also affect carrier locking for VSB signals. For VSB signals, the analyzer must also find the pilot signal to achieve carrier lock.

When you start a VSB measurement, the analyzer displays SEARCHING FOR PILOT. This message appears for a fixed amount of time while the analyzer searches for the pilot signal. The measurement begins when the pilot search ends (when the SEARCHING FOR PILOT message disappears).

If your VSB signal uses a high-side pilot, you must configure the analyzer to demodulate a high-side pilot by selecting the Video Demodulation instrument mode and pressing [Instrument Mode], [demodulation setup], [demod format], [freq spectrum mirror]. If you don't do this, the analyzer cannot find the pilot signal and cannot lock to your signal.

If the analyzer cannot lock to your signal, it displays CARRIER LOCK?. There are several conditions that may cause loss of carrier lock, one of which is an unsuccessful pilot search. If carrier lock is not obtained after several measurements, the analyzer assumes the pilot search failed and repeats the pilot search.

CARRIER LOCK? may appear even when the data appears to be locked. If this occurs, the results may be inaccurate. Normally, this condition clears in a few measurements as the instrument obtains better estimates of the carrier frequency.

The following paragraphs describe other conditions that may cause loss of carrier lock. The analyzer always assumes pilot search failed if there are carrier lock problems, even if the cause is one of the conditions below.

Like QAM signals, the analyzer's center frequency must be close to the transmitted carrier frequency to achieve carrier lock for VSB signals. The following formulas show you how to calculate the ideal center frequency. Use the formula for low-side pilot if your pilot is on the left (low) side of your spectrum; use high-side pilot if your pilot is on the right (high) side of your spectrum.

 $Center Frequency (LOW SIDE PILOT) = \frac{Symbol Rate}{4} + (Pilot Frequency)$

Center Frequency (HIGH SIDE PILOT) = (Pilot Frequency) $-\frac{Symbol Rate}{4}$

Hint

The "Using Video Demodulation" chapter contains a task that shows you how to use the analyzer's frequency counter to measure your pilot frequency.

The result length also affects the analyzer's carrier locking. For VSB measurements, the result length should be at least 800 symbols. Smaller result lengths may cause unreliable carrier locking.

The following may also cause loss of carrier lock:

- A frequency span that is too narrow.
- An incorrect range setting.
- Using [freq spectrum normal] when you should be using [freq spectrum mirror].
- A pilot that is not in phase with the transmitted data. You may be able to compensate for pilot-phase problems by using [clock adjust] to change when the analyzer samples the I/Q trajectory (press [Instrument Mode], [demodulation setup], [more], [clock adjust]).

Input Range

The input range must be set correctly to obtain accurate measurements. Input ranges that are too low overload the analyzer's ADC. Input ranges that are too high increase noise, which increases errors reported in error parameters, such as EVM.

To select the optimum input range when using the RF section (2-2650 MHz) receiver, press [Range], [chl range] and decrease the range (using the down-arrow key) until OVI appears in the active trace. Then increase the range one step at a time (by pressing the up-arrow key) until OVI disappears.

To select the optimum input range when using the RF section (0-10 MHz) receiver or the IF section (0-10 MHz) receiver, press [Range], [ch1 range] and decrease the range (using the down-arrow key) until the Channel 1 Over and Half LEDs turn on. Then increase the range one step at a time (by pressing the up-arrow key) until the Over LED turns off.

I-Q measured signal

The IQ measured signal is the result of resampling the data to an integer number of points per symbol and applying system gain normalization, carrier locking, and filtering to the incoming signal. The filtering is root-raised cosine with a user-adjustable alpha. For QAM measurements, the analyzer also applies I/Q origin offset compensation (similar to pilot removal for 8 VSB and 16 VSB). I/Q origin offset compensation is not applied to DVB QAM measurements.

I-Q reference signal

A powerful analysis technique involves comparing a demodulated signal with an ideal signal generated from detected bits. The analyzer detects bits from the measured IQ signal and reconstructs a sequence of ideal I and Q states. These are then treated as ideal impulses and are baseband filtered using a raised cosine filter selected by the user. The resultant IQ reference can be overlaid or compared side-by-side with the IQ measured signal.

Parameter interactions

Changing one parameter may necessitate changes in other parameters to achieve the desired measurement. The following topics may help you optimize your measurements and explain the reasons for changes made automatically by the analyzer.

Data size considerations

Maximum data size for measured and reference IQ data is generally determined by max time pts⁺⁺ which is user selectable, 64-4096. A given measurement will generally use all available memory as defined by max time pts:

max time pts≥ result length × points/symbol

Resolution bandwidth

Resolution bandwidth in video demodulation is determined automatically by the analyzer, and cannot be set independently. Resolution bandwidth is determined by the time record length in the same manner as in Vector mode (see Fundamental Measurement Interactions):

RBW = WBW/T

where RBW = resolution bandwidth
T = time record length
WBW = window bandwidth

However, in Video Demodulation the time record length is determined as follows:

 $T \approx Result \ Length \ (in \ symbols)/Symbol \ Rate$

⁺⁺ See Imax time pts] under [System Utility], [memory usage], [configure meas memory].

Span considerations

When selecting a frequency span, select the narrowest span that includes all of your signal components (select a span that is larger than the bandwidth of your signal). If you select a span that is too narrow, your measurement may have excessive errors or the analyzer may lose carrier lock. If you select a span that is too wide, your measurement may be affected by excessive noise and slower speed. You may want to select the Vector instrument mode and set the span while viewing the spectrum of your signal.

The analyzer displays a warning message if the frequency span is less than the symbol rate for QAM and DVB QAM formats, and less than half the symbol rate for VSB formats. If you see this warning message, increase the frequency span until it includes all components of your signal.

When using video demodulation, the symbol rate determines the maximum frequency span that you can select, as follows:

Maximum Span (VSB) =
$$20 \frac{(SymbolRate)}{2.56}$$

Maximum Span (All Other Formats) =
$$20 \frac{(SymbolRate)}{1.28}$$

These formulas can be rewritten to obtain the maximum-span-to-symbol-rate ratio. These ratios are fixed and cannot be changed.

$$VSB: \quad \frac{Maximum\,Span}{Symbol\,Rate} = \frac{20}{2.56} \quad OR \quad \frac{Maximum\,Span}{Symbol\,Rate} = 7.8125$$

All Other Formats:
$$\frac{Maximum \, Span}{Symbol \, Rate} = \frac{20}{1.28}$$
 OR $\frac{Maximum \, Span}{Symbol \, Rate} = 15.625$

For VSB measurements, you must use arbitrary spans; you cannot use cardinal spans (cardinal spans are spans that are powers of two, such as 2.5 MHz, 5 MHz, and 10 MHz). The analyzer displays an error message if you select a cardinal span when using the VSB demodulation format.

You may notice that the frequency span for digitally demodulated spectrums (the IQ measured spectrum, IQ reference spectrum, and error vector spectrum) is different than that set with the [span] softkey. The reason is that the digital demodulation process derives its own frequency span and sample rate, as follows:

Demod Sample Rate = $(symbol\ rate) \times (points-per-symbol)$ Demod Span = (Demod Sample Rate)/1.28 When viewing digitally demodulated spectrums, aliasing may occur if the frequency span is too large. The aliasing does not affect the accuracy of the demodulation, only the validity of the spectral displays. The analyzer displays DATA? if it suspects aliasing in digitally demodulated spectrums. To prevent aliasing, be sure that:

$$Frequency \ Span \leq \frac{Symbol \ Rate \times (points-per-symbol)}{1.28}$$

where: Frequency span is set by pressing [Frequency] [span].

symbol rate is set by pressing [Instrument Mode], [demodulation setup], [symbol rate].

points-per-symbol is set by pressing [Time], [points/symbol].

Display limitations

Points per symbol affects all displayed results by controlling result resolution but is not coupled to span. More points per symbol improves the resolution of the vector diagram, but there is still only one point at the symbol clock.

 $(number\ of\ time\ points) = (result\ length) \times (points-per-symbol)$

Result length takes precedence over points per symbol—if you try to set points per symbol such that the number of time points would exceed the memory size⁺⁺, an error indicates that the requested number of points per symbol cannot be set. In this case, you may choose to reduce the result length to allow an increased number of points per symbol. Conversely, if you increase result length such that the number of time points exceeds the memory limit, points per symbol automatically decreases to allow the result length to increase.

⁺⁺ See [max time pts] under [System Utility], [memory usage], [configure meas memory].

Feature Availability in Video Demodulation

Most features that are available with other instrument modes are also available with video demodulation with the following exceptions:

- Time gating is not available
- Averaging is not available for any trace data in video demodulation but may be applied to numeric error data in the error table. Three types of averaging are available:
- ms (video)—computes an rms average of each rms error update in the table
- rms exponential—is like rms (video) except that averaging continues past the average count with an exponential weighting
- continuous peak hold—keeps track of the peak rms error of each update in the table

Special considerations for sync search

Synchronization words (or patterns) are often used to resolve carrier phase ambiguity on non-differential modulation formats. It is important to realize that synchronization words are optional and are not necessary in order to achieve carrier locking.

Note

You cannot use sync search for VSB measurements. The [sync search on/off] softkey (under the [Time] hardkey) is ghosted (inactive) if VSB is selected.

Sync search lets you use a synchronization pattern to isolate a portion of your signal for display and analysis. The analyzer searches through demodulated data to find your sync pattern, and then uses the [result length] to determine how much data to display, and the [offset] to display data relative to the sync pattern.

Note

The sync pattern must be a multiple of the number of bits-per-symbol. For example, if the number of bits-per-symbol is 4 (as with 16 QAM), the number of bits in the sync pattern must be a multiple of four. Sync search lets you specify any number of bits for the sync pattern, however, bits that aren't a multiple of the bits-per-symbol are truncated. In this example, if you entered 6 bits for the sync pattern, sync search would only use the first four bits.

Triggering determines when the analyzer starts demodulating data and search length determines when the analyzer stops demodulating data. Sync search locates only the first match and ignores any subsequent matches within the search length. The sync pattern and the offset must fit within the search length.

You may use sync search with or without pulse search, although many measurements require both features.

See online help for the following softkeys for additional information (all softkeys are under the [Time] hardkey):

- [sync search]
- [search length]
- [sync setup], [pattern]
- [sync setup], [offset]

Special considerations for pulsed signals

You can use pulse search to demodulate pulsed (burst) transmissions. Pulsed transmissions are generated by on/off carriers such as those used in mobile units.

-	
ш	INTO
	ULU

You cannot use pulse search for VSB measurements. The [pulse search on/off] softkey (under the [Time] hardkey) is ghosted (inactive) if VSB is selected.

Speed and resolution considerations

Maximizing speed - measurement and display

- Use fewer points per symbol
- Use fewer symbols
- Decrease span

Maximizing resolution

- Use more points per symbol
- Increase max time points⁺⁺

^{+ +} This parameter is under [System Utility] [memory usage] [config meas memory]. See the online help on this key for more information on this topic

Filtering

The IQ measured signal is always passed through a root-raised cosine filter with the selected alpha.

Mirrored Spectrums

The HP 89441V provides a feature that lets you configure the analyzer's demodulator to conjugate the complex time-domain waveform. This has the effect of flipping the spectrum around the analyzer's center frequency. To enable this feature, select the Video Demodulation instrument mode, then press [Instrument Mode], [demodulation setup], [demod format], [freq spectrum mirror].

This feature is often used with VSB measurements that use a high-side pilot. For VSB signals, the pilot must be on the low-side of the spectrum to achieve carrier lock. For details, see "Carrier locking and pilot search: VSB" earlier in this chapter.

This feature may also be used with QAM measurements to obtain the correct data patterns.

RF receiver and 8 MHz spans

HP 89441V lets you extend the maximum frequency span of the RF receiver from 7 MHz to 8 MHz. Press [Instrument Mode] [receiver] [RF (2-1800 MHz)] to display the normal (7 MHz) and wide (8 MHz) softkey menu. Press [RF (2-1800 MHz) normal] to select the RF section with a maximum frequency span of 7 MHz; press [RF (2-1800 MHz) wide] to extend the maximum frequency span to 8 MHz.

Remember that, in two-channel analyzers, channel 1 determines the frequency span of channel 2. Therefore, selecting wide (8 MHz) also extends the frequency span of channel 2 to 8 MHz (channel 2 is always baseband, so the frequency span is 0 to 8 MHz).

Normal (7 MHz) provides the best specifications: for example, improved noise performance.

Index

fast averaging HT frequency response traces HT 2-channels instantaneous-spectrum traces HT video demod 1-19 long averages and calibration HT overlap processing HT A,B,C,D LEDs HT pausing HT accessories vi peak-hold averaging HT adaptive equalization repeat averaging HT See equalization filter rms averaging HT aliasing rms exponential averaging HT video demod 10-11 selecting an averaging function HT alpha entry, using HT selecting the number of averages HT alpha, setting HT single-stepping HT amplitude droop (in symbol table) HT spectrum traces HT analyzers time averaging HT types of 7-4 time exponential-averaging HT applications softkey HT video demodulation 10-14 arm AYH (video modulation analysis) HT See external arm AYJ (adaptive equalization) 2-1 arrow keys HT assistance (by phone) 2-i band power measurements 3-2, HT atv 16 HT band-selectable measurements 8-3 atv 8 HT See Also zoom measurements AUI connector HT bandwidth auto cal on/off softkey HT See information bandwidth auto sweep, selecting HT See noise equivalent bandwidth auto zero calibration See resolution bandwidth See Also calibration See window bandwidth autorange softkeys HT bandwidth coupling 8-4 autorange, using HT baseband measurements 8-3, HT autostate file HT baseband signals creating HT video demod 1-19 recalling HT BASIC HT average power HT about HP instrument BASIC HT averaging HT available utilities HT about averaging HT creating a program with keystrokes HT auto correlation traces HT debugging a program HT available averaging functions HT deleting a function HT cross correlation traces HT deleting a program HT cross spectrum traces HT deleting a subprogram HT exponential averaging HT

deleting multiple functions HT deleting multiple subprograms HT displaying a program HT editing a program HT executing a single program line HT indenting nested programs HT memory allocations HT printing a program HT program error messages HT program error messages HT re-saving programs HT recalling programs HT realling programs HT renumbering a program HT running a program HT saving programs HT saving programs HT securing a program HT stack space, auto allocation HT stack space, nanual allocation HT stopping a program HT beeper on/off softkey HT bins See frequency points bins, defined HT block diagrams HT ch1 + j*ch2 receiver HT connectors, front panel HT reft overview HT general 7-11 HP IBASIC memory HT instantaneous spectrums HT main memory HT measurement data HT measurement memory HT scalar 6-3, HT source block diagram HT time capture HT traces HT vector 6-5, HT video demodulation 10-3	about calibration HT adjusting calibration data HT auto zero calibration HT auto zero calibration, single HT performing a single calibration HT saving calibration data HT time-domain calibration HT capture See time capture carrier frequency error (in symbol table) HT carrier locking video demod 10-8 center frequency HT setting center frequency HT setting with the marker HT signal tracking HT ch1 + j*ch2 receiver HT changing numeric parameters HT channel optional IF input v channel 1 See input channels channel 1 and 2 connectors HT coherence HT color index softkey HT color, adjusting HT connectors, rear panel connectors HT connectors, rear panel connectors HT constellation diagram, example 1-14 constellation diagram, using HT continuous sweep, selecting HT coordinates, trace See Also traces copying files between 3.5 inch diskettes HT correlation HT auto correlation HT
time capture HT	
	diskettes HT
block size	
See time record size	cross correlation softkey HT cross-correlation, math function HT
	coupling
C	bandwidth 8-4
C/N (carrier-to-noise) HT	cross spectrum measurements HT
C/No (carrier-to-noise-density) HT CAL?, definition of HT calibration HT	CW (fixed sine) softkey HT

standard setups, example HT n state definitions, defining HT data comment header HT state definitions, displaying HT data format hardkey HT symbol clock, adjusting HT data registers HT symbol locking 10-8 about data registers HT symbol rate, setting HT displaying data-register contents HT sync patterns, using pre-defined removing HT patterns HT DATA?, definition of HT sync search 1-16 date, changing HT sync words, using HT dc measurements 8-9 trellis diagram HT dc offset softkey (source) HT troubleshooting HT dc offset, compensation HT VSB 8/16 HT dc response 8-9 detection 8-12, HT decibels HT about detection HT demodulation, video HT normal detector HT about video demodulation HT positive peak detector HT block diagram 10-3 sample detector HT capabilities 10-2 diagnostics softkey HT carrier frequency error (in symbol disk drive table) HT flexible disks for vii carrier lock and result length HT disk drives HT carrier locking 10-8 about disk drives HT center frequency, setting 1-4 comparison HT constellation diagram HT copying files HT DVB QAM 16/32/64 HT deleting files HT DVB QAM state definitions HT displaying contents of HT DVB QAM, example 1-12 external disk drive HT error-vector magnitude (in symbol formatting HT table) HT HP-IB address: external disk drive HT eye diagram HT internal disk drive HT filtering HT non-volatile RAM disk HT formatting and displaying 10-7 formatting displays 1-14 packing a disk HT renaming files HT gating 9-5 selecting a default disk HT hexadecimal, in symbol table HT using disk specifiers HT I/Q measured, displaying HT volatile RAM disk HT I/Q origin offset (in symbol table) HT volatile RAM disk, removing HT ideal states HT display HT magnitude error HT adjusting the color HT maximum number of time points, allocating portion for programs HT setting HT blanking HT mirrored spectrums 10-17, HT changing colors HT normalization HT indicators HT overview 6-6 See Also traces phase error (in symbol table) HT display group hardkeys HT points-per-symbol, setting HT pulse modulation HT display points, defined HT QAM 16/32/64/256 HT display resolution 8-11 - 8-12 display, digital 8-9 range, setting 10-10 documentation HT setup 1-2 SNR HT DVB 16 HT

DVD 99 UT	for a second of the second of
DVB 32 HT	frequency HT
DVB 64 HT DVB QAM HT	about frequency parameters HT
	center frequency HT
block diagram 10-4	frequency counter HT
dynamic signal analyzers 7-6	frequency span HT
E	manual frequency, setting HT signal tracking HT
entry group hardkeys HT	span, extending to 8 MHz HT
equalization filter 2-1, HT	The state of the s
about the equalization filter HT	start frequency HT step size HT
frequency response HT	step size HT stop frequency HT
impulse response HT	using markers to set step size HT
equivalent noise bandwidth HT	frequency domain overview 7-2
error & status messages HT	frequency error (in symbol table) HT
error-vector magnitude (in symbol	frequency points 8-5, HT
table) HT	about frequency points HT
error-vector magnitude, displaying EVM	and display 8-12
trace HT	memory allocation HT
EXT ARM connector HT	setting the number of HT
EXT REF IN connector HT	frequency resolution 8-11
EXT REF OUT connector HT	frequency response measurements HT
EXT TRIGGER connector HT	frequency span
external arm HT	and display 8-5
about external arm HT	and information bandwidth 8-3
trigger, using with external arm HT	and resolution bandwidth 8-14, 8-19
turning on/off HT	video demodulation 10-12
external calibration softkey HT EXTERNAL MONITOR connector HT	front panel tour HT
external receiver	FTP (File Transfer Protocol) HT
See Also receiver	FTP, and LAN 4-10
external softkey HT	full span softkey HT
external trigger, overview HT	G
eye diagram, example 1-14	gate length softkey HT
eye diagram, using HT	gate time-record HT
	displaying HT
F	gate delay HT
fault log, displaying HT	gate time HT
FFT 7-6	gate-delay step size HT
properties of 7-7	setting the length of HT
See Also spectrum analyzers	turning on/off HT
FFT, overview & terminology HT	GATHERING DATA, definition of HT
FILLING TIME RECORD, definition of HT	gating
filters	description 9-2
IF 8-18	German softkey HT
video 8-3	ghosted softkeys HT
firmware version, displaying HT	grids HT
flexible disks vii	1 grid HT
fonts HT	2 grids HT
fourier transform 7-7	4 grids HT
French softkey HT	hiding HT
freq counter softkey HT	group delay softkey HT

H	input hardkey HT
half LED HT	input section (chl + j*ch2) softkey HT
description of HT	installing options HT
using to set the range HT	instantaneous spectrum, displaying HT
hardkeys, defined HT	instrument mode hardkey HT
help (by phone) 2-i	IQ measured signal 10-10
Help hardkey HT	IQ reference signal 10-10
hold scale softkey HT	Italian softkey HT
HP-GL (Hewlett-Packard graphics	K .
language) HT	keyboard HT
HP-IB HT	about the keyboard HT
about the HP-IB HT	keyboard connector HT
addressable only HT	keyboard type HT
HP-IB address: analyzer HT	knob HT
HP-IB address: external devices HT	about the knob HT
HP-IB address: external disk drive HT	changing the operation of HT
HP-IB address: external receiver HT	oranging wie operation of 111
HP-IB address: plotter HT	L
HP-IB address: printer HT	LAN
HP-IB controllers HT	about the advanced LAN (option UG7)
keys that have HP-IB commands HT	НТ
LAN use 4-6	about the lan HT
system controller HT	activating 4-5
I	addressing 4-4
I-BASIC, instrument BASIC	and FTP 4-10
See BASIC	connectors, descriptions HT
ideal state softkey HT	controlling the analyzer via the lan HT
IF bandwidth, external receiver HT	ethernet address, displaying HT
IF center frequency, external receiver	FTP (File Transfer Protocol), using HT
HT	gateway address, setting HT
IF section (0-10 mhz) softkey HT	HP-IB with 4-6
IF trigger	interface, connecting 4-1
See trigger	IP address, setting HT
indent softkey HT	port, configuring HT
indicators, display HT	ports, activating HT ports, selecting HT
INF, meaning of HT	subnet mask, setting HT
information bandwidth 8-3, 8-10	Telnet, about HT
input channels HT	X-Windows with 4-7
about input channels HT	X11 display, configuring HT
channel 2 with RF section HT	X11 display, controlling the analyzer
clearing input overloads HT	with HT
compensating for dc offset HT	X11 display, setting the update rate HT
compensating for gain & delay HT	X11 IP address, setting HT
connections HT	LAN (local area network) HT
coupling: ac or de HT	leakage 8-6
dBm calculations HT	learning products (manuals) HT
disabling HT	LEDs: front panel HT
disabling the anti-alias filter HT	level softkey HT
input impedance HT	linear averaging
input-state table HT	See time averaging

lines See frequency points	trace annotation HT turning on markers HT
lines, defined HT	using for numeric entry HT
listen LED HT	using to set frequency step size HT
LO feedthrough	
See zero response	using to update frequency values HT
loading files	x-axis, scaling with markers HT math HT
See recalling	about math HT
Local Area Network	cross-correlation math function HT
See LAN	
local oscillator 7-12	defining a math constant HT
TOCKI OSCINGOT 1-12	displaying math functions HT
M	displaying results HT
magnitude log(dB)/linear softkey HT	math constants, overview HT
main length softkey HT	math function operands HT math functions HT
main time vs. gate time HT	
main time-record	memory for math-buffers HT recalling math functions HT
displaying HT	saving math functions HT
length equal to gate length HT	MAU connector HT
main length HT	measured signal
main time HT	video demod 10-10
setting the length of HT	measurement calculations, disabling HT
See Also time record	measurement data, about HT
manual sweep 8-13	MEASUREMENT Group hardkeys HT
manual sweep, selecting HT	measurement points, defined HT
manuals, for this product HT	measurement resolution 8-11
Marker Cnt, meaning of HT	measurement speed, enhancing HT
marker group hardkeys HT	measurement state HT
Marker Man, meaning of HT	recalling HT
marker readout HT	saving HT
Marker/Entry LED HT	measurement time 8-2, 8-10, 8-17
markers HT	measurements HT
about markers HT	continuing HT
band power HT	displaying the measurement-state
band power, rms square-root of HT	table HT
carrier-to-noise HT	pausing HT
carrier-to-noise-density HT	single-stepping HT
frequency counter HT	starting HT
marker into center frequency HT	memory HT
marker into reference level HT	about memory H-1
marker into span HT	capture RAM HT
marker into start frequency HT	erasing HT
marker into stop frequency HT	for applications HT
multiple traces HT	for frequency points HT
offset marker, zeroing HT	for temporary math buffers HT
offset markers, repositioning HT	memory limitations 8-19
offset markers, using HT	menu HT
peak tracking HT	mirror freq on/off softkey HT
polar display markers HT	mirrored spectrums 10-17
repositioning markers HT search functions HT	Mkr Val HT
Search Innerious 111	

N	date and time HT
NAN, meaning of HT	default pen assignments HT
narrowband measurements 7-8	output to file HT
Network, Local Area	plot speed HT
See LAN	selecting an output device HT
NO DATA, definition of HT	selecting display items HT
noise equivalent bandwidth 8-18	setting P1/P2 HT
non-volatile RAM disk	setting the HP-IB address HT
See disk drives	specifying line types HT
normalization HT	starting HT
numeric entry softkeys HT	points
•	See frequency points
0	points, defined HT
offset	points-per-symbol, setting HT
video demod 1-16	polar display, using HT
offset marker	post-trigger delay HT
See markers	power HT
online help	average HT
See Help hardkey	band power 3-2, HT
options, installing HT	band power, rms square-root of HT
options, temporary HT	carrier-to-noise HT
output filter on/off softkey HT	carrier-to-noise-density HT
output z softkey (source) HT	peak HT
OV1 or OV2, definition of HT	peak to average HT
OVEN REF OUT connector HT	power ratio HT
over LED HT	statistical power measurements HT
description of HT	pre-trigger delay HT
using to set the range HT	preset hardkey HT
overlap processing HT	printing HT
P	aborting HT
packing a disk HT	about printing HT
PARALLEL PORT HT	data and file formats HT
pausing a measurement HT	date and time HT
PCL (HP-GL) (PCL embedded HP-GL)	online help, printing HT
HT	output to file HT
	selecting an output device HT
PCL (printer control language) HT peak power HT	selecting display items HT
peak search HT	setting the HP-IB address HT
peak to average power 1-8, HT	starting HT
peak track softkey HT	PROBE POWER connectors HT
peak-hold averaging	problems, video demodulation HT
See Also averaging	PSD measurements HT
performance test softkey HT	pulse search
phase, displaying HT	in video demodulation 10-16
phone assistance 2-i	pulsed signals, demodulating 10-16
phone assistance 2-1 plotting HT	0
aborting HT	$\mathbf{Q}_{\mathbf{M}}$
	QAM
about plotting HT	block diagram, video demod 10-4
changing plotter pen assignments HT	QAM 16/32 softkey HT
data and file formats HT	QAM 16/32/64/256 softkey HT

R	entering arbitrary values HT
RAM	interaction with other parameters HT
See memory	scalar limitations 8-11
RAM disk	setting the resolution bandwidth HT
See disk drives	vector limitations 8-18
random noise softkey HT	video demod 10-11
range HT	result length
autoranging HT	video demod 1-16
setting optimum range HT	result length softkey HT
single ranging HT	rms averaging
tracking the reference level HT	See averaging
range hardkey HT	RPG
RBW	See knob
See resolution bandwidth	RS232
rear panel tour HT	See serial port
recalling HT	0
about recalling HT	S
autostate file HT	sample frequency
BASIC programs HT	See sample rate
capture-buffer contents HT	sample rate 8-14
math functions HT	video demodulation 10-12
measurement state HT	samples, defined HT
trace HT	saving HT
receiver HT	about saving HT
about receivers HT	autostate file HT
HP-IB address: external receiver HT	calibration trace HT
using an external receiver HT	capture buffer contents HT
receiver softkey HT	math functions HT
REF, definition of HT	measurement state HT
reference level	re-saving BASIC programs HT saving BASIC programs HT
See reference line	traces HT
reference line HT	scalar measurements HT
displaying HT	about scalar mode HT
examples of HT	block diagram HT
position of HT	block diagrams 6-3
setting reference level HT	limitations 8-11
setting with the marker HT	overview 6-2
tracking the range HT	scale at markers softkey HT
Remote LED HT	scaling HT
REMOTE OPERATION group	auto scaling HT
hardkeys HT	x-axis HT
resolution	x-axis scaling: linear vs. log HT
display 8-12	y-axis scaling HT
frequency 8-11	scan time
measurement 8-5	See sweep time
resolution bandwidth HT	search length HT
about resolution bandwidth HT	video demod 1-16
and gating 9-5	searching for pilot HT
See Also bandwidth coupling	self test HT
coupling to frequency span HT	long confidence test HT
EDECTOR DUISE A.Z	

quick confidence test HT Spanish softkey HT self-test log HT spectrum analyzers serial 1/serial 2 connectors HT comparisons 7-9 serial number, displaying HT types of 7-4 serial number, location HT spectrum measurements HT serial port, configuring & cabling HT speed, enhancing HT serial x setup softkey HT SRQ LED HT service assistance (by phone) 2-i start frequency HT shifted functions HT setting start frequency HT signal track softkey HT setting with the marker HT signal tracking HT starting a measurement HT sine freq softkey HT state definitions HT single measurements, running HT stop frequency HT single range softkeys HT setting stop frequency HT single ranging HT setting with the marker HT single sweep, selecting HT suffix menus HT SNR, video demodulation HT supplied accessories vi softkeys HT Swedish softkey HT about softkeys HT sweep speed bracketed softkeys HT See sweep time numeric entry HT sweep time softkeys that toggle HT described 8-10 source HT See Also measurement time about the source HT sweep, manual 8-13 amplitude, setting HT sweeping HT available source outputs HT about sweeping HT connections HT auto sweep, selecting HT CW (fixed sine) output HT continuous sweep, selecting HT displaying the source-state table HT manual sweep, selecting HT external signals, using as input to single sweep, selecting HT source HT symbol clock, adjusting HT optional RF v symbol rate 10-12 output filter, disabling HT symbol rate softkey HT output impedance & dBm units HT SYNC NOT FOUND HT output impedance, setting HT SYNC NOT FOUND, pulse search HT output protection, clearing HT SYNC OUT connector HT random noise output HT sync pattern sine frequency, setting HT video demod, creating, saving, SOURCE LED HT recalling 1-18 turning on and off HT video demod, user-defined 1-18 source hardkey HT sync search source type softkey HT example 1-16 span HT video demod 10-15 arbitrary spans HT sync word cardinal spans HT video demod 1-16 coupling to main length HT SYSTEM Group hardkeys HT maximum span HT SYSTEM INTERCONNECT connector setting span HT HT setting with the marker HT video demodulation 10-12

span softkey HT

an an	Africa a considera e a Pala a LEFF
T	time resitn softkey HT
talk LED HT	time softkey (averaging) HT
telephone assistance 2-i	time, changing HT
Telnet, about HT	time-domain analysis HT
testing	time-domain data, displaying HT
See self test	traces HT
ThinLan connector HT	about traces HT
TIFF (tag-based file format)) HT	activating multiple traces HT
time averaging 8-15	adding a title HT
See averaging	adding trace information HT
time capture HT	auto correlation HT
about time capture HT	capture buffer contents HT
calibration and time-capture HT	changing colors HT
displaying capture information HT	coherence HT
displaying capture-buffer contents HT	coordinates HT
recalling capture-buffer contents HT	cross correlation HT
saving capture-buffer contents HT	cross spectrum HT
starting a time capture HT	data register contents HT
time capture buffer HT	disabling measurement calculations HT
time corrections HT	See Also display
time data 8-15	displaying group delay HT
time data softkey HT	displaying linear magnitude HT
time domain overview 7-2	displaying log magnitude HT
time gating HT	displaying multiple traces HT
about time gating HT	frequency response HT
displaying gate time-record HT	See Also grids
gate delay HT	hiding HT
gate length HT	imaginary part (imaginary data),
See gating	displaying HT instantaneous spectrum HT
selecting a window HT	marker annotation HT
turning on/off HT time points, video demodulation HT	math functions HT
time record 7-7, 8-16, HT	modifying trace labels HT
about the time record HT	overlaying HT
applying a window HT	phase, displaying HT
coupling to span HT	PSD HT
displaying gate time-record HT	real part (real data), dispaying HT
displaying main time-record HT	recalling HT
effects of averaging HT	saving HT
effects of demodulation HT	scaling data, overview HT
effects of span HT	selecting measurement data HT
FILLING TIME RECORD message HT	spectrum HT
gate length HT	time-domain data HT
main length HT	trace boxes HT
real vs. complex data HT	trellis diagram, using HT
time record length	trigger HT
and memory 8-19	about trigger HT
defined 8-16	available trigger signals HT
limitations 8-19	delay HT
time record size	EXT TRIGGER LED HT
defined 8-16	external arm, using with trigger HT

external trigger HT free run trigger HT HP-IB trigger HT IF channel trigger HT input channel trigger HT level HT slope HT source trigger HT trigger holdoff HT trigger LED HT trigger line HT trigger type softkey HT two-channels video demod 1-19 IJ U.K. English softkey HT U.S. English softkey HT UFG (LAN and 4 MB memory option) HT UG7 (advanced LAN option) HT UNCAL, definition of HT units: x-axis HT units: y-axis HT vector averaging See time averaging vector diagram, example 1-14 vector measurements 7-8, HT block diagram HT block diagrams 6-5 overview 6-4 video averaging 8-3 video demodulation See demodulation, video video filtering 8-3 volatile RAM disk See disk drives **VSB** block diagram 10-6 center frequency, setting 1-4 demodulation 1-6 VSB 8/16 softkey HT W window bandwidth defined 8-18 values 8-18 windows HT about windows HT comparison HT

equivalent noise bandwidth HT window bandwidth HT window functions 8-6 window shapefactor HT windows for gate time record HT windows for main time record HT

X

x-axis scaling
See scaling
x-axis, scaling with markers HT
X-Windows, LAN use 4-7
X11 display, using
See lan

Y

y-axis scaling See scaling

Z

zero padding 8-20 zero response 8-9 zero span measurements HT zoom measurements 7-8, 8-3, HT

Declaration of Conformity

According to ISO/IEC Guide 22 and EN 45014

Manufacturer's name:

· Hewlett-Packard Company

Manufacturer's address:

Lake Stevens Instrument Division

8600 Soper Hill Road

Everett, Washington 98205-1298

declares, that the product

Product Name:

Vector Signal Analyzer

Model Number:

HP 89441A

Options:

Similar Product(s):

Product Name:

VSB/QAM Signal Analyzer

Model Number:

HP 89441V

Options:

All

All

conforms to the following specifications, except as noted in the Product Specifications:

Safety:

IEC 348/HD401

EMC:

EN55011/CISPR 11: 1990/EN55011 (1991), Group1, Class A

EN50082-1/IEC 801-2: 1991/EN50082-1 (1992): 4 kV CD, 8 kV AD

EN50082-1/IEC 801-3: 1984/EN50082-1 (1992): 3 V/m EN50082-1/IEC 801-4: 1988/EN50082-1 (1992): 1 kV

Supplementary Information:

The product herewith complies with the requirements of the Low Voltage Directive 73/23/EEC and the EMC Directive 89/336/EEC and bears the CE Mark.

Everett, Washington - October 1, 1997

Billy Miracle, Quality Manager

Need Assistance?

If you need assistance, contact your nearest Hewlett-Packard Sales and Service Office listed in the HP Catalog, or contact your nearest regional office listed at the back of this guide. If you are contacting Hewlett-Packard about a problem with your analyzer, please provide the following information:
☐ Model number:
☐ Serial number:
Options:
Date the problem was first encountered:
☐ Circumstances in which the problem was encountered:
☐ Can you reproduce the problem?
☐ What effect does this problem have on you?
You may find the serial number and options from the front panel of your analyzer by executing the following:
Press [System Utility], [more], [serial number].
Press [System Utility], [options setup].

HP 89400-Series Documentation Roadmap

If you are thinking about	And you want to	Then read the analyzer's Installation and Verification Guide	
Unpacking and installing the analyzer	Install the analyzer, or do operation verification or performance verification tests		
Getting started	Make your first measurements with your new analyzer	Getting Started Guide	
	Review measurement concepts	Operator's Guide	
	Learn what each key does	Online Help (press the (Help) key)	
Making measurements	Learn how to make typical measurements	Getting Started Guide and Operator's Guide	
Creating automated measurements	Learn the HP Instrument BASIC interface	HP 89400 Series Using HP Instrument BASIC	
(To receive HP Instrument BASIC and HP Instrument BASIC manuals, order option 1C2)	Program with HP Instrument BASIC	HP Instrument BASIC User's Handbook	
Remote operation	Learn about the HP-IB and SCPI	HP-IB Programmer's Guide	
	Find specific HP-IB commands quickly	HP 89400-Series HP-IB Commands: Quick Reference	
	Find HP-IB command details	HP 89400-Series HP-IB Command Reference	
Using analyzer data with a PC application	Transfer analyzer data to or from a PC (Personal Computer) application	Standard Data Format Utilities: User's Guide	
	Display analyzer data on a PC, or display PC data on the analyzer		
Servicing the analyzer (To receive service information, order option OB3)	Adjust, troubleshoot, or repair the analyzer	Service Guide	

89441-90012



HP 89441V dc to 2.65 GHz VSB/QAM Signal Analyzer

Technical Data

Specifications describe warranted performance over the temperature range of 0° to 55°C (except where noted) and include a 30-minute warm-up from ambient conditions, automatic calibrations enabled, auto-zero on, time domain calibration off, and anti-alias filter in, unless noted otherwise. Supplemental characteristics identified as "typical" or "characteristic," provide useful information by giving non-warranted performance parameters. Typical performance is applicable from 20° to 30°C.

When enabled, automatic calibrations are periodically performed to compensate for the effects of temperature and time sensitivities. During the calibration, no signals >0 dBm should be connected to the front panel inputs.

Definitions

Baseband = dc to 10 MHz measurements.

Baseband time = Time-domain measurements selected by setting start frequency to exactly 0 Hz or choosing full span in 0 to 10 MHz measurements.

dBc = dB relative to input signal level.

dBfs = dB relative to full scale amplitude range setting. Full scale is approximately 2 dB below ADC overload.

FS or fs = Full scale; synonymous with amplitude range or input range.

RBW = Resolution bandwidth.

RF = 2 MHz to 2.65 GHz measurements.

Scalar mode = Measurements with only frequency-domain analysis available. Frequency spans up to 2648 MHz.

SNR = Signal to noise ratio.

Vector mode = Measurements with frequency- and time-domain capabilities. Frequency spans up to 10 MHz in baseband, and 8 MHz for RF analysis.

Zoom time = Time-domain measurements selected by setting frequency parameters using center frequency and span values.

Standard Features

Frequency

dc to 2.650 GHz 51 to 3201 points

Center frequency signal-tracking

Instrument modes

Scalar (frequency-domain only)

Vector (amplitude and phase information in frequency-

and time-domain and also time-gating)

Sweep types

Continuous

Manual

Single

Triggering

Free run Input channel External arm

Programmable polarity and

IF channel HP-IB

level

Trigger holdoff

Pre and post delay

Averaging

Video

Peak hold

spectrum

Video exponential Time

Simultaneous display of instantaneous and average

Time exponential

Source Types

 $\mathbf{C}\mathbf{W}$

Random noise

Input

One channel

Second 10 MHz input channel (optional)

Auto-ranging (baseband only)

Overload indicators

 $50/75/1M \Omega$ BNC (dc to 10 MHz)

50 Ω Type-N, 75 Ω with minimum-loss pad

(2 MHz to 2650 MHz)

Resolution/window shapes

1-3-10 bandwidth steps

Arbitrary RBW

Windows: Flat-top (high amplitude accuracy), Gaussian-top (high dynamic range), Hanning (high

frequency resolution), Uniform

Detectors: normal, positive peak, sample

Measurement data

Spectrum Time capture

PSD Frequency response,

Main time coherence, cross spectrum,
Gate time and cross correlation (with

Math function second 10 MHz input

Data register channel)

Auto correlation Instantaneous spectrum Additional data formats for video demodulation

Data format

Log magnitude Imaginary part Linear magnitude Group delay Phase (wrap or unwrap) Log/linear x-axis

Real part

Trace math

Display

1, 2, or 4 grids

1 to 4 traces displayed (single or overlay)

Auto-scaling

Color (user definable)

User trace title and information

Graticule on/off
Data label blanking
X-axis scaling

Instrument/Measurement state displays

External monitor

Markers

Marker search: Peak, next peak, next peak right, next

peak left, minimum

Marker to: Center frequency, reference level, start

frequency, stop frequency

Offset markers

Couple markers between traces

Marker functions: Peak track, frequency counter, band

power (frequency, time, or demodulation results)

peak/average statistics

Memory and data-storage

Disk devices

Nonvolatile RAM disk (100 Kbyte) Volatile RAM disk (up to 1 Mbyte)

90 mm (3.5-inch) 1.44 Mbyte flexible disk (HP LIF or

MS-DOS® formats)
External HP-IB disk

Disk format and file delete, rename, and copy

Nonvolatile clock with time/date

Save/recall of: Trace data, instrument states, trace math

functions, HP Instrument BASIC programs,

time-capture buffers

Online help

Hard copy output

HP-IB/HPGL plotters

HP-IB/RS-232/parallel printers

Plot to file Time stamp

Single-plot spooling

Interfaces

HP-IB (IEEE 488.1 and 488.2)

External reference in/out External PC-style keyboard

Active probe power RS-232 (one port) Centronics

LAN and second HP-IB

Standard data format utilities

Optional features

HP Instrument BASIC (Option 1C2) Advanced LAN support (Option UG7)

RF

RF specifications apply with the receiver mode set to "RF section (2-2650 MHz)."

Frequency

Frequency tuning

2 MHz to 2650 MHz

Frequency range Frequency span

Scalar mode 1 Hz to 2648 MHz
Vector mode 1 Hz to 8 MHz

Center frequency tuning 0.001 Hz

resolution

Number of frequency 51 to 3201

points/span

Signal track (when enabled) keeps the largest measured signal at the center frequency.

Frequency accuracy (with standard highprecision frequency reference)

Frequency accuracy is the sum of initial accuracy, aging, and temperature drift.

Initial accuracy $\pm 0.1 \text{ ppm}$

Aging ± 0.015 ppm/month

Temperature drift ± 0.005 ppm (0 ° to 55 °C)

Frequency counter

The frequency counter operates in scalar or vector mode.

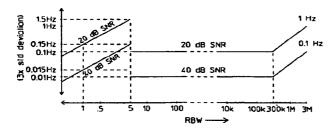
Frequency counter accuracy

Total accuracy is the sum of the frequency counter's basic accuracy and the instrument's frequency accuracy.

Conditions/Exceptions:

Signal-to-noise ratio within resolution bandwidth, 20 dB minimum

Marker within 1/2 resolution bandwidth of peak Unspecified for uniform window and resolution bandwidth < 5 Hz



Frequency counter basic accuracy

Stability (spectral purity) (with standard highprecision frequency reference or equivalent with ≥ 5 dBm level)

Phase noise (absolute and residual)

 $F_{in} \le 200 \text{ MHz}$

100 Hz offset < −103 dBc/Hz 1 kHz offset < −112 dBc/Hz ≥ 10 kHz offset < −116 dBc/Hz

 $200 \text{ MHz} \le F_{\text{in}} \le 1 \text{ GHz}$

100 Hz offset < −96 dBc/Hz 1 kHz offset < −104 dBc/Hz ≥ 10 kHz offset < −116 dBc/Hz

 $1 \text{ GHz} \le F_{in} \le 2650 \text{ MHz}$

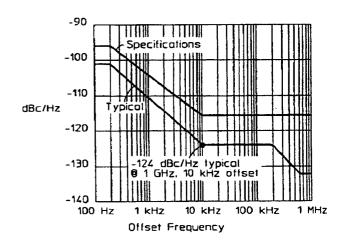
100 Hz offset < −87 dBc/Hz 1 kHz offset < −97 dBc/Hz ≥ 10 kHz offset < −116 dBc/Hz

LO spurious sidebands

Offset > 1 kHz < -75 dBc

Offset $\leq 1 \text{ kHz}$

 $\begin{array}{ll} f_{\rm in} \leq 2 \ GHz & <-70 \ dBc \\ f_{\rm in} > 2 \ GHz & <-68 \ dBc \end{array}$



Spectral purity at 1 GHz

Resolution bandwidth

Range 312.5 µHz to 3 MHz in 1, 3, 10

sequence or arbitrary user-definable

bandwidth

Note: In scalar mode, the minimum resolution bandwidth is 312.5 µHz and the maximum resolution bandwidth is a function of span. In vector mode, the minimum resolution bandwidth is a function of span and the number of frequency points, and the maximum resolution bandwidth is a function of span only.

Window	Selectivity*	Passband flatness	Sideband level
Flat-top	2.45:1	+ 0, -0.01 dB	-95 dBc
Gaussian-top	4.0:1	+ 0, -0.68 dB	-125 dBc
Hanning	9.1:1	+ 0, -1.5 dB	-32 dBc
Uniform	716:1	+ 0,-4 dB	-13 dBc

^{*} Shape factor or ratio of -60 dB to -3 dB bandwidths.

Amplitude

Input range

-50 dBm to + 25 dBm

(5 dB steps)

Maximum safe input power

Average + 25 dBm (300 mW)

continuous power

DC voltage 25 V

A/D overload level > 1.5 dB above range

(typical)

Input port

Input channels

1

VSWR

Range ≥ -20 dBm

1.6:1 (12.7 dB return loss)

Range ≤ -25 dBm

1.8:1 (11 dB return loss)

Impedance

 $50 \Omega (75 \Omega \text{ with minimum}-$

loss pad Option 1D7)

Connector

Type-N

Amplitude accuracy

Accuracy specifications apply with flat-top window selected.

Amplitude accuracy is the sum of absolute full-scale accuracy and amplitude linearity.

Absolute full-scale accuracy (with signal level equal to range)

20 ° - 30 °C 0 ° - 55 °C ≥-25 dBm range ± 1 dB $\pm 2 dB$

(0.5 dB typical) ≤-30 dBm range

 $\pm 1.5 dB$ ±3 dB

(0.5 dB typical)

Amplitude linearity

0 to -30 dBfs < 0.10 dB-30 to -50 dBfs < 0.15 dB -50 to -70 dBfs < 0.20 dB

In vector mode, relative level accuracy within a single span is the sum of vector mode frequency response and amplitude linearity.

Vector mode frequency response (relative to the center frequency) $\pm 0.4 dB$

< -80 dBfs

Dynamic range

Dynamic range indicates the amplitude range that is free of erroneous signals within the measurement bandwidth.

Harmonic distortion (with a single full scale signal at the input)

> ≥ -25 dBm range $< -75 \, \mathrm{dBc}$ ≤ -30 dBm range < -54 dBc

Third-order intermodulation $< -75 \, dBc$ distortion (with two input tones at 6 dB below full scale and \geq 10 MHz)

General spurious (with input signal level equal to range and input frequency $\leq 2650 \text{ MHz}$)

For spans ≤ 1.5 MHz and for < 75 dBc offset frequencies ≤ 1.5 MHz from input signal For all spans and offsets <-70 dBc*

Input noise density (50 Ω input, vector mode or . scalar mode with sample detector)**

Residual responses (50 Ω input)

20°-30°C 0°-55°C ≥-25 dBm range <-115 dBfs/Hz <-112 dBfs/Hz \leq -30 dBm range < -110 dBfs/Hz < -109 dBfs/Hz

Sensitivity**

-50 dBm range < -160 dBm/Hz< -159 dBm/Hz/Hz

*< -60 dBc for RF (2-2650 MHz)-wide

** Add 4 dB for RF (2-2650 MHz)-wide

Phase (vector mode)

Phase specifications apply with flat-top window selected.

Deviation from linear phase (relative to best fit line with peak signal level within 6 dB of full scale) ±5 deg

Time (vector mode)

Time-sample resolution = 1/(k*span(Hz)) [second]; where k = 1.28 for zoom time.

Main time length = (number of frequency points - 1) ÷ span (Hz) [second]; for resolution bandwidth in arbitrary and auto-coupled mode.

Amplitude accuracy (for a sine wave in the measurement passband, time-domain calibrations on, range ≥ -25 dBm)

20 ° - 30 °C

 \pm 12% full scale

0°-55°C

 $(\pm 6\% \text{ typical})$ $\pm 26\% \text{ full scale}$

Sample error rate for zoom time (typical)

Error threshold:

10⁻⁸ times/sample

5% full scale

Sample error rate reflects the probability of an error greater than the error threshold occurring in one time sample.

Trigger

Trigger types

Scalar mode

Free run, HP-IB, external (each measurement step requires a separate trigger)

Vector mode

Free run, IF channel, HP-IB, external Pre-trigger delay range (see time specifications for sample resolution)

One channel

64 Ksamples (1 Msample with extended time capture,

Option AY9)

Two channels (requires second 10 MHz input, Option AY7) 32 Ksamples (0.5 Msample with extended time capture,

Option AY9)

Post-trigger delay range (see time specifications for sample resolution) 2 Gsample

Trigger holdoff

When enabled, each measurement requires two trigger events. The first event starts a holdoff timer. After the specified holdoff time, a subsequent trigger event will initiate a measurement.

Holdoff resolution

 $2.5 \mu s$

Holdoff range 2.5 µs to 41 s

IF trigger (characteristics only)

Used to trigger only on in-band energy, where the trigger bandwidth is determined by the measurement span (rounded to the next higher $10^{7/2^n}$ [Hz]).

Amplitude resolution

< 1 dB

Amplitude ranges

+1 to -70 dBfs.

Useable range will become limited by the total integrated noise in the measurement span.

IF trigger hysteresis < 4 dB

External trigger (positive and negative slope)

Level accuracy

± 0.5 V ± 5 V

Input impedance

10 $k\Omega$ (typical)

External arm

Range

Level accuracy Range ± 0.5 V

±5 V

Input impedance

10 $k\Omega$ (typical)

Source (requires internal RF source Option AY8)

Source types (vector mode and CW (fixed sine), random noise

video demodulation)

Frequency

Range

2 MHz to 2650 MHz

Maximum offset from center frequency

3.5 MHz

Amplitude (fixed sine source type)

Amplitude range

-40 dBm to +13 dBm

Typical maximum amplitude +17 dBm (overdrive is available using direct numeric entry)

Amplitude resolution

0.1 dB

Amplitude accuracy (source level $\leq 13 \text{ dBm}$) Source amplitude accuracy is the sum of absolute accuracy at the center frequency (zero offset frequency) and the IF flatness.

 $20 \degree - 30 \degree C$ $0 \degree - 55 \degree C$

Absolute accuracy at the

center frequency

 $\pm 1.2 dB$ $\pm 3.5 \text{ dB}$

IF flatness (relative to

center frequency)

± 1 dB $\pm 1.5 dB$

IF Flatness with

 $\pm 0.3 dB$

offset frequency | ≤ 500 kHz

Dynamic range (source level $\leq dBm$)

Harmonic distortion

< -40 dBc< -40 dBc

Non-harmonic spurious

(within measurement

bandwidth)

Average noise level (for

< -120 dBc/Hz

offsets > 1 MHz from the carrier and carrier

frequency >100 MHz. For

offsets < 1 MHz, add the

LO phase noise.)

Crosstalk (source-to-receiver, < -80 dBfs source level ≤ 0 dBm)

Source port

VSWR

Level \leq −10 dBm

Impedance

Connector

1.8:1 (11 dB return loss) $50~\Omega~(75~\Omega~with~optional$

minimum-loss pad)

Type-N

Baseband

Baseband specifications apply with the receiver mode set to "IF section (0-10 MHz)" or "RF section (0-10 MHz)" unless noted otherwise. Specifications noted as "IF section only" apply with the receiver mode set to "IF section (0-10 MHz)" and the input signal connected directly to the IF section's channel 1 or channel 2 input.

Frequency

Frequency tuning (characteristic only)

Frequency range dc to 10 MHz
Frequency span 1.0 Hz to 10 MHz
Center frequency tuning resolution 0.001 Hz
Number of frequency points/span 51 to 3201
Signal track (when enabled) keeps the largest measured signal at the center frequency.

Frequency accuracy

Same as the RF specifications.

Frequency counter

Same as the RF specifications.

Stability (spectral purity)

Absolute and residual phase noise, $F_{\rm in}=10~MHz$ (with standard high precision frequency reference or equivalent)

100 Hz offset < −106 dBc/Hz 1 kHz offset < −110 dBc/Hz ≥ 10 kHz offset < −120 dBc/Hz

Phase noise decreases with decreasing input

frequency by
$$20 \log_{10} \left| \frac{Fin}{10 \text{ MHz}} \right| dB$$
.

Resolution bandwidth

Same as the RF specifications.

Amplitude

Input range (characteristic only)(2 dB steps)

50 Ω input -30 dBm to + 24 dBm 75 Ω input -31.761 dBm to +22.239 dBm 1 M Ω input -30 dBm to + 28 dBm (referenced to 50 Ω)

Maximum safe input power 50 Ω /75 Ω input +27 dBm 1 M Ω input 20 V Peak

Auto-ranging (characteristic only)

Up-only, up-down, single, off

Input port

Input channels

 $\begin{array}{c} \text{channel optional)} \\ \text{Return loss (IF section only)} \\ 50 \ \Omega \ \text{input} & > 25 \ \text{dB} \\ 75 \ \Omega \ \text{input} & > 20 \ \text{dB} \\ \\ \text{Coupling} & \text{dc/ac (ac coupling attenuation } < 3 \ \text{dB at 3 Hz)} \\ \\ \text{Input Impedance} & 50/75 \ \Omega, 1 \ \text{M}\Omega \pm 2\% \\ \\ \text{(IF section only)} & (< 80 \ \text{pF shunt capacitance)} \\ \\ \text{Connector} & \text{BNC (RF section: Type-N)} \\ \end{array}$

1 (second 10 MHz input

Amplitude accuracy

Accuracy specifications apply with flat-top window selected.

Amplitude accuracy is the sum of absolute full-scale accuracy and amplitude linearity.

Absolute full-scale ± 0.5 dB accuracy (IF section only, with signal level equal to range)

Amplitude linearity

 $\begin{array}{lll} 0 \text{ to } -30 \text{ dBfs} & < 0.10 \text{ dB} \\ -30 \text{ to } -50 \text{ dBfs} & < 0.15 \text{ dB} \\ -50 \text{ to } -70 \text{ dBfs} & < 0.20 \text{ dB} \\ \text{Residual dc } (50 \Omega) & < -25 \text{ dBfs} \end{array}$

Dynamic range

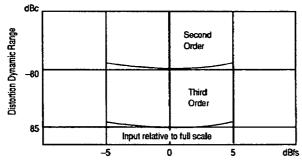
Dynamic range indicates the amplitude range that is free of erroneous signals within the measurement bandwidth.

Harmonic distortion (with a single full scale signal at the input)

2nd < -75 dBc (-80 dBc typical) 3rd, 4th, 5th < -75 dBc (-85 dBc typical)

Intermodulation distortion (with two input tones at 6 dB below full scale)

Second-order < -75 dBc (-80 dBc typical) Third-order < -75 dBc (-85 dBc typical)



Typical harmonic and intermodulation distortion

Residual (spurious) responses (IF section only) (50 Ω input and front panel connections to RF section disconnected)

Frequencies < 1 MHz < -75 dBfs or < -100 dBm

whichever is greater

Frequencies $\geq 1 \text{ MHz} < -80 \text{ dBfs}$

Alias responses (for a < -80 dBfs single out-of-band tone at full scale)

Input noise density (50 Ω input, vector mode or scalar mode with sample detector)

1 kHz to 40 kHz < -101 dBfs/Hz 40 kHz to 10 MHz < -114 dBfs/Hz

(-118 dBfs/Hz typical)

Sensitivity (-30 dBm range, 50 Ω input, vector mode or scalar mode with sample detector)

1 kHz to 40 kHz < -131 dBm/Hz 40 kHz to 10 Hz < -144 dBm/Hz

(-148 dBm/Hz typical)

Crosstalk < -85 dBfs (source-to-input or

channel-to-channel, 50Ω terminations)

Phase (vector mode)

Phase specifications apply with flat-top window selected.

Deviation from linear phase (relative to best fit line with peak signal level within 6 dB of full scale)

Time (vector mode)

Time-sample resolution = 1/(k*span(Hz)) [second]; where k = 1.28 for zoom time, 2.56 for baseband time measurements.

Main time length = (number of frequency points -1) \div span (Hz) [second]; for resolution bandwidth in arbitrary and auto-coupled mode.

Amplitude accuracy ± 5% full scale (IF section only)(for a sine wave in the measurement passband, time-domain calibrations on)

Sample error rate for zoom time (typical)

 ${\bf Error\ threshold:}$

10⁻⁸ times/sample

±5 deg

5% full scale

Sample error rate reflects the probability of an error greater than the error threshold occurring in one time sample.

Analog channel-to-channel < 1 ns time skew (IF section only) (time-domain calibrations on, both channels on the same range)

Two-channel

The second 10 MHz input channel (Option AY7) provides additional measurements, including frequency response, coherence, cross spectrum, and cross correlation. These measurements are made by comparing a signal on channel two to a signal on channel one or to a demodulated signal on the RF input.

Channel match

 $\pm 0.25 \text{ dB}, \pm 2.0 \text{ deg}$

(IF section only, at the center of the frequency bins, dc coupled, 16 rms averages, frequency response, full scale inputs, both inputs on the same range. Exclude the first 5 bins of the dc response.)

Trigger

Same as RF trigger specifications with the following additional specifications.

Input channel trigger (positive and negative slope)

Level accuracy Range

± 10% full scale ± 110% full scale

Resolution

Full scale/116 (typical)

Source

Source types

Scalar mode

CW (fixed sine),

Vector mode and

CW, random noise

video demodulation mode

Random noise source % of energy in-band > 70%

(Span = $10 \text{ MHz/}2^{\text{N}}$, N = 1 to 24)

Frequency

Frequency range

dc to 10 MHz

Frequency resolution 25 µHz

Amplitude

Source level

CW and

 $-110 \text{ dBm to } +23.979 \text{ dBm } (50 \Omega)$

random noise

5.0 Vpk maximum

DC offset

± 3.42 V maximum (resolution and range of programmable dc offset is dependent on source

amplitude)

Amplitude accuracy (50 Ω , fixed sine)

(IF section only)

-46 dBm to +24 dBm

± 1.0 dB

-56 dBm to -46 dBm

 $\pm 2.0 \text{ dB}$

Harmonic and other spurious products (fixed sine, 0 V dc offset)

dc to 10 kHz

< -55 dBc

10 kHz to 5 MHz

< -40 dBc 5 MHz to 10 MHz < -33 dBc

Source port

Return loss (IF section only)

> 20 dB

Source impedance

 $50/75 \Omega$

Safety and environmental

Safety standards **CSA** Certified for

Electronic Test and Measurement Equipment per CSA

C22.2, No. 231

This product is designed

for compliance to:

Acoustics

UL1244 and IEC348, 1978 LpA < 55 dB typical at

25 °C ambient

4600 m (15,000 ft)

4600 m (15,000 ft)

0 to 55 °C

(Temperature controlled fan to reduce noise output)

Temperature

Operating

Internal disk operations 4 ' to 40 'C

Storage

-20 ° to 65 °C (no disk in drive)

Humidity, non-condensing

Operating

10% to 90% at 40 °C Internal disk operations

20% to 80% at 30 °C Storage 10% to 90% at 40 °C

(no disk in drive)

Altitude

Operating (above

2285 m (7,500 ft), derate operating temperature by -3.6 °C/1000 m

(-1.1 °C/1000 ft))

Storage

Calibration interval

Warm-up time

Power requirements

115 VAC operation

IF section

RF section

90 - 140 Vrms, 47 - 63 Hz

1 vear

30 minutes

230 VAC operation

198 - 264 Vrms, 47 - 63 Hz

90 - 140 Vrms, 47 - 440 Hz

Maximum power dissipation

IF section

750 VA

RF section

275 VA

IEC 801-3 (Radiated Immunity) Performance degradation may occur at Severity Level 2.

Physical

Weight	IF section	n 25 kg (55 lb)
Dimensions	RF section	on 25 kg (55 lb)
IF section	Height	230 mm (9.1 in)
	Width	426 mm (16.7 in)
	Depth	530 mm (20.9 in)
RF section	Height	173 mm (6.8 in)
	Width	419 mm (16.5 in)
	Depth	495 mm (19.5 in)

Real-time bandwidth (characteristics only)

Real-time bandwidth is the maximum frequency span that can be continually analyzed without missing any time segment of the input signal.

Frequency spans of 10⁷/2ⁿ Hz, arbitrary auto-coupled resolution bandwidth, markers off, one display trace with calculations off on other traces, and maximum frequency points equal to number of frequency points.

Averaging off

Single-channel vector mode (log magnitude spectrum

measurement data, 1601 frequency points, channel

2 off, averaging off)

Two-channel vector mode (requires second 10 MHz input channel, Option AY7) (Log magnitude frequency response

measurement data, 801 frequency points, averaging off) 78.125 kHz,

48 updates/second

39.0625 kHz,

48 updates/second

Averaging

Single-channel vector mode averaging (log magnitude spectrum measurement data, 1601 frequency points, channel 2 off)

Fast average Displayed

78.125 kHz 78.125 kHz,

48 updates/second

Two-channel vector mode averaging (requires second 10 MHz input channel, Option AY7) (Log magnitude frequency response measurement data, 801 frequency points)

Fast average Displayed

39.0625 kHz 39.0625 kHz, 48 updates/second

Measurement speed

Display update speed (vector mode with full span, one or two channels, 401 frequency points, no averaging, markers off, single trace with calculations off on other traces, log magnitude spectrum, frequency spans of 107/2n Hz): 60/second

Averaging (characteristics only)

Number of averages Overlap averaging Average types 1 to 99,999 0% to 99.99%

Scalar mode

Vector mode

rms (video), rms (video) exponential, peak hold rms (video), rms (video) exponential, time, time exponential, peak hold

Fast averaging allows averaging a user-defined number of measurements without updating the displayed result. This provides faster averaging results for most measurements.

Gating (characteristics only)

Time-selective, frequency-domain analysis can be performed on any input or analog demodulated time-domain data. When gating is enabled, markers appear on the time data; gate length and delay can be set directly. Independent gate delays can be set for each input channel. See time specifications for main time length and time resolution details.

Gate length

Maximum: Main time length

Minimum: Approximately window shape ÷ (0.3 x span (Hz)) [seconds]; where window shape (ws) and minimum gate length for a 10 MHz zoom time span are (for 10 MHz baseband time spans subtract 39.0625 ns):

Window	ws	Minimum gate length
Flat-top	3.819	1.328125 µs
Gaussian-top	2.215	781.25 ns
Hanning	1.5	546.875 ns
Uniform	1.0	390.625 ns

Time-capture (characteristics only)

Direct capture of input waveforms can be accomplished with spans of 10 MHz/2ⁿ Hz. See time specifications for time-sample resolution details.

Time capture memory: 64 Ksample; 1 Msample (Option AY9)

Benchmarks: For a one-channel, zoom time measurement (for baseband time, halve the time), 64 Ksample captures from 5.12 ms in a 10 MHz span to over 11.9 hours in a 1.19 Hz span. The optional 1 Msample captures from 81.92 ms in a 10 MHz span to over 190 hours in a 1.19 Hz span. Memory is shared if two channels are enabled, therefore length of capture is half as long.

Band power marker (characteristics only)

Markers can be placed on any time, frequency, or demodulated trace for direct computation of band power, rms square root (of power), C/N, and C/N₀ within the selected portion of the data.

Peak/Average statistics

Peak and peak-to-average statistics can be enabled on main time, gate time, IQ measured timed, IQ reference time, and math functions involving these trace types. Average power and peak statistics are computed using all samples in the active trace. Each successive trace adds additional samples to the calculations.

Displayed results average power

peak power peak/average ratio number of samples

Peak percent 90% - 99.99%. Setting can

be changed at any time during or after the

measurement

Signal characteristics

Peak power range

+ 13 dB relative to average power of the first time

record

reco

Average power

range

+ 3 dB relative to average power of the first time

record.

Display (characteristic on)	v))
-----------------------------	----	---

Trace formats One to four traces on one,

two, or four grids or a quad

display

Other displays On-line help text, view state

Number of colors User-definable palette

Display points/trace 401

User-definable trace titles and information

X-axis scaling Allows expanded views of

portions of the trace

information

Display blanking Data or full display

Graticule on/off

Center ±5 mm referenced to bezel

opening

Dimensions

Height 105 ± 5 mm Width $147 \pm 5 \text{ mm}$ 180.6 mm (7.1 in)

Diagonal

Status indicators

Overload, half range, external trigger, source on/off, trigger, pause, active trace, remote, talk, listen, SRQ.

External PC-style keyboard interface

Compatible with PC-style 101-key keyboard, such as the HP C1405B with HP C1405-60015 adapter.

Interfaces (characteristics only)

Active probe power +15 Vdc, -13 Vdc; 150 mA

maximum, compatible with

HP active probes

Sync out (not used) Active low TTL level signal synchronous with source output of periodic chirps and arbitrary blocks up to 8192

samples.

External reference in/out IF section

External

Locks to a 1, 2, 5, or 10 MHz signal

reference input (± 10 ppm) with a level > 0 dBm

External

Output the same frequency reference output as the external reference input

at a level of > 0 dBm into a

 $50 \Omega load.$

External reference in/out RF section

External

Locks to a 1, 2, 5, or 10 MHz signal

reference input

(± 10 ppm) with a level > 0 dBm (use ≥ 5 dBm for optimum phase noise

performance).

External

Outputs 10 MHz at > 0 dBm

reference output (+6 dBm typical) into a 50 Ω

load.

HP-IB

Implementation of IEEE Std 488.1 and 488.2 SH1, AH1, T6, TE0, L4, LE0, SRI, RL1, PP0, DC1, DT1, C1, C2, C3, C12, E2

Benchmark characteristics (typical transfer rate of 401 frequency-point traces)

Scalar

25 traces/second

Vector RS-232

20 traces/second Serial port (9-pin) for

connection to printer

Centronics

Parallel port for connection to

a printer

External monitor output

Format

Analog plug-compatible with 25.5 kHz multi-sync monitors

 75Ω

Impedance Level

0 to 0.7 V

Display rate

60 Hz

25.5 kHz

Horizontal refresh

rate

Horizontal lines 400

Second HP-IB

Implementation of IEEE

Std 488.1 and 488.2

LAN

ThinLAN BNC

Peripherals

Plot/print

Direct plotting and black-and-white printing to parallel (Centronics), serial (RS-232), and HP-IB graphics printers and plotters. Printers supported include the HP LaserJet, HP PaintJet, HP ThinkJet, HP DeskJet, and HP QuietJet. Single-plot spooling allows instrument operation while printing or plotting a single display.

Memory and data storage

Disk devices

Nonvolatile RAM disk 100 Kbytes

Volatile RAM disk

5 Mbytes that can be partitioned between

measurement,

HP Instrument BASIC program space and RAM.

Internal 90 mm (3.5-inch) 1.44 Mbyte flexible disk (HP LIF or

MS-DOS® formats)

External disk

HP-IB interface

Disk format and file delete, rename and copy

Nonvolatile clock with time/date

Save/recall can be used to store trace data, instrument states, trace math functions, HP Instrument BASIC programs, and time-capture buffers.

Benchmarks (typical disk space requirements for

different file types)
Trace data (401 points)

6.2 Kbyte 12.3 Kbyte

Instrument state Trace math

2 Kbyte

Time-capture buffers

271 Kbyte

(32 Ksamples)

Trace math

Operands

measurement data, data register,

constant, other trace math functions, jw

Operations

+, -, *, /, cross correlation, conjugate, magnitude, phase, real, imaginary, square root, FFT, inverse FFT; natural

logarithm, exponential

Trace math can be used to manipulate data on each measurement. Uses include user-units correction and normalization.

Marker functions

Peak signal track, frequency counter, band power peak/average statistics.

Standard data format utilities

Included on two 90 mm (3.5-inch) 1.44 Mbyte flexible disks and two 130 mm (5.25-inch) 1.2 Mbyte floppy disks. The utilities run in MS-DOS® 2.1 or greater on an IBM PC (AT or higher) or compatible. The utilities include conversions to standard data format (SDF), PC displays of data and instrument state information, and utilities for conversion to PC-MATLAB, MATRIX $_{\rm X}$, data set 58 and ACSII formats.

Digital video modulation analysis

Supported modulation formats

Modulation formats

8 and 16VSB

16, 32, 64 and 256QAM 16, 32, and 64QAM (differentially encoded per DVB standard)

Frequency span

The (2 - 2650 MHz)-wide receiver mode increases the maximum allowable vector frequency span to 8 MHz. Specifications for this mode are in the RF specification section.

Maximum symbol rate

The HP 89441V analyzes vector modulated signals up to a maximum symbol rate determined by the information bandwidth of the receiver mode and the excess bandwidth factor (a) of the input signal, according to:

 $Max Symbol Rate \leq \frac{Information Bandwidth}{1 \cdot \cdot \cdot \cdot}$

(Note: the maximum symbol rate is doubled for VSB signals.)

Receiver mode

Information bandwidth

ch1 + j*ch20 - 10 MHz ≤ 20 MHz *

2 - 2650 MHz - normal

≤ 10 MHz

2 - 2650 MHz - wide

≤7 MHz ≤8 MHz

External

≤ 10 MHz *

Example: For a 64 QAM signal ($\alpha = 0.15$), the maximum symbol rate for the (2-2650 MHz)-wide receiver is 8 MHz/(1.15) = 6.96 Msymbols/second.

* Downconverter dependent.

Measurement results

I-Q measured

Time, spectrum

(Filtered, carrier locked, symbol locked)

I-Q reference

Time, spectrum

(Ideal, computed from detected symbols)

I-Q error vs. time

Magnitude, phase

(I-Q measured vs. reference)

Error vector

Time, spectrum

(Vector error of computed vs. reference)

Symbol table +

Error vector magnitude is

error summary

computed at symbol times only

Display formats

The following trace formats are available for measured data and computed ideal reference data, with complete marker and scaling capabilities and automatic grid line adjustment to ideal symbol or constellation states. Polar diagrams

Constellation: Samples displayed only at symbol

times

Vector: Display of trajectory only at symbol times with 1 to 20 points/symbol

I or Q vs time

Eye diagrams: Adjustable form 0.1 to 10 symbols Trellis diagrams: Adjustable from 0.1 to 10 symbols Continuous error vector magnitude vs. time

Continuous I or Q vs. time Error summary

Measured rms and peak values of the following:

Error vector magnitude

Magnitude error

Phase error

Frequency error (carrier offset frequency)

I-Q offset

SNR and MER for QAM + VSB formats VSB pilot level is shown, is dB relative to nominal. For VSB formats, SNR is calculated from the real part of the error vector only.

For DVB formats, EVM is calculated without removing IQ offset.

Detected bits (symbol table)

Binary bits are displayed and grouped by symbols. Multiple pages can be scrolled for viewing large data

Symbol marker (current symbol shown as inverse video) is coupled to measurement trace displays to identify states with corresponding bits. Bits are user-definable for absolute states or

differential transitions.

Accuracy

Residual errors (typical)

8VSB or 16VSB, symbol rate = 10.762 MHz, $\alpha = 0.115$, instrument receiver mode of IF 0-10 MHz or RF 2 - 2650 MHz, 7 MHz span, full-scale signal, range ≥ -25 dBm, result length = 800, averages = 10.

Residual EVM $\leq 1.5\%$ (SNR ≥ 36 dB) 16, 32, 64 or 256QAM, symbol rate = 6.9 MHz, $\alpha = 0.15$, instrument receiver mode of IF 0 - 10 MHz or RF 2-2650 MHz - wide, 8 MHz span, full-scale signal, range ≥ -25 dBm, result length = 800, averages = 10.

Residual EVM

≤ 1.0% (SNR ≥ 40 dB)

Filtering

All filters are computed to 40 symbols in length

Filter types

Root Raised-Cosine

User-selectable filter parameters

Alpha continuously adjustable from 0.05 to 1.0

Adaptive equalization

The HP 89441V equalizes the digitally-modulated signal to remove effects of linear distortion (such as unflatness and group delay) in a modulation quality measurement.

Equalizer performance is a function of the filter design (e.g., length, convergence, taps/symbol) and the quality of the signal being equalized.

Equalizer

Decision-directed, LMS, feed-forward equalization with adjustable convergence rate.

Filter length Filter taps 3 - 99 symbols, adjustable 1,2,4,5,10, or 20 taps/symbol

Measurement results

Equalizer impulse response Channel frequency response

4 Mbytes Extended RAM and additional I/O

Extended RAM

Extended memory type: 4 Mbytes dynamic RAM Approximately 6 Mbytes, user-allocatable to measurement memory, RAM disk and IBASIC program space.

LAN I/O

LAN support: Ethernet (IEEE 802.3) TCP/IP LAN interface: ThinLAN (BNC connector) or AUI Recommended MAU: HP 28685B (l0base-T) or HP 28683A (FDDI)

Program interface: Send and receive HP-IB programming codes, status bytes and measurement results in ASCII and/or binary format.

HP-IB I/O

Secondary HP-IB port: Per IEEE Std 488.1 and 488.2 Functions: Controller-only; accessible from IBASIC program or front panel commands.

Advanced LAN support—Option UG7

Remote X11 display (characteristic only)
Update rate: > 20 per second, depending on
workstation performance and LAN activity.
Xll R4 compatible
X-terminals, UNIX workstations, PC with X-server
software
Display 640 x 480 pixel minimum resolution
required; 1024 x 768 recommended.

FTP data (characteristic only)

Traces A, B, C, D
Data registers D1 - D6
Time capture buffer
Disk files (RAM, NVRAM, floppy disk)
Analyzer display plot/print